

			3 10						
Motion C		near Stage itional accuracy, working accu	racy, moment stiffness, measurement of XY axis stage accuracy)	G004	Stepping Motor	X Translation	1	OSMS Series Translation Motorized Stages -5 Phase Stepping Motor OSMS20-(Z)	G036
Motion Control Products Guide		otation Stage ositional accuracy,	working accuracy, attitude accuracy)	G006	Motor	tion	8	Precision Motorized Stages with Builit -in Compact Scale OSMS(CS)20-(X)	G038
ucts Guide	Go (po	oniometer Stage ositional accura	cy, attitude accuracy)	G007		ı	1	OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor OSMS26-(X)	G040
ı	Quality Assurance / Traceability			G008		ı	×	OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor OSMS26-(XY)	G042
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Controllers / Drivers	Controllers						1	Precision Motorized Stages with Builit -in Compact Scale OSMS(CS)33-(X)	G054
s / Drivers	Dr	ivers		G020		AC servo		SGMV series Translation Motorized Stages - AC servo Motor SGMV	G056
Softwares	So	ftwares		G022		X Translation		Thin Long Travel Stage KLSA/KLSS	G058
01			minal Software TERME	G024		tion		Aluminum Crossed Roller Guide Motorized Stage TAMM	G060
			ware for Positioning & Measurement EMCSE	G025		ı	per	Precision Motorized Stages - 5 Phase Stepping Motor KST-X	G062
Stepping	S.	Mot	torized Stage/Controller/Cable Sets	G026		ı		Precision Motorized Stages with built in Glass-scale Encoder KST(GS)	G064
Motor	X Translation		High Performance Motorized Stages HPS	G028		ı		Precision Motorized Stages - 5 Phase Stepping Motor KST-XY	G066
	tion	S	OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor OSMS20-(X)	G032				Precision Motorized Stages - 5 Phase Stepping Motor KST-Z	G068
			OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor OSMS20-(XY)	G034			EE	Translation Motorized Stages, Flat Z axis - 5 Phase Stepping Motor SGSP-ZF	G070

Stepping Motor	X Translation	0	Actuator for Objective Lenses (Stepper motor type) SGSP-OBL-3	G072
Motor	Rotation	學	Rotation Motorized Stages SGSP-YAW	G074
		2	Precision Rotation Motorized Stages KST-YAW	G078
		\$ 6°	High Durability Automatic Rotation Stage HDS-YAW	G080
	Goniometer		Motorized Extended Guide Goniometer OSMS-40A	G082
	ter	000	Motorized Extended Guide Goniometer OSMS-60A	G084
		OCC.	Motorized Goniometers - 5 Phase Stepping Motor SGSP-A/B	G086
	Vacuum	Vacuum C VSGSP G	Compatible Motorized Stages Guide uide	G090
			Vacuum Applications Miniature Motorized Stages VSGSP-60	G092
		23	Vacuum Compatible Motorized Stages VSGSP	G094
			Vacuum Compatible Rotation Motorized Stage VSGSP-YAW	G096
Controller			Single axis Stage Controller GSC-01	G098
rs / Drivers			2 axis Stage Controller GSC-02	G099
	11	-11	2 axis Stage Controller SHOT-702	G100
	, FR/	and and	Intelligent Positioning System GIP-101	G101
			2 axis / 4 axis Stage Controllers SHOT-GS	G102
		ME	Extensible Stage Controller HIT-M/S	G103
			Pulus Generating Controller PGC-04	G104

		Joystick Terminal	
Controller		SJT-02	G106
Controllers / Drivers	SULUTION OF THE PROPERTY OF TH	Jog Dial JD-100	G106
	12000	Joy Stick JS-300	G107
		og Operation Box JB-400	G107
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Option		Maintenance/Grease Replacement AFA/AFB/AFE/YVAC	G110
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	200	Piezo Actuator for Objective Lens SFS-OBL/SFAI-OBL	G116
		SFS Controllers FINE	G117
	ECS Positione ECS series	ers	G118

Quality Assurance

We verify the working accuracy when stage assembly is completed. All products we ship are compliant to JIS or have passed company regulations.

Serial Number

A sticker like the one shown in the picture is affixed onto Sigma Koki products. It shows information such as our company logo, part number, and serial number.



Positional Accuracy



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Options

□40mm

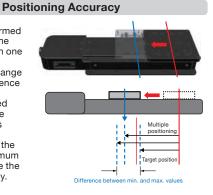
□80mm

□85mm

□120mm

Others

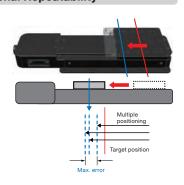
Positioning is performed successively from the reference position in one direction at a fixed interval across the range of travel. The difference between the target values and measured values at each of the positioning points is calculated, and the difference between the minimum and maximum values is taken to be the positioning accuracy.



Positional Repeatability

Positioning is performed multiple times from the same direction on any position (e.g. both ends or center point) of the stage, and the maximum value of the deviation amount with respect to the stop position is calculated.

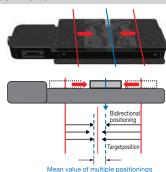
The maximum of those numerical values is taken to be positional repeatability.



Lost Motion

Positioning is performed multiple times in the (+) forward and (-) backward directions on any position (e.g. both ends or center point) of the stage, and the mean value of the deviation amount with respect to the stop position is calculated. The maximum of the

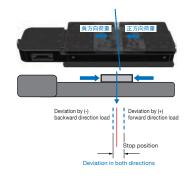
The maximum of the numerical values is taken to be lost motion.



Backlash

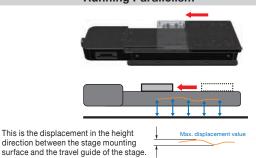
A fixed load is applied to the (+) forward or (-) backward direction on any position (e.g. both ends or center point) of the stage.

The total deviation in the respective direction at that time is taken to be backlash.



Working Accuracy

Running Parallelism



The displacement in the vertical direction of the table during stage motion along the full stroke is taken to be the running parallelism.

Orthogonality of Motion

Measure the working displacement of the Y axis when referenced to the X axis of the XY axis stage with a square. The displacement at this time is taken to be the orthogonality of motion.

Perpendicularity of Motion

Place a dial gauge on the Z stage, and measure the displacement with respect to a vertical plate. The displacement at this time is taken to be the perpendicularity of motion.

(Reference) Measurement Result (OSMS20-35)

								,								1			
			1	2	2	3	3	4	1		5	(3	7	7	3	3	(9
Target Position [µm]		()	25	00	50	00	75	00	100	000	12	500	150	000	175	500	200	000
Positioning Direction		1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
Position Deviation [µm]	1st time	0.0	-1.2	-0.1	-0.5	0.2	-0.8	-0.3	-0.5	-0.1	-1.4	-0.4	-1.1	-1.7	-2.3	0.3	0.1	-1.5	-1.8
(Measured Value - Target Position)	2nd time	-0.6	-1.2	-0.2	-0.4	0.1	-0.7	-0.2	-0.6	-0.3	-1.4	-0.8	-0.9	-1.7	-2.5	0.0	-0.1	-1.5	-1.9
	3rd time	-0.4	-0.9	-0.1	-0.8	0.2	-1.3	-0.4	-0.7	-0.1	-1.3	-0.8	-1.2	-1.5	-2.6	0.3	0.0	-1.5	-1.9
	4th time	-0.2	-1.6	-0.3	-0.6	-0.2	-0.9	-0.4	-0.6	-0.3	-1.2	-0.8	-1.2	-1.5	-2.5	0.3	-0.2	-1.5	-2.0
	5th time	-1.0	-1.2	-0.3	-0.6	0.0	-1.4	-0.5	-0.6	-0.2	-1.2	-0.6	-1.1	-1.6	-2.6	0.2	-0.1	-1.7	-2.0
Mean Position Deviation	١X	-0.44	-1.22	-0.20	-0.58	0.06	-1.02	-0.36	-0.60	-0.20	-1.30	-0.68	-1.10	-1.60	-2.50	0.22	-0.06	-1.54	-1.92
Standard Deviation X		0.38	0.25	0.10	0.15	0.17	0.31	0.11	0.07	0.10	0.10	0.18	0.12	0.10	0.12	0.13	0.11	0.09	0.08
X+S		-0.06	-0.97	-0.10	-0.43	0.23	-0.71	-0.25	-0.53	-0.10	-1.20	-0.50	-0.98	-1.50	-2.38	0.35	0.05	-1.45	-1.84
X-S		-0.82	-1.47	-0.30	-0.73	-0.11	-1.33	-0.47	-0.67	-0.30	-1.40	-0.86	-1.22	-1.70	-2.62	0.09	-0.17	-1.63	-2.00
Lost Motion B=X ↑ –X	ļ	0.	78	0.	38	1.0	08	0.:	24	1.1	10	0.	42	0.	90	0.:	28	0.	38
Maximum (Position Deviation) Value S	1+S + B	1.	41	0.	63	1.	56	0.4	42	1.3	30	0.	72	1.	12	0.	52	0.	55
Wobble per Rotation		1.	00	0.	80	0.	80	0.9	90	0.	70	1.	60	2.	60	1.9	90		

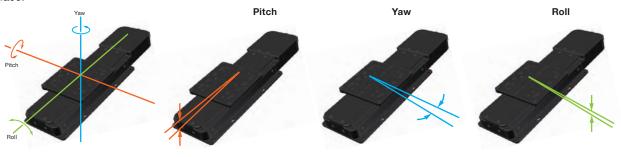
■Result

Maximum Lost Motion	1.10µm
Average Lost Motion	0.62µm
Positional Repeatability	
Unidirectional Positioning †	0.77µm
1	0.62µm
Bidirectional Positioning	1.56µm
Positioning Accuracy	2.97µm
Frror per Rotation (maximum)	2 60 um

Moment Stiffness (Pitch/Yaw/Roll)

Moment stiffness is the stage strength against load exerted at a point away from the center of the table face. (The center of the table face does not match the center of gravity of work.)

It indicates the degree of tilt of the table face (sec) when 1N load is exerted at a point 1cm away from the center of the stage face.



Angular Accuracy

Pitch

Pitch is the angle displacement of the table face in the pitch direction while the stage is in motion.

It indicates the maximum angle displacement during full travel.

Parallelism

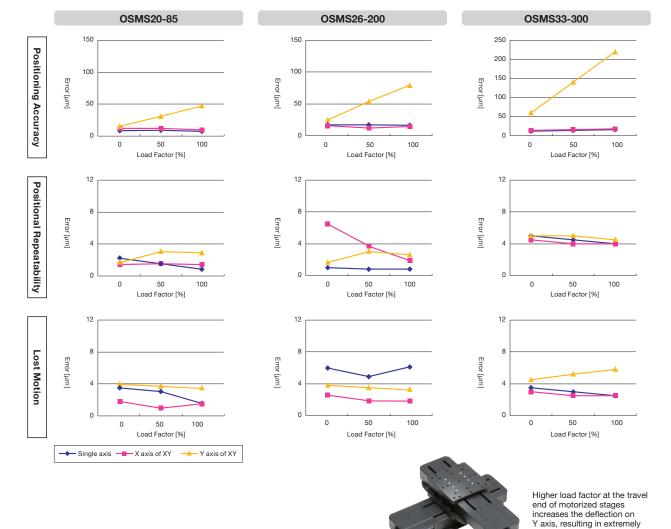
It indicates the parallelism of the table fixed on the stage against the base plane.

Yaw

Yaw is the angle displacement of the table face in the yaw direction while the stage is in motion.

It indicates the maximum angle displacement during full travel.

(Reference) Measurement of XY axis Stage Accuracy



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□40mm □60mm

□80mm

□85mm

□100mm

□120mm

Others

poor positioning accuracy.

Positional Accuracy



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Vacuum **Options**

□40mm

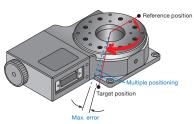
□60mm

□80mm

□85mm □100mm

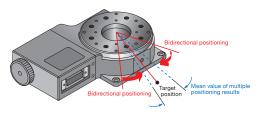
□120mm Others

Positioning Accuracy



Positioning is performed successively from the reference position in one direction at a fixed interval across almost the entire range of travel. The difference between the target values and measured values at each of the positioning points is calculated, and the difference between the minimum and maximum values is taken to be the positioning accuracy.

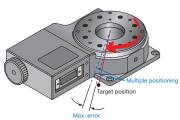
Lost Motion



Positioning is performed multiple times in the (+) forward and (-) backward directions on any position (e.g. both ends or center point) of the stage, and the mean value of the deviation amount with respect to the stop position is calculated.

The maximum of the numerical values is taken to be lost motion.

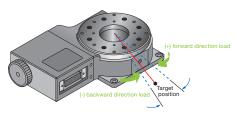
Positional Repeatability



Positioning is performed multiple times from the same direction on any position of the stage, and the maximum value of the deviation amount with respect to the stop position is calculated. The maximum of those numerical values is taken to be positional

repeatability.

Backlash

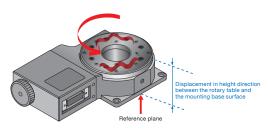


A fixed load is applied to the (+) forward or (-) backward direction on any position of the stage.

The total deviation in the respective direction at that time is taken to be backlash.

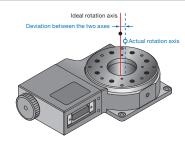
Working Accuracy

Wobble



Wobble is the maximum displacement in the height direction between the rotary table and the mounting base surface when the rotation stage is rotated once.

Concentricity



Concentricity is the difference between the ideal rotation center and the actual rotation center when the rotation stage is rotated

(Reference) Measurement Result (SGSP-60YAW-0B)

		()	1		2	2		3	4	1		5	6	3	7	'	8	3)	1	0	1	1	1	12
Target Position [°]		()	2	9	5	8	8	37	11	16	14	45	1	74	20	03	23	32	26	31	29	90	31	19	34	48
Positioning Direction		1	+	†	1	1	1	1	ļ	1	1	†	1	1	1	1	+	1	+		1	1	1	†	1	1	1
Position Deviation [°]	1st time	0.000	0.015	-0.009	0.003	-0.010	-0.001	-0.013	-0.004	-0.012	0.001	-0.007	0.009	-0.007	0.009	0.000	0.012	0.004	0.016	0.002	0.015	0.007	0.020	0.000	0.013	-0.001	0.010
(Measured Value – Target Position)	2nd time	0.002	0.015	-0.007	0.003	-0.009	-0.001	-0.012	-0.004	-0.012	0.001	-0.006	0.009	-0.007	0.009	-0.001	0.013	0.004	0.016	0.002	0.015	0.007	0.020	0.000	0.013	-0.001	0.011
	3rd time	0.003	0.015	-0.007	0.003	-0.009	-0.001	-0.012	-0.004	-0.012	0.001	-0.007	0.009	-0.007	0.009	-0.001	0.013	0.004	0.016	0.002	0.015	0.007	0.020	0.000	0.014	-0.001	0.011
	4th time	0.003	0.016	-0.007	0.003	-0.009	-0.001	-0.013	-0.004	-0.012	0.000	-0.006	0.009	-0.007	0.009	-0.001	0.013	0.004	0.016	0.002	0.015	0.007	0.020	-0.001	0.014	-0.001	0.011
	5th time	0.002	0.016	-0.007	0.004	-0.009	-0.001	-0.013	-0.004	-0.012	0.001	-0.007	0.009	-0.007	0.009	-0.001	0.014	0.003	0.016	0.002	0.015	0.007	0.020	-0.001	0.014	-0.001	0.011
Mean Position Deviation >	<	0.002	0.015	-0.007	0.003	-0.010	-0.001	-0.012	-0.004	-0.012	0.001	-0.007	0.009	-0.007	0.009	-0.001	0.013	0.004	0.016	0.002	0.015	0.007	0.020	0.000	0.014	-0.001	0.011
Standard Deviation X		0.001	0.000	-0.001	0.000	-0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
X+S		0.003	0.016	-0.007	0.004	-0.009	-0.001	-0.012	-0.004	-0.012	0.001	-0.006	0.009	-0.007	0.009	0.000	0.013	0.004	0.016	0.002	0.015	0.007	0.020	0.000	0.014	-0.001	0.011
X-S		0.001	0.015	-0.008	0.003	-0.010	-0.001	-0.013	-0.004	-0.012	0.000	-0.007	0.009	-0.007	0.009	-0.001	0.013	0.003	0.016	0.002	0.015	0.007	0.020	-0.001	0.013	-0.001	0.010
Lost Motion B=X↑-X↓		0.0	135	0.0	107	0.0	084	0.0	088	0.0	125	0.0	154	0.0	163	0.0	36	0.01	122	0.0	127	0.0	130	0.0	139	0.0	1120
Maximum (Position Deviation) Value S † -	+S↓+ B	0.0	148	0.0	116	0.0	091	0.0	091	0.0	129	0.0	158	0.0	168	0.0	42	0.01	127	0.0	131	0.0	133	0.0	144	0.0	1125

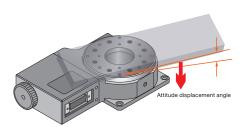
■Result

Maximum Lost Motion 0.0163° Unidirectional Positioning 0.0022° 0.0009° Bidirectional Positioning 0.0168

Wobble Accuracy 12µm

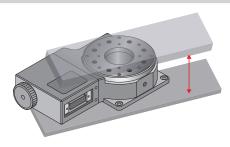
Angular Accuracy

Moment Stiffness



The angular displacement of the stage when unit moment load is applied.

Parallelism



The parallelism of the table fixed on the stage against the base plane.

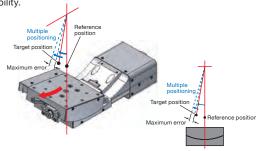
Measurement of Goniometer Stage Accuracy

Positional Accuracy

Positional Repeatability

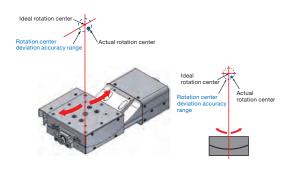
Positioning is performed multiple times from the same direction on any position of the stage, and the maximum value of the deviation amount with respect to the stop position is calculated.
The maximum of those numerical values is taken to be positional

repeatability.



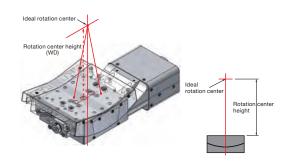
Rotation Center Deviation Accuracy

The maximum deviation range from the ideal rotation center position when a gonio stage is moved throughout the full travel.



Rotation Center Height

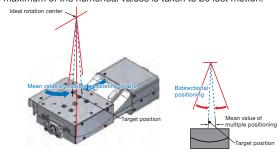
The distance to the top surface of the table from the ideal rotation



Lost Motion

Positioning is performed multiple times in the (+) forward and (-) backward directions on any position (e.g. both ends or center point) of the stage, and the mean value of the deviation amount with respect to the stop position is calculated.

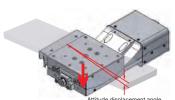
The maximum of the numerical values is taken to be lost motion.



Angular Accuracy

Moment Stiffness

The angular displacement of the stage when unit moment load is applied.



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□60mm

□80mm

□85mm

□100mm □120mm



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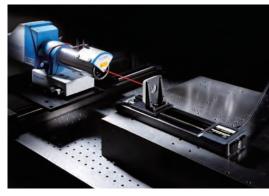
Actuators

Motorized Stages Guide

Accuracy Verification

Motorized stage accuracy is, in principle, confirmed in compliance with the JIS test code for machine tools (JIS B 6190). In addition, all measuring instruments are traceable standard instruments compliant to the national standard.





Category	Measurement Item	Device Used	Standards		
	Positioning Accuracy				
	Positional Repeatability	Dynamic Calibrator (HP5529A)	JIS B 6190		
Linear Stage	Lost Motion	(,			
	Running Parallelism	Dial Indicator	Company Standard		
	Pitch/Yaw	Auto Collimator	Company Standard		

It has to be guaranteed that measured values and indicated values are within the specification range of international standard values. In other words, traceability must be ensured. JIS defined this traceability as "the capacity to trace measurement results back to the domestic measurement standards, with the use of measuring instruments that have gone through a sequence of calibrations with high-ranking standards."

Linear Stage Traceability System Diagram									
State Institution	National Institute of Standards and Technology (NIST)								
Manufacturer	Agilent Technologies, Inc.								
Calibration Device	Dynamic Calibrator								

Category	Measurement Item	Device Used	Standards		
	Positional Repeatability	Rotary Encoder	Company Standard		
Rotation Stage	Lost Motion	Hotary Encoder	Company Standard		
	Wobble Accuracy	Dial Indicator	Company Standard		
	Positional Repeatability	Rotary Encoder	Company Standard		
Goniometer Stage	Lost Motion	hotary Encoder	Company Standard		
Gorilometer Stage	Rotation Center Height	Three Dimensional Instrumentation	Company Standard		
	Rotation Center Deviation Accuracy	Three Differisional instrumentation	Company Standard		

Accuracy Check in Assembled State

We check accuracy of motorized stages as a single unit. Regarding the accuracy check in assembled state, we need to confirm use conditions etc. Contact our International Sales Division separately.

Accuracy Check at Delivery Destination

We cannot conduct accuracy check at delivery destinations. We will request a check from organizations such as Japan Quality Assurance Organization as necessary. Contact our International Sales Division separately for more information.

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□40mm

□60mm

□85mm

□100mm

□120mm

Interpretation of the Specification Table

	Specificat	tions		
1	Part Number			**_**
2	Opposite Mod	del		**-**R
3		Travel	**mm	
4		Table Size	**×**mm	
5	Mechanical	Feed Screw		
6	Specifications	Positioning S	lide	
7		Stage Materia	al	
8		Weight		**kg
9		Resolution	(Full)	**µm/pulse
0		riocolation	(Half)	**µm/pulse
10		MAX Speed	**mm/sec	
11		Repeatability		**µm
12		Positional Re	peatability	**µm
13		Load Capacit	**N (**kgf)	
			Pitch	**"/N•cm
14	Accuracy	Moment Stiffness	Yaw	**"/N•cm
	Specifications		Roll	**"/N•cm
15		Lost Motion		**µm
16		Backlash		**µm
17		Parallelism		**µm
18		Running Para	llelism	**µm
19		Orthogonality	of Motion	**µm
20		Perpendicularit	y of Motion	**µm
21		Pitch / Yaw		**"/**"
22		Sensor Part N	Number	
23	Sensor	Limit Sensor		
24	0011301	Origin Sensor	•	
25		Proximity Orig	gin Sensor	

	Motor / Se	ıs					
26		Туре					
27	Motor	Motor Part Number					
28		Step Angle					
29		Power Voltage					
30	Sensor	Current Consumption					
31	Sensor	Control Output					
32		Output Logic					

Compatib	le Driver / Controll	er
Control System	Compatible Driver	
	Compatible Controller	

- 1	Dart	Number	

[Mechanical Specifications] 3

Table Size 4

5

Feed Screw

6 Positioning Slide

Stage Material 8 Weight

[Accuracy Specifications]

Resolution (Full)

10 MAX Speed

11 Positioning Accuracy

12 Positional Repeatability

13 Load Capacity

14 Moment Stiffness

Pitch

Yaw

Roll

15 Lost Motion

16 Backlash 17 Parallelism

18 Running Parallelism

21 Pitch

Yaw

Opposite Model

Travel Indicates the full travel.

> Size of top table face. Ball screw

* Precision ground screws * Outer rail structure

Crossed roller guide Material used for the product. Self weight of the product.

Refer to the accuracy verification page for more information.

Reference G004 – G007

Travel per pulse for full step

Travel per pulse for half step MAX speed of the product (maximum travel speed). Deviation between the measured value and the target value at the positioning point.

Deviation in stop positions when unidirectional positioning is performed multiple times.

Load capacity at the center of the stage.

Stage strength against a load exerted at a position away from the center of the table top (the table center and the center of gravity of a work does not match). It indicates the degree of tilt of the table top (") when 1N load is exerted at the position 1cm away from the center of the

stage surface. Stiffness in the direction of tilt around the axis in the

horizontal plane perpendicular to the direction of travel when moving the stage for full travel. Stiffness in the direction of tilt around the axis in the

vertical plane perpendicular to the direction of travel when moving the stage for full travel. Stiffness in the direction of tilt around the axis in the horizontal plane parallel to the direction of travel when

moving the stage for full travel. Deviation between the stop position of forward positioning and that of backward positioning.

Deviation in each direction when a certain load is exerted in forward and backward directions at an arbitrary position on the stage.

The parallelism of the table fixed on the stage against the base plane.

Note that it is different from "Running Parallelism". Displacement in the vertical direction of the table during

stage motion along the full travel. 19 Orthogonality of Motion Working displacement in the direction perpendicular to the Y axis when referenced to the X axis motion of the XY axis

stage. 20 Perpendicularity of Motion Displacement between the Z axis stage and the perpendicular optical breadboard when moving the stage for full

> Maximum angle displacement in the direction of tilt around the axis in the horizontal plane perpendicular to the direction of travel when moving the stage for full travel. Maximum angle displacement in the direction of tilt around the axis in the vertical plane perpendicular to the direction of travel when moving the stage for full travel.

[Sensor] 22 Sensor Part Number Sensor used for the product.

23 Limit Sensor Indicates whether fitted with a limit sensor. 24 Origin Sensor Indicates whether fitted with an origin sensor. Indicates whether fitted with a proximity origin sensor.

25 Proximity Origin Sensor [Motor Specifications]

26 Type

27 Motor Part Number 28 Step Angle

Type of motor.

Part number of motor used for the product. Step angle of the motor.

[Sensor Specifications] 29 Power Voltage

30 Current Consumption

31 Control Output 32 Output Logic

Specifications of the sensor.

[Compatible Driver / Controller]

34 Compatible Controller

33 Compatible Driver Driver/controller compatible with the product.

[Memo]

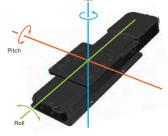
33...

The drawing shows the types of tilt when a linear stage travels.

Towards the direction of travel...

Pitch Rotation around the axis in the horizontal plane perpendicular to the direction of travel Yaw Rotation around the axis in the vertical plane perpendicular to the direction of travel

Rotation around the axis in the horizontal plane parallel to the direction of travel



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□80mm 85mm

□100mm

□120mm



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Operating Environment of Motorized Stages

Use motorized positioning stages within the following operational environment temperature range. Contact our International Sales Division separately if you desire to use the stages outside the operational environment temperature range.

*Operating environment

Temperature: 5°C - 40°C

Humidity: 30% - 80% (without condensation)

*Recommended environment

Temperature: 23°C ±5°

Humidity: 60±10% (without condensation)

Operational environment temperature changes depending on various conditions such as the type of motorized positioning stage, installation and operation conditions.

Avoid use of the stages in the following sites.

- Sites subject to water or oil
- Sites subject to direct sunlight or radiant heat
- Sites subject to dirt and dust

- Sites subject to vibration or impact
- Sites close to fire
- Sites subject to inflammable gas and corrosive gas

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Piezo

Life Cycle

Although the life cycle varies depending on intended use or application, 2,000 to 3,000 hours for linear systems and 1,000 to 1,500 hours/year (about 3 to 4 hours/day) for rotation/goniometer systems are assumed.

Note that the above assumption may not apply to repeated operations (high-speed drive or high-load drive). Careful maintenance or supply of grease is important for using the products for a long time without a problem.

Reference G018 Maintenance / Grease Replacement

Storage

When not using motorized stages for a long time, store motorized stages wrapped with anti-rust paper, or store in a plastic bag with a desiccant.

Storage Temperature: 0°C - 40°C

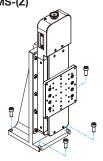
Humidit: 10% - 85% (without condensation)

Example of Installation Procedure

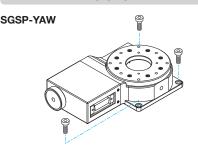
Linear

OSMS

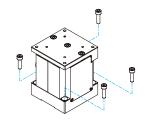




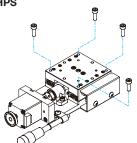
Rotation



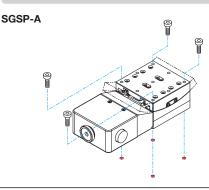
OSMS-ZF



HPS



Goniometer



Attention

- ▶ Recommended parallelism for stage mounting surface is 0.02 or lower. A product might be warped when it exceeds 0.02, causing abnormal operation.
- When mounting another product on the upper table of a motorized stage, make sure that the stage is not subjected to abnormal external force.
- ▶ Foreign substances in tapped holes on the upper table or on the side of the stage will cause malfunction.

Mounting Orientation

The values in the specifications of each product are based on installation on a level surface.

Note that load capacity and other precision values will significantly change for upside down, lateral horizontal and other installation orientations, because mounting on other than the horizontal surface require securing with screws.

Category	Series Name	Positioning Slide	Upside Down	Lateral Horizontal	Lateral Vertical
OSMS		Outer Rail	0	0	0
Linear	HPS	Ball Guide	0	0	\triangle
	TAMM, KST	Crossed Roller	0	0	\triangle
	SGSP-YAW	Worm and Worm Wheel	0	\triangle	\triangle
Rotation	HDS-YAW	Bearing	0	\triangle	\triangle
	KST	Crossed Roller	0	0	\triangle
Goniometer	OSMS-A/B	Ball Guide	0	0	\triangle
Gorilometer	SGSP-A/B	Crossed Roller	0	\triangle	\triangle

- O: Possible with limits on load capacity and other accuracy.
- △: Possible depending on the model, with limits on load capacity and other accuracy.
- ×: Not allowed

Please contact our International Sales Division regarding other unclear points related to mounting orientation.

Selection Guide

Motorized stages are categorized in several different travel axes and types by the differences in structure or positioning slide.

Since precision, stiffness and price differ depending on the type, select a product ideal for the intended purpose.

Procisio -	Precision		Rotation		Goniometor	
Precision	Series Name	Relevant Product	Series Name	Relevant Product	Series Name	Relevant Product
High	KST Crossed Roller Reference G062 –		KST Bearing Reference) G078			
	TAMM Crossed Roller		HDS- YAW Bearing		OSMS Ball Guide Reference G082	
	HPS Ball Guide		SGSP Bearing			
Bottom	OSMS Outer Rail Reference G032 -		G074 –		SGSP Crossed Roller Reference G086	

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□40mm

□60mm

□80mm

□100mm

□120mm



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□40mm

□60mm

□80mm □85mm

□100mm

□120mm

Others

HPS Series

Durable linear stages with excellent cost performance.



Motor Variation

Compatible with 2 phase stepping motor, q stepping motor and AC servo motor manufactured by Oriental Motor Co., Ltd. in addition to the standard 5 phase stepping motor.

Low Price

Integration of the main unit and guide has reduced the number of parts and assembly man-hours, offering low price.

High Durability

Ball screws are used for the feed mechanism to achieve both low price and durability.

OSMS Series





Stepping motor stages compatible with versatile travel range between 35 to 500mm and can be used in any orientation.



Slim Body

These stages are our standard CE-compliant motorized stages, covering motors neatly. These stages offer attractive range of travel by fully utilizing the features of the outer rails.

Line Up

Full closed loop control for stage table positioning, and linear encoder version for coordinate counting are standard line up.

Option

Various options are available according to the application. Geared motors and electromagnetic brakes are available for high-load specifications and Z axis specifications, respectively. Contact our International Sales Division for more information.

Safety Cover

Safety specifications of these stages are compliant with safety requirements on electrical measuring and control equipment and electrical equipment for laboratory use (EN61010-1:2010).

The structure in which the U-shaped outer rail and inner block with center integrated ball screw offers high stiffness, high

Base Plate

Slim Body

Stages can be installed by securing with bolts without removing their covers. If rigidity is required, the base plates can be removed.

5 Phase Stepping Motor

Achieves the minimum size and minimum weight with high speed and high torque. The rated current is 0.75A/phase which is common to all sizes.

<Line Un>

CLITE OP>								
Part Number	Table Size [mm]	Wide [mm]	Height [mm]	Travel [mm]	Load Capacity [N]			
OSMS20-35(X)	85×85	85	35.7	35	78.4			
OSMS20-85(X)	85×85	85	35.7	85	78.4			
OSMS26-50(X)	100×100	100	42	50	117			
OSMS26-100(X)	100×100	100	42	100	117			
OSMS26-200(X)	100×100	100	42	200	117			
OSMS26-300(X)	100×100	100	42	300	117			
OSMS33-300(X)	120×120	120	57	300	196			
OSMS33-500(X)	120×120	120	57	500	196			

XY axis mounting becomes easier.



Two single axis stages can be assembled directly and used as an XY axis stage without the need of XY-axis mounting plates.



Translation Motorized Stages, Flat Z axis - 5 Phase Stepping Motor

Motorized Extended Guide Goniometer

TAMM Series

RoHS

Motorized crossed roller stages that combine compactness, low-profile and high durability



High Durability

Line contact with rollers and V groove rail offers high stiffness, low friction and virtually no differential slip, suitable for minute feeding.

Compact/ Low-profile "Ideal for space-saving and assembly of systems with low optical axis."

Sizes

 \square 40/ \square 60/ \square 100mm are available.

KST Series

RoHS



High Precision

High precision stages with steel body relatively strong against heat, and in which precision ball screws and crossed roller guide are arranged with highest precision.

High Load Capacity

Achieved the maximum load capacity of 392N (40.0kgf).

High Stability

Steel body fitted with large table face can mount anything.

Rotation

SGSP-YAW Series

RoHS

CE

Stepping motor driven rotation stages fitted with bearing guide and worm gear feed mechanism



Low Price

Number of parts and assembly time were reduced to lower the price.

Compact/ Low-profile Ideal for space-saving and assembly of systems with low optical axis.

Sizes

 $\phi 40/\phi 60/\phi 80/\phi 120/\phi 160$ mm are available.

HDS-YAW

RoHS

High durability rotation motorized stages for minute angle adjustment.



High Durability

Ball screws and steel belts used in the drive mechanism offer excellent durability in minute angles.

Isokinetic

Since it converts linear motion by the ball screw into rotational motion by the steel belt, there is no difference between traveling center and end by rotation speed and resolution.

Sizes

 $\phi 40/\phi 60/\phi 80/\phi 120/\phi 160$ mm are available.

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□40mm

□60mm

□80mm

□85mm

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□120mm



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KST-YAW Series

RoHS | C €

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□40mm **□60mm**

□80mm

□85mm

□100mm □120mm

Others

High Precision

High repeatability stages fitted with bearing positioning slide.

High Load Capacity

High precision and high stability rotation motorized stages fitted with bearing positioning slide

Achieved the maximum load capacity of 392N (40.0kgf).

High Stability

Steel body fitted with large table face can mount anything.

High precision motorized goniometers with integrated bearing ways for superior stiffness, accuracy and durability

Their smooth movement is ideal for frequent angle adjustment.

Low Price

Number of parts and assembly time were reduced to lower the price.

High Precision High Stiffness High Durability

Integrated ball guide structure in which guides are directly processed on the main body minimized machining/assembly errors and improved rotation center accuracy.

SGSP-A/B Series

RoHS

Stepping motor driven motorized goniometer stages fitted with crossed roller guide



High Stiffness

High stiffness goniometer stages fitted with excellent abrasion resistant crossed roller guide.

Operability

Products with two axes combined offer further flexible alignment.

Lightweight

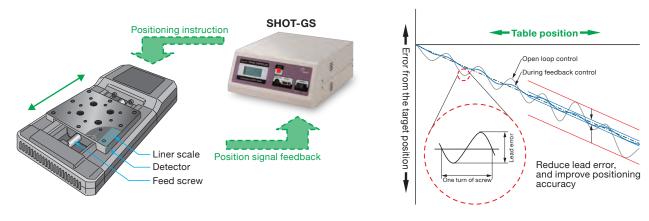
Aluminum body offers lightweight.

GS/CS series Guide

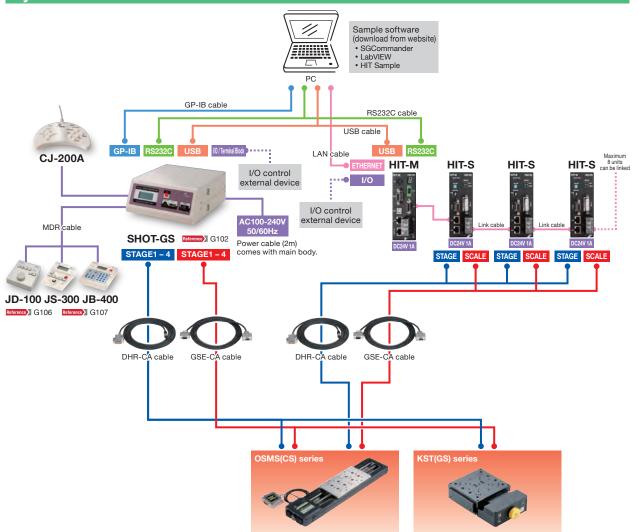
Full closed loop control system that controls a motorized stage with built-in high resolution compact linear encoder using a special controller.

- Linear encoder signal feedback and micro-step drive can minimize lead error, which is inherent to feed screw mechanism.
- Small glass scale of linear expansion coefficient enabled a highly reliable positioning system stable against fluctuations in ambient environment.
- Ideal for use in positioning that requires precision in submicron units, and prolonged driving that is affected by reproducibility by temperature drift.

Full Closed Control System (Image diagram)



System Chart



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□80mm

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□100mm

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SGMV series Translation Motorized Stages - AC servo Motor

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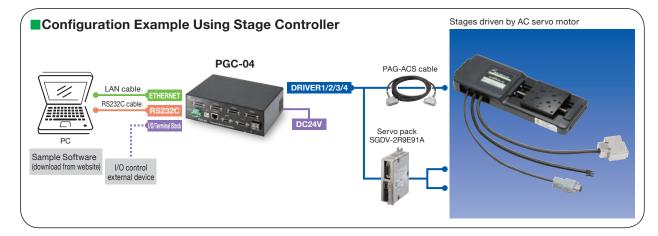
High precision/high stiffness stages driven by AC servo motor. The stage structure unifies the functions of precision linear guide and precision ball screw, places the linear guide, inner block (table) and drive ball screw at the same position, and uses high stiffness U-shape outer rail for the guide to offer small footprint with large load rating.

- AC servo motor stages are recommended for production equipment that runs at high speed accompanied by rapid acceleration/deceleration for reduction of takt time, because they generate sufficient torque in high-speed area and are less subject to position deviation.
- Stepping motor stages are recommended for positioning of optical systems that requires stability at rest.



Motor Type	Stepping Motor	Servo Motor
Control Method	Open loop control	Semi-closed loop control
Torque Characteristic	Torque is large in low speed and small in high-speed area	Generate the same torque throughout the low-speed area to high-speed area
Stability at Rest	Very stable under normal conditions, but cannot detect position deviation caused by external force, etc.	Deviation may occur within the range of in position, but it returns to the original position by detecting position deviation due to external force, etc. with an encoder.
Recommended Application	Applications that exert light load and require stability at rest, such as positioning and measurement in optical systems or small areas	Applications that do not allow position deviation even during high-speed operation or load fluctuation, such as production lines

 The control system has automatic tuning functions, and a stage controller system usable just by connecting with a special cable as well as servo pack that has high compatibility with the existing FA system are available.



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Vacuum **Options**

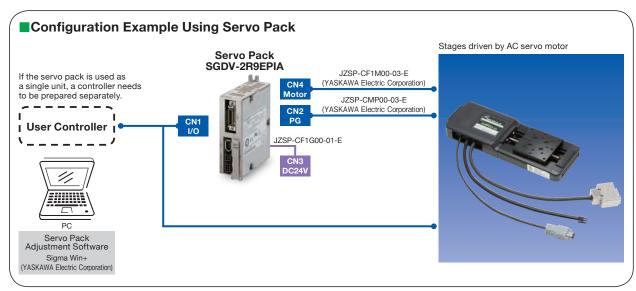
□40mm

□60mm

□80mm □85mm

□100mm

□120mm

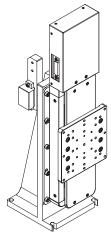




Mounting of Electromagnetic Brake Equipped Motors

A normally closed type electromagnetic brake exerts braking force when the power is off and securely holds load. It prevents the movable table from falling to avoid sample damage.

OSMS26-100(Z) Example of electromagnetic brake assembly dimensions



 Change stepping motors or servo motors (optional) used for Z axis motorized stages to electromagnetic brake equipped motors.

Guide

- ► Contact our International Sales Division for changing to electromagnetic brake. Or use the mortorized stage system question sheet. Reference 3 G111
- ▶ To drive a motorized stage, DC24V power voltage is required.

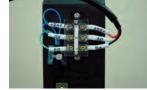
Attention

External dimensions diagram will change because motors are changed to electromagnetic brake equipped motors.

Wiring Example

Lead wire for brake of electromagnetic brake equipped motor

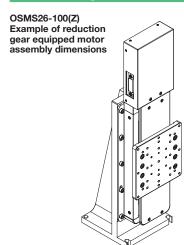




Stage controller side

Motorized stage side

Mounting of Reduction Gear Equipped Motors



Deceleration, high torque and high resolution can be achieved by changing to reduction gear equipped motors. Effective for downsizing and weight saving of systems since it does not require power supply.

 Change 5-phase stepping motors or servo motors used for Z axis motorized stages to reduction gear equipped motors.

Guide

► Contact our International Sales Division for changing motors. Or use the motorized stage system question sheet.

Reference G111

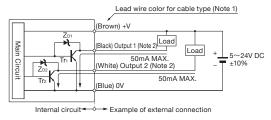
Attention

▶ Outline drawing may change because motors are changed with reduction gear equipped motors. The OSMS20 series are not compatible.

Limit Sensor

- Regarding the limit sensor used for motorized stages, refer to the specification of each product.
- We will change output operations or add a limit sensor on special orders.

■Input/Output Circuit Diagram (NPN output type)



■Output Operation

	Lead Wire Color	Output Operation
Output 1	Black	ON when light enters (NORMAL CLOSE)
Output 2	White	ON when shaded (NORMAL OPEN)

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□40mm

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□85mm

□100mm

□120mm

Others



GSC-01

GSC-02

SHOT-702





Reference G098

Reference G099

Reference G100

Standard driver (full step/half step)

0.75A/phase rated motor or lower

Single axis

1 – 2 axes

1 - 2 axes

OSMS-ZF SGSP-40/60YAW SGSP-ACT-B0



D15RP-CA cable

D15RP-CA cable

D15RP-CA cable

TAMM OSMS HPS



D15RP-CA cable

D15RP-CA cable

D15RP-CA cable



Not compatible

Not compatible

D15D15A cable



Not compatible

Not compatible

Not compatible

Stages with built in Glass-scale Encoder

Stepping Motor Stage



Not compatible

Not compatible

Not compatible

KST(GS) series



Not compatible

Not compatible

Not compatible

Part Name		1 axis Stage Controller	2 axis Stage Controller	2 axis Stage Controller	
Part Number		GSC-01	GSC-02	SHOT-702	
	Controller Function	0	0	0	
	Number of Control Axes	1	2	2	
	Stored Program Control	_	Δ	_	
	Feedback Control	-	-	_	
Primary Functions	Circular Interpolation Control	_	_	_	
	Linear Interpolation Control	_	-	_	
	Driver Function	Standard	Standard	Standard	
	Micro-step (Max. Division)	2	2 (half step only)	250	
	Driving Current (A/phase)	0.8	0.8	1.1	
	Power Voltage	DC24V 1.2A	DC24V 2A	AC100 — 240V 50/60Hz	
General Specifica-	Power Consumption	30VA	48VA	50VA	
tions	External Dimensions (W×H×Dmm)	47×90×125	180×40×125	260×70×280	
	Weight (kg)	0.4	0.7	2.8	
	GP-IB	_	-	_	
Interface	RS232C	0	0	0	
пцегтасе	USB	_	_	_	
	Ethernet	_	-	-	

SHOT-302GS SHOT-304GS HIT-M PGC-04 **GIP-101** Reference G101 **™** G102 [™] G102 ■ G103 G103 **©** G104 Micro-step driver 1.4A/phase rated motor or lower 0.75A/phase rated motor or lower Single axis 1 - 2 axes 1 - 4 axes 1 - 8 axes 4 axes D15RP-CA D15RP-CA D15RP-CA D15RP-CA D15RP-CA cable cable cable cable cable D15RP-CA D15RP-CA D15RP-CA D15RP-CA D15RP-CA cable cable cable cable cable D15D15A D15D15A D15D15A D15D15A D15D15A cable cable cable cable cable D15D15A D15D15A D15D15A Not compatible Not compatible cable cable cable DHR/GSE DHR/GSE DHR/GSE cable Not compatible Not compatible cable cable DHR/GSE DHR/GSE Not compatible Not compatible Not compatible cable cable

Intelligent Positioning System	2 axis Stage Controller	4 axis Stage Controller	Extensible Stage Controller (Master)	Extensible Stage Controller (Slave)	Pulus Generating Controller
GIP-101	SHOT-302GS	SHOT-304GS	HIT-M	HIT-S	PGC-04
0	()	0	-	0
1	2	4	8	_	4
_	(0	_	0
_	Glass	scale	Glass scale (exc	ept for KST(GS))	-
_	()	0	_	0
_	2 a	xes	3 axes	-	0
Micro-step	Micro-step		_	Micro-step	_
250	25	50	_	250	_
0.75	1	.4	_	1.1	_
AC100-240V 50/60Hz		0–240V 60Hz		24V A	DC24V 1.4A
100VA	160VA	300VA	24	VA	34VA
145×205×81	270×1	270×118×302		20×50	180×140×60
2.0	5.5	6.5	0.62	0.63	1.3
_	0	0	_	-	_
0	0	0	0	-	0
_	0	0	0	-	-
_	_	_	0	-	0

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□40mm □60mm

□80mm

□85mm

□100mm □120mm



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□120mm



Part Name					
Part Number					
	Driving Motor				
	Drive System				
	Driving Current (A/phase)				
	Excitation System				
	Number of Divisions				
Primary Functions	Input Signal				
	Input Logic				
	Max. Response Frequency				
	Auto Current Down OFF Input				
	Motor Excitation OFF Input				
	Micro-step Selection Input				
	Origin Excitation Timing Output				
General Specifications	Input Voltage				
	Operating Temperature Range				
	External Dimensions (W×H×Dmm)				
	Weight (kg)				

Stage	Motor Used	Basic Step Angle [°]	Phase Current [A/phase]	External Dimensions [W×H×Dmm] (excluding shaft)
OSMS40-5ZF SGSP-ACT series	PK513PB-C9		0.35	20×20×72
OSMS20-35 OSMS20-85 series	TS3664N4E10			24×24×31
SGSP-40/60YAW HDS-60 series	TS3664N4	0.72		24×24×31
OSMS26 OSMS60-ZF SGSP-60A/B TAMM OSMS-40/60	PK523HPB-C12	0.036	- 0.75	28×28×32
SGSP-80/120/160YAW HPS HDS-80/120 series	PK525HPB-C4			28×28×51.5
OSMS80-20ZF	A7177-90215KTG			28×28×61.3
OSMS33 series	TS3667N43E967			42×42×47
KST-120/160YAW series	TS3624N42E967	0.72		60×60×56.5
KST-50 / KST(GS)-50 KST-100 / KST(GS)-100 KST-200 / KST(GS)-200 series	PK564-NBW PK566-NBW PK569-NBW		1.4	60×60×46.5 60×60×57.5 60×60×87













Compact Driver	Compact Driver	Compact Micro-step Driver	Compact Micro-step Driver	Micro-step Driver	Micro-step Driver
SG-5MA	SG-5M	SG-55MA	SG-55M	SG-514MSC	MC-7514PCL
		5-phase ste	pping motor		
		Bipolar constant cu	rrent pentagon drive		
0.25 — 0.85	0.5 — 1.4	0.23 - 0.75	0.5 — 1.6	0.3 - 1.4	0.5 — 1.4
Full/Ha	alf step	Micro	o-step	Micro-step	Micro-step
Two t		1, 2, 4, 5, 8, 10	ypes , 16, 20, 25, 40, 125, 200, 250	16 types 1, 2, 2.5, 5, 8, 10, 20, 25, 40, 50, 80, 100, 125, 200, 250	16 types 1, 2, 4, 5, 8, 10, 16, 20, 25, 4 50, 80, 100, 125, 200, 250
1 clock inp 2 clock inp			out method out method	2 clock input method	1 clock input method 2 clock input method
Photocou	pler input	Photocoupler input		C-MOS equivalent negative logic input	Photocoupler input
50k	pps	500kpps		500kpps	500kpps
No	ne	None		None	Equipped
Equip	oped	Equipped		Equipped	Equipped
No	ne	4 bit signal input or switching by the number of division setting switch		4 bit signal input	Switching by the numb of division setting switch
No	ne	Equi	pped	Equipped	Equipped
DC20 — 40V 1.5A Max	DC20 — 40V 3A Max	DC24 — 36V 1.5A Max	DC24 — 36V 3A Max	For motor drive: DC24 - 36V ±10% 2A or lower For logic: DC5V ±5% 0.1A or lower	AC100 - 230V±10% 50/60Hz 3.5A Max
0 – 4	40°C	0 - 40°C		0 - 40°C	0-40°C
77×3	2×45	105×	38×74	91×36×70	170×130×39
0.	.1	0	.2	0.2	0.75

	×		×		X
	0	0			0
					0
O*		O*			0
O*		O*			0
O*		O*			
O*		O*			0
×	* DC36V	×	* DC36V	* DC36V	
×	0	×	0		

^{*} Can be used with 0.75A/phase.

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□40mm

□60mm

□80mm □85mm

□100mm

□120mm



Softwares

Software for creating operation check or automation applications and for supporting program development are available.

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□100mm

□120mm

Others

Sample Softwares

SGCommander

RS232C interface stage controller control software. In addition to remote control from a PC, simple program control using Excel is possible.

LabVIEW Sample Program

Sample module for controlling stages using the graphical programming environment LabVIEW of National Instruments Corporation

Compatible with LabVIEW 5.1/6i/7.1/8.6/2010/2012

Special Application Softwares

SGTERME Reference G024



Terminal software for receiving and sending SETERM commands input in Excel cells. Applications can be developed flexibly using repetition and conditional branching macros, without programming knowledge. Compatible with 32/64bit version of Windows®XP/Vista/7 Refer to our website for the latest support status



SGEMCSE Reference G025

Software for positioning & measurement that automatically collects data and outputs results in Excel simply by selecting a controller and setting a measuring instrument.

Applications can be developed using the program measurement function with routine drive patterns and the Excel instruction measurement function that measures arbitrary coordinates, without programs. Compatible with 32/64bit version of Windows®XP/Vista/7 Refer to our website for the latest support status.

Software for Positioning, Measurement & Analysis



SGMACSE

Software with enhanced functions such as real-time graphical display, analysis or correction of measurement data and RS232C binary data exchange.

Compatible with 32 bit version of Windows®XP/Vista/7 Refer to our website for the latest support status

Automated Collimation Measurement Software SGCAMSE



Used in combination with the collimation checker system, this software automatically measures laser light collimation (parallelism) and judges good or bad.

Compatible with 32 bit version of Windows®XP/Vista/7 Refer to our website for the latest support status.

Software for Monitoring & Control



Software for measuring dimensions and angles based on images loaded from a USB camera connected to a PC, as well as for saving loaded images.

It can measure an arbitrary point or perform simple time-lapse measurement when used in combination with a stage. Compatible with 64 bit version of Windows®XP/Vista/7 Refer to our website for the latest support status.

Software for Liquid Crystal Evaluation System SGLCESE



Being compatible with major color luminance meters and spectroradiometers, this software packaged luminance, chromaticity, viewing angle characteristics and other functions required for flat panel evaluation. Compatible with 64 bit version of Windows®XP/Vista/7

Refer to our website for the latest support status.

Library for Program Development

Component Software for VB.NET **SGNETXE**



RS232C/GP-IB/USB communication library enabling control programming for stage controller with VB.NET.

Compatible with 32/64bit version of Windows®XP/Vista/7 NET Framework1.1 or later version is required.

ActiveX for Positioning & Measurement SGACTXE/SGPATXE/SGSFSXE

RS232C/GP-IB/USB communication library enabling control programming for stage controller with VB6.0 or VBA.

32 bit Windows®-only Windows®Vista/7 does not work with USB.

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▶ Contact our International Sales Division for more information. Information is also available on WEB

Part Name	Part Number
Software for Positioning, Measurement & Analysis	SGMACSE
Automated Collimation Measurement Software	SGCAMSE
Software for Monitoring & Control	SGVIEWE
Software for Liquid Crystal Evaluation System	SGLCESE

Part Name	Part Number
Component Software for VB.NET	SGNETXE
ActiveX for Positioning & Measurement	SGACTXE SGPATXE SGSFSXE

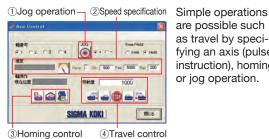


Free Software | SGCommander (for RS232C) Windows[®] Version

(For SHOT(Mark)-102/202/204, FINE(Mark)-501/502/503, FINE-01, SHOT-302GS/304GS, PAT-001, OMEC-2BF/2BG/4BF/4BG, SHOT-602, CSG-602R/522R, MINI-5D, BS-302GS/304GS, PKA-ID-02, SHOT-702, FINE-01y, GIP-101, GSC-01/02)

WEB Reference Home > Support > Software Information > Sample Software: SGCommander

Free software is available to operate your controller easily from a PC. Each axis of a connected motorized stage can be moved using buttons on the screen. The software can be downloaded from our website.



are possible such as travel by specifying an axis (pulse instruction), homing or jog operation.



Controllers such as SHOT-30* /702 and FINE-**, which have a built-in program function. allow editing of programs from a PC. Since data can be downloaded/uploaded from/to Excel sheets, it is easy to edit programs. In addition, upload of memory switch or download mode is available.

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□40mm

□60mm **□80mm**

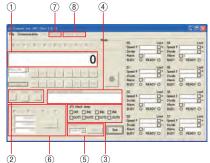
□85mm

□100mm

□120mm Others

Free Software (for HIT) HIT sample for LAN/RS232C

Free software is available for HIT of SGCommander.



Functions

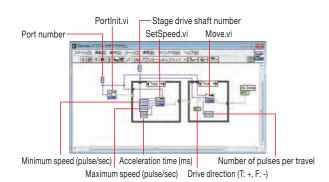
- travel
- 3IO menu
- (Terminal)

- 1)Relative position
- ②Origin return
- (4)Command input
- ⑤Number of division setting
- 6Speed change Program editing

®Memory switch menu

Free Application LabVIEW (for v.5.1/v.6i/v.7.1/v.8.6/v.2010/v.2012) RS232C/GP-IB

LabVIEW application is available for LabVIEW users.



Other: 30 Day Trial Version | SGEMCSE / SGTERME

SGEMCSE.....SGEMCSE is software for collecting data or measuring using automatic positioning equipment, measuring instrument or controller, and is offered 30 days for free.

SGTERM E.....It allows command input using Excel for easy program making. SGTERME is ideal software to link with various devices, and is offered 30 days for free.





SIGMA KOKI

Part Number

Terminal Software

SGTERME

SGTERME



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□85mm

□100mm

□120mm

Others

General-purpose communication terminal software that uses Excel.

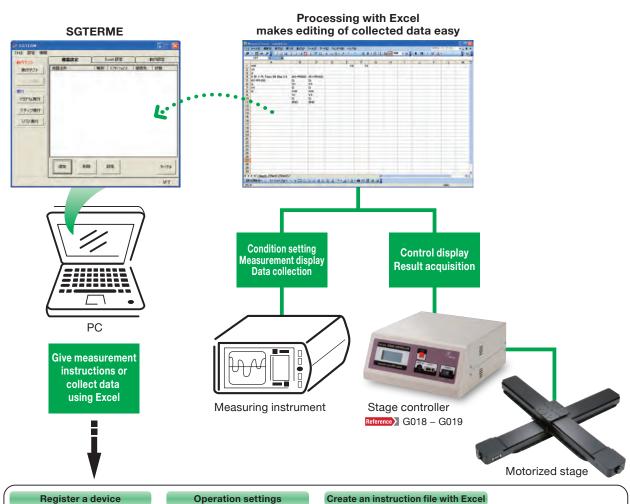
- Positioning and measurement can be performed just by listing and executing commands in an Excel sheet.
- Continuous process or step-by-step process can be selected.
- Use of SGTERM's original control scripts, "If", "Jump", "Loop" and "Print" in an Excel worksheet simplifies processing control.
- Since measurement results are output to an Excel sheet, easy to analyze and manage measured data.
- Set content can be saved as a "*.SGE" file, which facilitates setting of the same process again.
- RS232C*1/GP-IB*2/USB*3 interfaces are supported.
- Compatible with Windows®XP/Vista/7*4.

- RS-232C ports are available from COM1 to COM8.

 As for GP-IB, only GP-IB of National Instruments Corporation is supported.

 USB is only supported for SHOT-302/304 series, HIT-M, FINE-01y/503 series, and OMEC-2BG/4BG series.

 Conditions when used with Windows®7 are as follows.
 - Administrative right is required for installation as well as execution.
 - 32/64 bit versions are supported. Check on our website for the latest support status.









- Run commands written in cells in order.
- Perform repetition or conditional branching using control scripts.
- Cell functions and VBA can also be used in combination.

Software for Positioning & Measurement | **SGEMCSE**





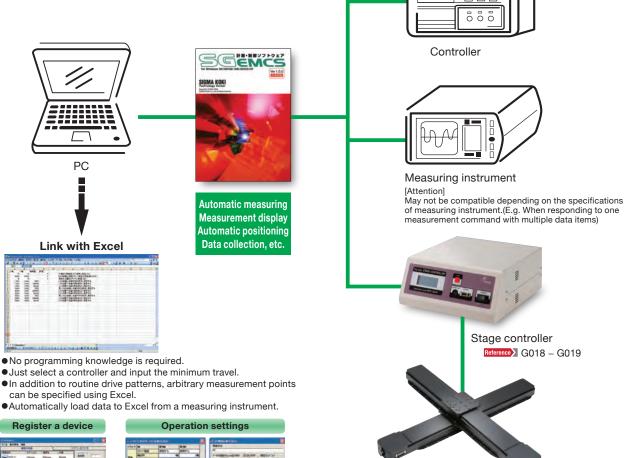
SGEMCSE Part Number

Positioning and measurement software highly compatible with motorized positioning devices offered by Sigma Koki.

- Multiple repetition of positioning/measurement sequence is easily realized.
- Various functions are available such as manual or time-series measurement and count presetting.
- By creating Excel instruction files, both stage control and measurement with a measuring instrument can be performed simultaneously.
- Since measurement results are output to an Excel sheet, easy to analyze and manage measured data.
- Set content can be saved as a "*.SGS" file, which facilitates setting of the same process again.
- Using this software in combination with motorized positioning devices offered by Sigma Koki, a positioning and measurement system can be easily configured.
 • RS232C*1/GP-IB*2/USB*3 interfaces are supported.
- Compatible with Windows®XP/Vista/7*4.

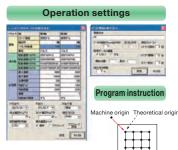
- RS-232C ports are available from COM1 to COM8.
 As for GP-IB, only GP-IB of National Instruments Corporation is supported.
 USB is only supported for SHOT-302/304 series, HIT-M, FINE-01γ/503 series, and OMEC-2BG/4BG series.
- Conditions when used with Windows®7 are as follows.

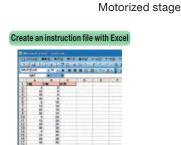
 Administrative right is required for installation as well as execution.
- 32/64 bit versions are supported. Check on our website for the latest support status.











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□40mm

□60mm

□80mm

□85mm

□100mm

□120mm



Motorized Stage/Controller/Cable Sets

These sets are offered at value prices. These sets are easy to operate. Enjoy them as soon as they arrive.

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□100mm □120mm Others

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X axis Set | HPS60-20X-SET



This set enables easy automatic positioning in one straight direction and JOG operation.

Stage size : 60mm×60mm
Travel : 20mm
Load Capacity : 49N [5kgf]
Cable lengh : 3m

Products Name	Part Number	Quantity	Reference
High Performance Motorized Stages	HPS60-20X-M5	1	G028
Single axis Stage Controller	GSC-01	1	G098
AC Adapter	PAT-001-POW1	1	_
D15RP Cable	D15RP-CA-3	1	G108

XY axis Set | SetHPS120-60XY-SET



This set enables XY axis automatic alignment, and program operation without using a PC.

Stage size : 120mm×120mm
Travel : 60mm
Load Capacity : 88.2 [9kgf]
Cable lengh : 3m

Products Name	Part Number	Quantity	Reference
High Performance Motorized Stages	HPS120-60X-M5	2	G028
2 axis Stage Controller	GSC-02	1	G099
Joystick Terminal	SJT-02	1	G106
AC Adapter	PAT-001-POW1	1	_
D15RP Cable	D15RP-CA-3	2	G108

rence E144

For easier positioning ... Manual stages which can be used in combination.

■θ axis Rotation Stages KSP-606M



Z axis Steel Extended Contact Slide Stages
TSD-603



Reference E086



G108

$Xy\theta$ axis Set HPS/HDS120-XYθ-SET



Motorized stage system for minute positioning and angle adjustment such as for marking of semiconductor wafers.

• It can be controlled externally using Ethernet/RS232C/ USB interface. Also, the number of axes is extendable by adding slave controllers (Part Number: HIT-S).

• Stage size : φ120mm : $\pm 6^{\circ}$ [θ axis] Travel : 60mm [XY axis] · Load Capacity: 58.8N [6kgf]

 Cable lengh : 3m

Products Name	Part Number	Part Number	Reference
High Performance Motorized Stages	HPS120-60X-M5	2	G028
High durability automatic rotation stage	HDS-120YAW	1	G080
Extensible Stage Controller (Master)	HIT-M	1	G103
Extensible Stage Controller (Slave)	HIT-S	3	G103
AC Adapter		1	_

D15RP-CA-3

XYZ axis Set | OSMS20-XYZ-SET

D15RP Cable



This set is best suited for measuring and inspection equipment and for XYZ axis automatic positioning of workpieces.

• It can be controlled externally using RS232C/GP-IB/USB interface, or manually using a joy stick (JS-300).

: 60mm×60mm Stage size

: 85mm [XY axis], 10mm [Z axis] Travel

Load Capacity: 29.4N [3kgf]

 Cable lengh : 3m

Products Name	Part Number	Part Number	Reference
OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor	OSMS20-85(X)	2	G032
Translation Motorized Stages, Flat Z axis - 5 Phase Stepping Motor	OSMS60-10ZF	1	G070
4 axis Stage Controllers	SHOT-304GS	1	G102
Joystick Terminal	JS-300	1	G107
D15RP Cable	D15RP-CA-3	1	G108
D15D15A Cable	D15D15A-CA-3	2	G108
MDR14-CA-2.5 Cable	MDR14-CA-2.5	1	G109

Make it more convenient ... Software for stage control

■Software for Positioning, Measurement & Analysis SGMACSE



■Software for Monitoring & Control SGVIEWE



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□40mm

□60mm

□80mm

□85mm

□100mm

□120mm

Others

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□40mm

□60mm _□80mm

□85mm

□100mm

□120mm

Others

Motorized stages with ball screws offering middle/high performance at low price.



- Ball screws with improved durability compared to the existing TSDM series.
- Our original high precision integrated ball guide used in place of a cross roller guide makes it possible to offer a price lower than the TAMM series.

Guide

- ▶ Please contact us when assembled into XYZ axis or use in reversion on the ceiling or vertical direction.
- ▶ Opposite model or various motor changes are optionally available.
 Reference ☐ G030

Specification	ons				
Part Number			HPS60-20X-M5	HPS80-50X-M5	HPS120-60X-M5
	Travel [mm]		20	50	60
	Table Size [mm]	60×60	80×80	120×120
Mechanical	Feed Screw	V	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead
Specifications	Positioning	Slide	Ball guide	Ball guide	Ball guide
	Stage Mate	erial	Aluminum	Aluminum	Aluminum
	Finish		Black anodized	Black anodized	Black anodized
	Weight [kg]		0.6	1	1.5
	D 1.11	(Full) [µm/pulse]	2	2	2
	Resolution	(Half) [µm/pulse]	1	1	1
	MAX Speed [mm/sec]		10	10	10
	Positioning Accuracy [µm]		15	25	25
	Positional Repeatability [µm]		±1	±2	±2
	Load Capacity [N]		49 (5kgf)	73.5 (7.5kgf)	98 (10kgf)
Accuracy		Pitch ["/N·cm]	0.4	0.5	0.5
Specifications	Moment Stiffness	Yaw ["/N·cm]	0.4	0.5	0.5
	Juliness	Roll ["/N·cm]	0.3	0.2	0.2
	Lost Motion [µm]		1	2	2
	Backlash [µm]		1	2	2
	Parallelism	[µm]	30	40	50
	Running Parallelism [µm]		10	10	10
	Pitch ["] / Yaw ["]		25/25	30/25	30/25
	Sensor Pari	t Number	Micro p	hoto sensor: GP1S097HCZ(Sharp Cor	rporation)
2	Limit Sensor		Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Sensor	Origin Sens	sor	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)
	Proximity O	rigin Sensor	None	None	None

Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number PK523HPB-C12 (_28mm)				
	Step Angle 0.72°				
	Power Voltage	DC5 - 24V ±10%			
	Current Consumption	60mA or lower (20mA or lower per sensor)			
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA When load current is 16mA, the residual voltage is under 0.4V When load current is 50mA, the residual voltage is under 0.7V			
	Output Logic	In the case of light shielded ,output transistor OFF (No conduction): Limit sensor In the case of light shielded ,output transistor ON (Conduction): Origin sensor			

Compatible Driver / Controller				
Compatible Driver		SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL		
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04		

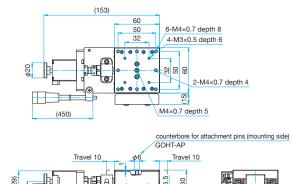


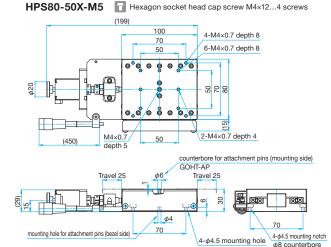


depth 4.5

Outline Drawing

mounting hole for attachment pins (bezel side)



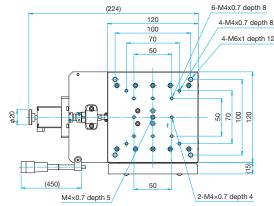


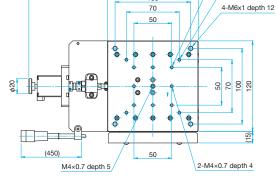
(+) φ4

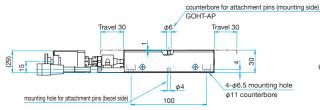
50

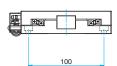
4-φ4.5 mounting hole

φ8 counterbore

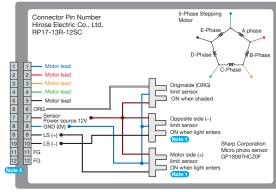








■Connection Diagram



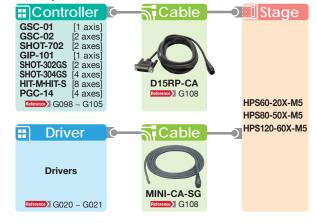
Note 1 The motor side limit sensor is the + direction limit sensor.

Motorized stages are not fitted with proximity origin sensors.

Compatible cable connector:

Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

■Compatible Controllers / Drivers and Cables



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□40mm

⊒60mm

⊒80mm

85mm

□100mm

□120mm



High Performance Motorized Stage Options | HPS Option

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Vacuum **Options**

□40mm

□60mm

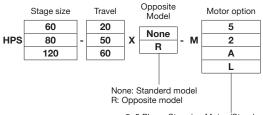
□80mm □85mm

□100mm □120mm

Others

Specification Method of Option Code

■Option Code



5: 5 Phase Stepping Motor (Standerd model) 2: 2 Phase Motor with Driver A: a-step Motor with Driver

L: No motor

Guide

- ▶ Please contact us when assembled into XYZ axis or use in reversion on the ceiling or vertical direction.
- ▶ Replacement with electromagnetic brakes or grease change is also available. Contact our International Sales Division for more information.

■Example of Code Specification

HPS60-20X -M

■Features of Options

	•
2 Phase Motor with Driver	It can reduce the total cost because a driver is equipped. On the other hand, precision is inferior to 5 phase motors.
α Stepping Motor with Driver	Can be replaced with an α stepping motor with driver which can move fast. The motor also has built-in encoder.
No Motor	No Motor Provide a stage without motor because the customer mounts own motor. Note that mounting and adjustment of a motor requires specialized skills.



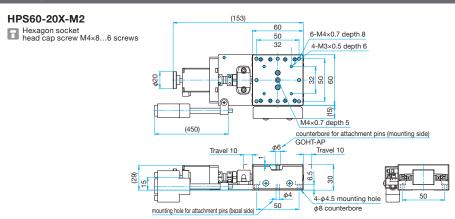
Specification	Specifications (ex. HPS60-20X)					
Part Number			HPS60-20X-M2	HPS60-20X-MA	HPS60-20X-ML	
	Travel [mm]		20	20	20	
	Table Size [mm]	60×60	60×60	60×60	
Mechanical	Feed Screw	ı	Ball screw diameter ϕ 6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter ϕ 6mm, 1mm lead	
Specifications	Positioning	Slide	Ball guide	Ball guide	Ball guide	
	Stage Mate	rial	Aluminum	Aluminum	Aluminum	
	Finish		Black anodized	Black anodized	Black anodized	
	Weight [kg]		0.6	1	0.6	
	Resolution	(Full) [µm/pulse]	5	2 (500P/R)	_	
	Resolution	(Half) [µm/pulse]	2.5	1 (1000P/R)	-	
	MAX Speed [mm/sec]		20	40	_	
	Positioning Accuracy [µm]		15	15	-	
	Positional Repeatability [µm]		±2	±0.5	-	
	Load Capacity [N]		49 (5kgf)	49 (5kgf)	49 (5kgf)	
Accuracy		Pitch ["/N·cm]	0.4	0.4	0.4	
Specifications	Moment Stiffness	Yaw ["/N·cm]	0.4	0.4	0.4	
	Ottimicss	Roll ["/N·cm]	0.3	0.3	0.3	
	Lost Motion [µm]		1	1	-	
	Backlash [µ	im]	1	1	1	
	Parallelism [µm]		30	30	30	
	Running Parallelism [µm]		10	10	10	
	Pitch ["] / Y	aw ["]	25/25	25/25	25-25	
	Sensor Part Number		Micro photo sensor: GP1S097HCZ (Sharp Corporation)	Micro photo sensor: GP1S097HCZ (Sharp Corporation)	Micro photo sensor: GP1S097HCZ (Sharp Corporation)	
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
	Origin Sens	sor	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)	
	Proximity C	rigin Sensor	None	None	None	

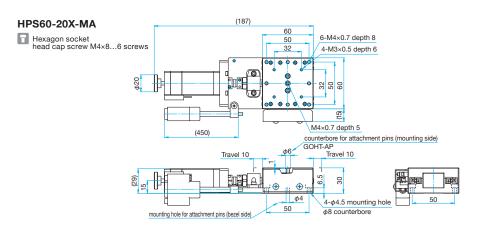
Motor / S	Motor / Sensor Specifications					
	Туре	2-phase stepping motor (Oriental Motor Co., Ltd.)	a STEP motor (Oriental Motor Co., Ltd.)	(No motor)		
Motor	Motor Part Number	PKP223D15B (□28mm)	ARM26SBK (□28mm)	_		
	Step Angle	1.8°	0.72°(500P/R)	_		
Driver	Part Number	A8576-0415Y	ARD-K	_		
Dilvei	Power input	DC24V±10% 1A	DC24V ±10% 0.9A	_		
	Power Voltage	DC5 - 24V ±10%				
	Current Consumption	60mA or lower (20mA or lower per sensor) A8576-0415Y				
Sensor	Control Output	DC24V±10% 1A				
	Output Logic	When load current is 16mA, the residual	NPN open collector output DC30V or lower, 50mA When load current is 16mA, the residual voltage is under 0.4V When load current is 50mA, the residual voltage is under 0.7V In the case of light shielded ,output transistor OFF (No conduction): Limit sensor			

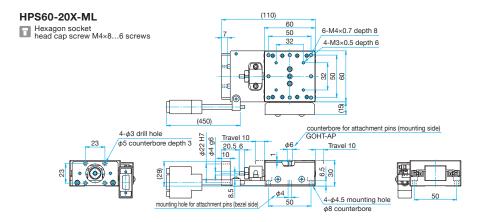




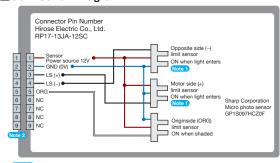
Outline Drawing







■Connection Diagram



The motor side limit sensor is the (+) forward direction limit sensor.
There is no origin proximity sensor for this motorized stage.

Note 2 Compatible cable connector: Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

■(Reference) Motor Comparison Table

Section	5 Phase Stepping Motor	2 Phase Stepping Motor	αSTEP Motor
Positioning Accuracy	0	0	0
Minute Feed Accuracy	0	0	0
Speed Stability	0	Δ	0
Heat Generation (Continuous Operation)	0	Δ	0
Max. Speed	0	0	0
Rising Responsiveness	0	0	0

^{*}Rough guide for when the motors are mounted on our motorized stage. (\bigcirc : goodness \bigcirc : standard \triangle : inferior)

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Options

□40mm

□60mm

□80mm □85mm

□100mm

□120mm

OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS20-(X) Stage size -85mm | RoHS

tion to achieve high stiffness.





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□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Others

• U-shaped rail offers light weight, and minimized deflec-

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Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

► Grease change is optionally available. Reference G110

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.



Part Number			OSMS20-35(X)	OSMS20-85(X)
Part Number (-M6)			OSMS20-35(X)-M6	OSMS20-85(X)-M6
Part Number (-INCH)			OSMS20-35(X)-INCH	OSMS20-85(X)-INCH
	Travel [mm]		35	85
	Table Size [mm]	85×85	85×85
Mechanical	Feed Screw	ı	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead
Specifications	Positioning	Slide	Outer rail structure	Outer rail structure
	Stage Mate	rial	Aluminum	Aluminum
	Finish		Black anodized	Black anodized
	Weight [kg]		1.1	1.3
	Resolution	(Full) [µm/pulse]	2	2
		(Half) [µm/pulse]	1	1
	MAX Speed [mm/sec]		25	25
	Positioning Accuracy [µm]		5	10
	Positional Repeatability [µm]		3	3
	Load Capacity [N]		78.4 (8.0kgf)	78.4 (8.0kgf)
ccuracy		Pitch ["/N·cm]	0.4	0.4
Specifications	Moment Stiffness	Yaw ["/N·cm]	0.25	0.25
		Roll ["/N·cm]	0.35	0.35
	Lost Motion	n [µm]	3	3
	Backlash [µ	ım]	3	3
	Parallelism	[µm]	30	30
	Running Pa	rallelism [µm]	10	10
	Pitch ["] / Y	aw ["]	30/20	30/20
	Sensor Part	t Number	Micro photo sensor: GP1S0	92HCPIF(Sharp Corporation)
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE
Serisor	Origin Sens	sor	Equipped	Equipped
	Proximity O	rigin Sensor	None	Equipped

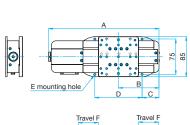
Motor / S	Motor / Sensor Specifications					
Motor	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)				
	Motor Part Number	TS3664N4E10 (□24mm)				
	Step Angle	0.72°				
	Power Voltage	DC5 - 24V±10%				
Sensor	Current Consumption	60mA or lower (20mA or lower per sensor)				
Serisor	Control Output	NPN open collector output DC30V or lower, 50mA or lower				
	Output Logic	When shaded: Output transistor OFF (no conduction)				

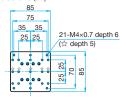
Compatible Driver / Controller						
Control System	Compatible Driver	SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL				
	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04				



Outline Drawing

OSMS20-**(X) Hexagon socket head cap screw M4×8...8 screws (35) Hexagon socket head cap screw M4×8...10 screws (85)

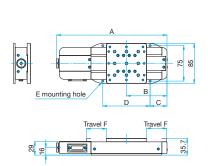


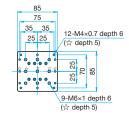


	Travel F	Travel F
1 p	3	35.7

Part Number	Α	В	С	D	Е	F
OSMS20-35(X)	183.5	60.8	35.8	75 (25×3)	8-φ4.5	17.5
OSMS20-85(X)	233.5	85.8	35.8	100 (25×4)	10-φ4.5	42.5

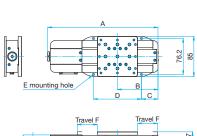
OSMS20-**(X)-M6 Hexagon socket head cap screw M4×8...8 screws (35) Hexagon socket head cap screw M4×8...10 screws (85)

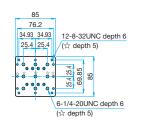




Part Number	Α	В	С	D	Е	F
OSMS20-35(X)-M6	183.5	60.8	35.8	75 (25×3)	8-φ4.5	17.5
OSMS20-85(X)-M6	233.5	85.8	35.8	100 (25×4)	10-φ4.5	42.5

OSMS20-**(X)-INCH Hexagon socket head cap screw 8 / 32UNC×5 / 16...8 screws (35) Hexagon socket head cap screw 8 / 32UNC×5 / 16...10 screws (85)

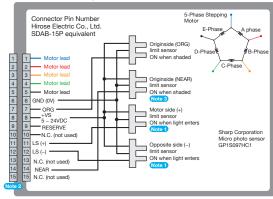






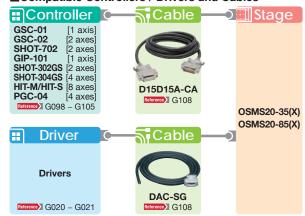
Part Number	Α	В	С	D	Е	F
OSMS20-35(X)-INCH	183.5	60.8	34.5	76.2(25.4×3)	8-φ4.5	17.5
OSMS20-85(X)-INCH	233.5	85.8	35	101.6(25.4×4)	10-φ4.5	42.5

■Connection Diagram



- te 1) The motor side limit sensor is the + direction limit sensor. Compatible cable connector: DDK Ltd. 17JE-13150
- 3 OSMS20-35 is not fitted with proximity origin sensor. 13 and 14P are short-circuited

■Compatible Controllers / Drivers and Cables



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Options

□40mm

□60mm

□80mm

⊒85mm

□100mm □120mm

OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS20-(XY) Stage size

85mm

from which high stiffness and high precision are required.





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Options

□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Others

• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

Guide

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

► Grease change is optionally available. Reference G110

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.



Specification	ons					
Part Number			OSMS20-35(XY)	OSMS20-85(XY)		
Part Number (-N	16)		OSMS20-35(XY)-M6	OSMS20-85(XY)-M6		
Part Number (-II	NCH)		OSMS20-35(XY)-INCH	35(XY)-INCH OSMS20-85(XY)-INCH		
	Travel [mm]		35	85		
	Table Size [mm]	85×85	85×85		
	Feed Screw	1	Ball screw diameter ϕ 6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead		
Mechanical Specifications	Positioning	Slide	Outer rail structure	Outer rail structure		
орестешного	Stage Material		Aluminum	Aluminum		
	Finish		Black anodized	Black anodized		
	Weight [kg]		2.2	2.6		
	Resolution	(Full) [µm/pulse]	2	2		
	Resolution	(Half) [µm/pulse]	1	1		
Accuracy	MAX Speed	[mm/sec]	25	25		
Specifications	Load Capa	city [N]	68.6(7.0kgf)	68.6(7.0kgf)		
	Backlash [µ	m]	3	3		
	Orthogonal	ity of Motion [µm]	5	5		
	Sensor Par	Number	Micro photo sensor: GP1S092HCPIF(Sharp Corporation)			
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)		
Sensor	Origin Sens	or	Equipped	Equipped		
	Proximity C	rigin Sensor	None	Equipped		

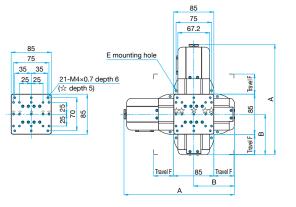
Motor / S	Motor / Sensor Specifications						
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)					
Motor	Motor Part Number	TS3664N4E10 (□24mm)					
	Step Angle	0.72°					
	Power Voltage	DC5 - 24V±10%					
Concor	Current Consumption	60mA or lower (20mA or lower per sensor)					
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower					
	Output Logic	When shaded: Output transistor OFF (no conduction)					

(Reference) Precision Specifications of Single Axis Stage							
Part Number			OSMS20-35(X)	OSMS20-85(X)			
	Positioning	Accuracy [µm]	5	7			
	Positional Repeatability [µm]		3	3			
	Moment Stiffness	Pitch ["/N·cm]	0.4	0.4			
Accuracy		Yaw ["/N·cm]	0.25	0.25			
Specifications		Roll ["/N·cm]	0.35	0.35			
	Lost Motion [µm]		3	3			
_	Parallelism	[µm]	30	30			
	Running Pa	arallelism [µm]	10	10			

Compatible Driver / Controller					
Control System	Compatible Driver	SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL			
	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04			



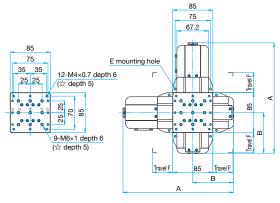
Outline Drawing

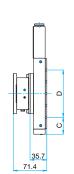


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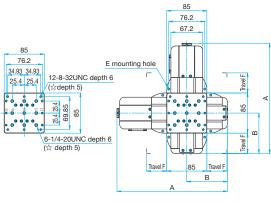
Part Number	Α	В	С	D	Е	F
OSMS20-35(XY)	183.5	60.8	35.8	75 (25×3)	8-φ4.5	17.5
OSMS20-85(XY)	233.5	85.8	35.8	100 (25×4)	10-φ4.5	42.5

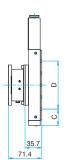
OSMS20-**(XY)-M6 Hexagon socket head cap screw M3×6...4 screws





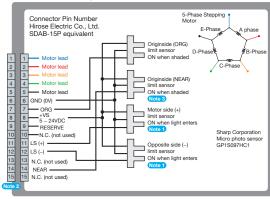
Part Number	Α	В	С	D	Е	F
OSMS20-35(XY)-M6	183.5	60.8	35.8	75 (25×3)	8-φ4.5	17.5
OSMS20-85(XY)-M6	233.5	85.8	35.8	100 (25×4)	10-φ4.5	42.5





Part Number	Α	В	С	D	Е	F
OSMS20-35(XY)-INCH	183.5	60.8	34.5	76.2(25.4×3)	8-φ4.5	17.5
OSMS20-85(XY)-INCH	233.5	85.8	35	101.6(25.4×4)	10-φ4.5	42.5

■Connection Diagram

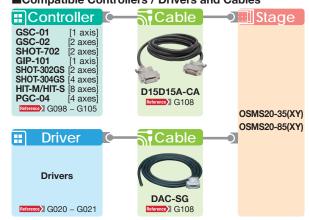


- Note 1) The motor side limit sensor is the + direction limit sensor.
- Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

 Note 3 OSMS20-35 is not fitted with proximity origin sensor.

 13 and 14P are short-circuited

■Compatible Controllers / Drivers and Cables



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□40mm

⊒85mm

□100mm

□120mm

OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS20-(Z) Stage size RoHS



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□40mm □60mm

□80mm □85mm

□100mm

□120mm

Others

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools from which high stiffness and high precision are required.



• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

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▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

Grease change is optionally available.

Reference G110

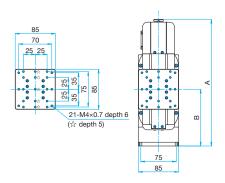
Part Number			OSMS20-35(Z)	OSMS20-85(Z)
Part Number (-M6)			OSMS20-35(Z)-M6	OSMS20-85(Z))-M6
Part Number (-I	NCH)		OSMS20-35(Z)-INCH	OSMS20-85(Z)-INCH
	Travel [mm]		35	85
	Table Size [mm]		85×85	85×85
	Feed Screw	ı	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead
Mechanical Specifications	Positioning	Slide	Outer rail structure	Outer rail structure
Орестоанота	Stage Mate	rial	Aluminum	Aluminum
	Finish		Black anodized	Black anodized
	Weight [kg]		2.3	2.5
	Resolution	(Full) [µm/pulse]	2	2
	Resolution	(Half) [µm/pulse]	1	1
	MAX Speed [mm/sec]		5	5
	Positioning Accuracy [µm]		10	20
	Positional Repeatability [µm]		3	5
	Load Capacity [N]		29.4 (3.0kgf)*1	29.4 (3.0kgf)*1
Accuracy Specifications		Pitch ["/N·cm]	0.8	0.8
opcomodition:0	Moment Stiffness	Yaw ["/N·cm]	0.5	0.5
		Roll ["/N·cm]	0.7	0.7
	Lost Motion [µm]		3	3
	Backlash [µm]		3	3
	Orthogonality of Motion [µm]		25	30
	Pitch ["] / Yaw ["]		45/20 45/20	
	Sensor Par	t Number	Micro photo sensor: GP1S09	92HCPIF (Sharp Corporation)
Canaar	Limit Sensor		Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Sensor	Origin Sensor		Equipped	Equipped
	Proximity C	rigin Sensor	None	Equipped

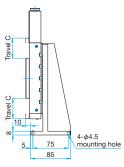
¹ If you use the controller of ②.

Motor / Sensor Specifications						
Туре		5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)				
Motor	Motor Part Number	TS3664N4E10(□24mm)				
	Step Angle	0.72°				
Sensor	Power Voltage	DC5 - 24V±10%				
	Current Consumption	60mA or lower (20mA or lower per sensor)				
	Control Output	NPN open collector output DC30V or lower, 50mA or lower				
Output Logic		When shaded: Output transistor OFF (no conduction)				

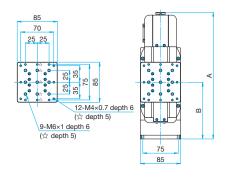
Compatible Driver / Controller					
Control System	Compatible Driver	①: SG-5M, SG-5MA ②: SG-55M, SG-55MA, SG-514MSC, SG-5151, KR-525M, MC-7514PCL			
	Compatible Controller	①: GSC-01, GSC-02 ②: SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04			

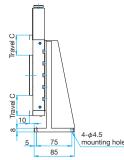






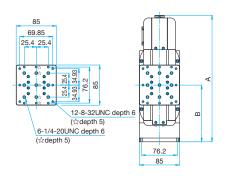
Part Number	А	В	С
OSMS20-35(Z)	217.7	95	17.5
OSMS20-85(Z)	267.7	120	42.5

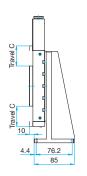




	Part Number	А	В	С
ole	OSMS20-35(Z)-M6	217.7	95	17.5
ле	OSMS20-85(Z)-M6	267.7	120	42.5

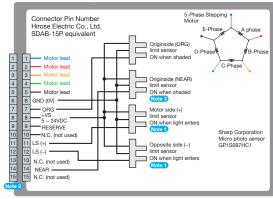
OSMS20-**(Z)-INCH Hexagon socket head cap screw M4×8...4 screws





Part Number	А	В	С
OSMS20-35(Z)-INCH	216.4	94.6	17.5
OSMS20-85(Z)-INCH	267.7	120	42.5

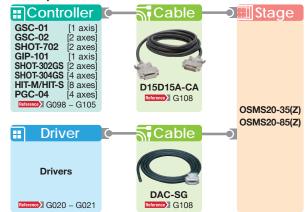
■Connection Diagram



- te 1) The motor side limit sensor is the + direction limit sensor.
- 2 Compatible cable connector: DDK Ltd. 17JE-13150

3 OSMS20-35 is not fitted with proximity origin sensor. 13 and 14P are short-circuited

■Compatible Controllers / Drivers and Cables



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Vacuum **Options**

□40mm

□60mm

□80mm

⊒85mm

□100mm

□120mm



Precision Motorized Stages with Built-in Compact Scale | OSMS(CS)20-(X) Stage size RoHS





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Vacuum

Options

□40mm

□60mm □80mm

□85mm

□100mm

□120mm **Others**

The dedicated stage controllers (SHOT-302GS/304GS, HIT series) offer a full closed loop system with high precision and high reliability.



- The stages enable high stiffness and high precision positioning because their structure, which is strong against momentum and combined load, is less susceptible to pitching, rolling and yawing.
- A compact scale is built in, but the installation space is the same as that of other OSMS series when the travel is the same.

Guide

- ▶ Contact our International Sales Division for replacement of motors or for stabilizing (drop-preventing) mechanism. Reference G017, G111 (Motorized Stage System Question Sheet)
- ► Grease change is optionally available. Reference G110
- ▶ Contact our International Sales Division to use the stage as an XY axis or a Z axis stage.

Specification	ons			
Part Number			OSMS(CS)20-35(X)	OSMS(CS)20-85(X)
Part Number (-M6)			OSMS(CS)20-35(X)-M6	OSMS(CS)20-85(X)-M6
Part Number (-I	Jumber (-INCH) OSMS(CS)20-35(X)-INCH OSMS(CS)20-85(X)-II			
	Travel [mm]		35	85
	Table Size [m	m]	85×85	85×85
	Feed Screw		Ball screw diameter \$\phi\$6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead
Mechanical Specifications	Positioning S	lide	Outer rail structure	Outer rail structure
opcomodiiono	Stage Materia	al	Aluminum	Aluminum
	Finish		Black anodized	Black anodized
	Weight [kg]		1.4	1.6
	Resolution	(Full) [µm/pulse]	2	2
	Resolution	(Half) [µm/pulse]	1	1
	MAX Speed [mm/sec]		25	25
	Positioning Accuracy [µm]		5	10
	Positional Repeatability [µm]		2	2
	Load Capacity [N]		78.4 (8.0kgf)	78.4 (8.0kgf)
Accuracy		Pitch ["/N·cm]	0.4	0.4
Specifications	Moment Stiffness	Yaw ["/N·cm]	0.25	0.25
		Roll ["/N·cm]	0.35	0.35
	Lost Motion [μm]	3	3
	Backlash [µm]	3	3
	Parallelism [µ	m]	30	30
	Running Para	llelism [µm]	10	10
	Pitch ["] / Yav	v [″]	30/20	30/20
	Sensor Part N	lumber	Micro photo sensor: GP1S09	2HCPIF (Sharp Corporation)
Sensor	Limit Sensor		Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
3611901	Origin Sensor		Equipped	Equipped
	Proximity Orig	gin Sensor	None	Equipped
Scale head	Resolution [µ	m]	0.5	0.5

Motor / Se	ensor Specifications	
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)
Motor	Motor Part Number	TS3664N4E10 (□24mm)
	Step Angle	0.72°
	Power Voltage	DC5 - 24V±10%
Sensor	Current Consumption	60mA or lower (20mA or lower per sensor)
Serisor	Control Output	NPN open collector output DC30V or lower, 50mA or lower
	Output Logic	When shaded: Output transistor OFF (no conduction)
Scale head	Power Voltage / Current Consumption	DC5V±5% / 50mA

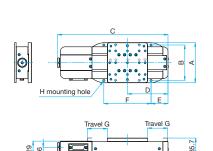
Compatible Cable				
Cable	Driver Cable	D15D15A-CA		
	Scale Cable	GSEF-CA-3		

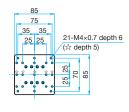
Compatible Driver / Controller				
Control Custom	Compatible Driver	_		
Control System	Compatible Controller	SHOT-302GS, SHOT-304GS, HIT-M·HIT-S		





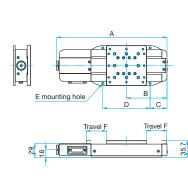
OSMS(CS)20-**(X) Hexagon socket head cap screw M3×6...4 screws

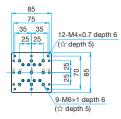




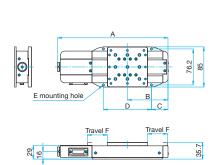
Part Number	А	В	С	D	Е	F
OSMS(CS)20-35(X)	183.5	60.8	35.8	75 (25×3)	8-φ4.5	17.5
OSMS(CS)20-85(X)	233.5	85.8	35.8	100 (25×4)	10-φ4.5	42.5

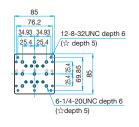
OSMS(CS)20-**(X)-M6 Hexagon socket head cap screw M3×6...4 screws





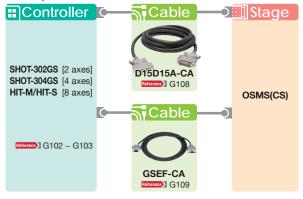
Part Number	Α	В	С	D	Е	F
OSMS(CS)20-35(X)-M6	183.5	60.8	35.8	75 (25×3)	8-φ4.5	17.5
OSMS(CS)20-85(X)-M6	233.5	85.8	35.8	100 (25×4)	10-φ4.5	42.5





Part Number	Α	В	С	D	Е	F
OSMS(CS)20-35(X)-INCH	183.5	60.8	34.5	76.2 (25.4×3)	8-φ4.5	17.5
OSMS(CS)20-85(X)-INCH	233.5	85.8	35	101.6 (25.4×4)	10-φ4.5	42.5

■Compatible Controllers / Drivers and Cables



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Vacuum **Options**

□40mm

□60mm

□80mm

□85mm

□100mm

□120mm Others



OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS26-(X) Stage size 100mm





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□40mm

□60mm

□80mm □85mm

□100mm

□120mm

Others

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools from which high stiffness and high precision are required.



• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

Guide

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

► Grease change is optionally available. Reference G110

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.

Specification	, no		0011000 5005	0011000 10055	0011000 00057	0011000 00177	
Part Number			OSMS26-50(X)	OSMS26-100(X)	OSMS26-200(X)	OSMS26-300(X)	
Part Number (-N	16)		OSMS26-50(X)-M6	OSMS26-100(X)-M6	OSMS26-200(X)-M6	OSMS26-300(X)-M6	
Part Number (-II	NCH)		OSMS26-50(X)-INCH	OSMS26-100(X)-INCH	OSMS26-200(X)-INCH	OSMS26-300(X)-INCH	
	Travel [mm]		50	100	200	300	
	Table Size [(M6, INCH)	mm]	100×100 (120×120)	100×100 (120×120)	100×100 (120×120)	100×100 (120×120)	
Mechanical	Feed Screw	ı	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mi 2mm lead	
Specifications	Positioning	Slide	Outer rail structure	Outer rail structure	Outer rail structure	Outer rail structure	
	Stage Mate	rial	Aluminum	Aluminum	Aluminum	Aluminum	
	Finish		Black anodized	Black anodized	Black anodized	Black anodized	
	Weight [kg]		2.2	2.7	3.8	4.0	
	Resolution	(Full) [μm/pulse]		4	4	4	4
		(Half) [µm/pulse]	2	2	2	2	
	MAX Speed [mm/sec]		40	40	40	40	
	Positioning Accuracy [µm]		5	10 15		20	
	Positional Repeatability [µm]		3	3	6	6	
	Load Capacity [N]		117 (12.0kgf)	117 (12.0kgf)	117 (12.0kgf)	117 (12.0kgf)	
Accuracy		Pitch ["/N·cm]	0.23	0.23	0.23	0.23	
Specifications	Moment Stiffness	Yaw ["/N·cm]	0.12	0.12	0.12	0.12	
	01	Roll ["/N·cm]	0.2	0.2	0.2	0.2	
	Lost Motion	n [µm]	3	3	5	5	
	Backlash [µ	im]	3	3	3	3	
	Parallelism	[µm]	50	50	50	50	
	Running Pa	rallelism [µm]	10	10	10	20	
	Pitch ["] / Y	aw ["]	25/20	25/20	30/25	30/25	
	Sensor Part	t Number		Micro photo sensor: GP1S09	92HCPIF (Sharp Corporation))	
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
	Origin Sens	sor	Equipped	Equipped	Equipped	Equipped	
	Proximity O	rigin Sensor	Equipped	Equipped	Equipped	Equipped	

Motor / Se	nsor Specifications	
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)
Motor	Motor Part Number	PK525HPB-C4(□28mm)
	Step Angle	0.72°
	Power Voltage	DC5 - 24V±10%
Sensor	Current Consumption	80mA or lower (20mA or lower per sensor)
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower
	Output Logic	When shaded: Output transistor OFF (no conduction)

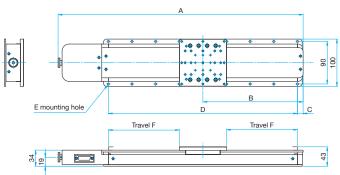
Compatible Driver / Controller						
Control Custom	Compatible Driver	SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL				
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04				

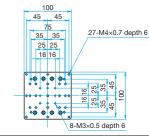


CAD

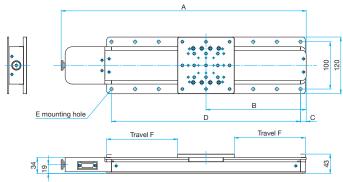
Outline Drawing

OSMS26-**(X) THexagon socket head cap screw M4×8...6 screws



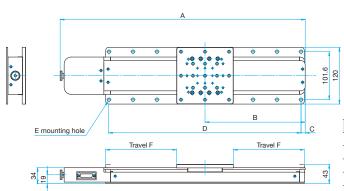


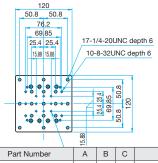
	Part Number	Α	В	С	D	Е	F
(OSMS26-50(X)	268.5	87	12	150 (25, 50×2, 25)	10-φ4.5	25
-	DSMS26-100(X)	318.5	112	12	200 (50×4)	10-φ4.5	50
(OSMS26-200(X)	418.5	162	12	300 (50×6)	14-φ4.5	100
(OSMS26-300(X)	518.5	212	12	400 (50×8)	18-φ4.5	150



_	12	20		
	50	50		
	7	5	П	
	35 25	35 25		17-M6×1 depth 6
	16	16	Ш	10-M4×0.7 depth 6
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		8		6 16 5 25 35 50 120
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			١ (3-M3×0.5 depth 6

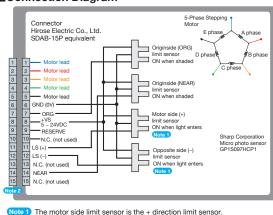
Part Number	Α	В	С	D	Е	F
OSMS26-50(X)-M6	268.5	87	12	150 (25, 50×2, 25)	10-φ4.5	25
OSMS26-100(X)-M6	318.5	112	12	200 (50×4)	10-φ4.5	50
OSMS26-200(X)-M6	418.5	162	12	300 (50×6)	14-φ4.5	100
OSMS26-300(X)-M6	518.5	212	12	400(50×8)	18-φ4.5	150





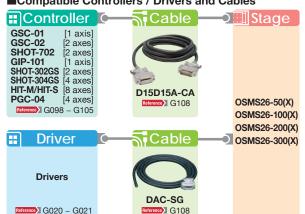
Part Number	А	В	C	D	E	F
OSMS26-50(X)-INCH	268.5	87	10.8	152.4 (25.4, 50.8×2, 25.4)	10-φ7	25
OSMS26-100(X)-INCH	318.5	112	10.4	203.2 (50.8×4)	10-φ7	50
OSMS26-200(X)-INCH	418.5	162	9.6	304.8 (50.8×6)	10-φ7	100
OSMS26-300(X)-INCH	518.5	212	8.8	406.4 (50.8×8)	10-φ7	150

■Connection Diagram



2 Compatible cable connector: DDK Ltd. 17JE-13150

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Vacuum **Options**

□40mm

□60mm

□80mm

□85mm

□100mm ⊒120mm



OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor OSMS26-(XY) Stage size 100mm RoHS



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□40mm

□60mm

□80mm □85mm

□100mm

□120mm

Others

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools from which high stiffness and high precision are required.



• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

Guide

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

- ► Grease change is optionally available. Reference G110
- ▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.

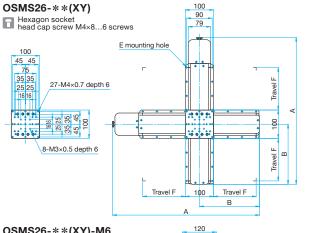
Specification	ons					
Part Number			OSMS26-50(XY)	OSMS26-100(XY)	OSMS26-200(XY)	OSMS26-300(XY)
Part Number (-M	16)		OSMS26-50(XY)-M6	OSMS26-100(XY)-M6	OSMS26-200(XY)-M6	OSMS26-300(XY)-M6
Part Number (-INCH)		OSMS26-50(XY)-INCH	OSMS26-100(XY)-INCH	OSMS26-200(XY)-INCH	OSMS26-300(XY)-INCH	
	Travel [mm]		50	100	200	300
	Table Size [(M6, INCH)	mm]	100×100 (120×120)	100×100 100×100 (120×120) (120×120)		100×100 (120×120)
Mechanical	Feed Screw	ı	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead
Specifications	Positioning Slide		Outer rail structure	Outer rail structure	Outer rail structure	Outer rail structure
	Stage Material		Aluminum	Aluminum	Aluminum	Aluminum
	Finish		Black anodized	Black anodized	Black anodized	Black anodized
	Weight [kg]		4.4	5.4	7.6	8.0
	Resolution	(Full) [µm/pulse]	4	4	4	4
	Resolution	(Half) [µm/pulse]	2	2	2	2
Accuracy	MAX Speed [mm/sec]		40	40	40	40
Specifications	Load Capac	city [N]	98 (10.0kgf)	98 (10.0kgf)	98 (10.0kgf)	98 (10.0kgf)
	Backlash [µ	ım]	3	3	3	3
	Orthogonal	ity of Motion [µm]	5	5	10	5
	Sensor Part	t Number		Micro photo sensor: GP1S09	2HCPIF (Sharp Corporation)	
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sens	sor	Equipped	Equipped	Equipped	Equipped
	Proximity O	rigin Sensor	Equipped	Equipped	Equipped	Equipped

Motor / S	Motor / Sensor Specifications								
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)							
Motor	Motor Part Number	PK525HPB-C4 (□28mm)							
	Step Angle	0.72°							
	Power Voltage	DC5 - 24V±10%							
Sensor	Current Consumption	80mA or lower (20mA or lower per sensor)							
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower							
	Output Logic	When shaded: Output transistor OFF (no conduction)							

(Reference) Precision Specifications of Single Axis Stage									
Part Number			OSMS26-50(X)	OSMS26-100(X)	OSMS26-200(X)	OSMS26-300(X)			
	Positioning Accuracy [µm]		5	10	15	15			
	Positional Repeatability [µm]		3	3	6	6			
	Moment Stiffness	Pitch ["/N·cm]	0.23	0.23	0.23	0.23			
Accuracy		Yaw ["/N·cm]	0.12	0.12	0.12	0.12			
Specifications		Roll ["/N·cm]	0.2	0.2	0.2	0.2			
	Lost Motion [µm]		3	3	5	5			
	Parallelism	[µm]	50	50	50	50			
	Running Pa	arallelism [µm]	10	10	10	10			

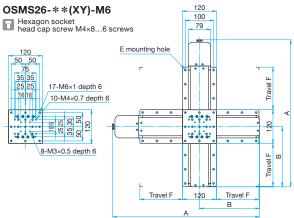
Compatible Driver / Controller						
Control Custom	Compatible Driver	SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL				
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04				

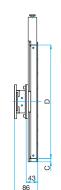




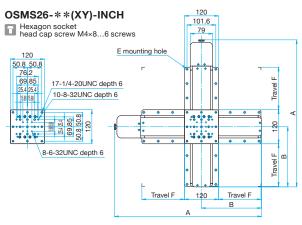
c		0
	43 86	0 0 0

Part Number	Α	В	С	D	Е	F
OSMS26-50(XY)	268.5	87	12	150 (25, 50×2, 25)	10-φ7	25
OSMS26-100(XY)	318.5	112	12	200 (50×4)	10-φ7	50
OSMS26-200(XY)	418.5	162	12	300 (50×6)	10-φ7	100
OSMS26-300(XY)	518.5	212	12	400 (50×8)	10-φ7	150





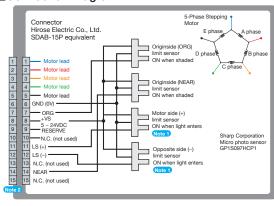
Part Number	Α	В	С	D	Е	F
OSMS26-50(XY)-M6	268.5	87	12	150 (25, 50×2, 25)	10-φ7	25
OSMS26-100(XY)-M6	318.5	112	12	200 (50×4)	10-φ7	50
OSMS26-200(XY)-M6	418.5	162	12	300 (50×6)	10-φ7	100
OSMS26-300(XY)-M6	518.5	212	12	400 (50×8)	10-φ7	150





Part Number	Α	В	С	D	Е	F
OSMS26-50(XY)-INCH	268.5	87	10.8	152.4 (25.4, 50.8×2, 25.4)	10-φ7	25
OSMS26-100(XY)-INCH	318.5	112	10.4	203.2 (50.8×4)	10-φ7	50
OSMS26-200(XY)-INCH	418.5	162	9.6	304.8 (50.8×6)	10-φ7	100
OSMS26-300(XY)-INCH	518.5	212	8.8	406.4 (50.8×8)	10-φ7	150

■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor.

© 2 Compatible cable connector: DDK Ltd. 17JE-13150

■ Compa	tible Contro	ollers / Drivers an	d Cables
:: Cont	roller 🕒	Cable -	Stage
GSC-01 GSC-02	[1 axis]		

GSC-02 [2 axes] SHOT-702 [2 axes] GIP-101 [1 axis] SHOT-302GS [2 axes] SHOT-304GS [4 axes] HIT-M/HIT-S [8 axes] PGC-04 [4 axes] D15D15A-CA OSMS26-50(XY) **™** G108 MG098 - G105 OSMS26-100(XY) OSMS26-200(XY) Driver Cable OSMS26-300(XY) Drivers DAC-SG ■ G020 – G021 **™** G108

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Vacuum **Options**

□40mm

□60mm

□80mm

□85mm

⊒100mm ⊒120mm



OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS26-(Z) Stage size 100mm





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Theta Rotation Goniometer

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Options

□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Others

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools from which high stiffness and high precision are required.



• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

Guide

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

► Grease change is optionally available. Reference G110

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost

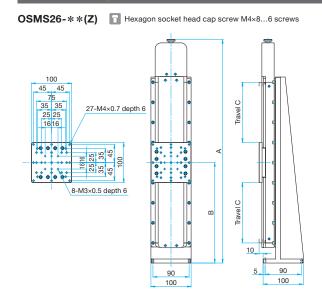
Specification	ons					
Part Number		OSMS26-50(Z)	OSMS26-100(Z)	OSMS26-200(Z)	OSMS26-300(Z)	
Part Number (-N	Л 6)		OSMS26-50(Z)-M6	OSMS26-100(Z)-M6	OSMS26-200(Z)-M6	OSMS26-300(Z)-M6
Part Number (-II	NCH)		OSMS26-50(Z)-INCH	OSMS26-100(Z)-INCH	OSMS26-200(Z)-INCH	OSMS26-300(Z)-INCH
	Travel [mm]		50	100	200	150
	Table Size [(M6, INCH)	mm]	100×100 (120×120)	100×100 (120×120)	100×100 (120×120)	100×100 (120×120)
Mechanical	Feed Screw	ı	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter ϕ 8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead
Specifications	Positioning	Slide	Outer rail structure	Outer rail structure	Outer rail structure	Outer rail structure
	Stage Mate	rial	Aluminum	Aluminum	Aluminum	Aluminum
	Finish		Black anodized	Black anodized	Black anodized	Black anodized
	Weight [kg]		4.4	4.9	7.2	7.4
	Resolution -	(Full) [µm/pulse]	4	4	4	4
		(Half) [µm/pulse]	2	2	2	2
	MAX Speed [mm/sec]		10	10	10	10
	Positioning	Accuracy [µm]	15	20	30	40
	Positional F	Repeatability [µm]	3	3	6	6
	Load Capacity [N]		39.2 (4.0kgf)	39.2 (4.0kgf)	39.2 (4.0kgf)	39.2 (4.0kgf)
Accuracy Specifications		Pitch ["/N·cm]	0.4	0.4	0.4	0.4
	Moment Stiffness	Yaw ["/N·cm]	0.15	0.15	0.15	0.15
		Roll ["/N·cm]	0.20	0.20	0.20	0.20
	Lost Motion	n [µm]	3	3	5	5
	Backlash [µ	ım]	3	3	3	3
	Orthogonal	ity of Motion [µm]	30	40	50	40
	Pitch ["] / Y	aw ["]	50/20	50/20	55/20	55/20
	Sensor Par	t Number		Micro photo sensor: GP1S09	2HCPIF (Sharp Corporation))
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sens	sor	Equipped	Equipped	Equipped	Equipped
	Proximity C	rigin Sensor	Equipped	Equipped	Equipped	Equipped

Motor / Sensor Specifications				
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)		
Motor	Motor Part Number	PK525HPB-C4 (□28mm)		
Step Angle	0.72°			
	Power Voltage	DC5 - 24V±10%		
Sensor	Current Consumption	80mA or lower (20mA or lower per sensor)		
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower		
	Output Logic	When shaded: Output transistor OFF (no conduction)		

Compatible Driver / Controller				
Control Custom	Compatible Driver	SG-5M, SG-55MA, SG-55MA, SG-514MSC, MC-7514PCL		
Control System Com	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04		



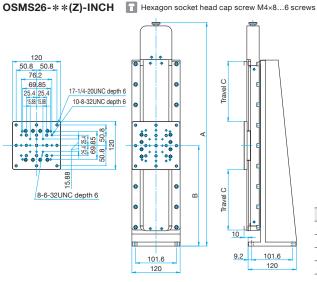




120 50 50 75 35 35 25 25 16 16 17-M6×1 depth 6 10-M4×0.7 depth 6 10-M4×0.7 depth 6 8-M3×0.5 depth 6	**************************************	Travel C

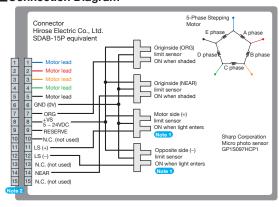
Part Number	A	В	С
OSMS26-50(Z)	306	125	25
OSMS26-100(Z)	356.5	150	50
OSMS26-200(Z)	463	200	100
OSMS26-300(Z)	556.5	250	150

Part Number	А	В	С
OSMS26-50(Z)-M6	306	125	25
OSMS26-100(Z)-M6	356.5	150	50
OSMS26-200(Z)-M6	463	200	100
OSMS26-300(Z)-M6	556.5	250	150



Part Number	Α	В	С
OSMS26-50(Z)-INCH	305.6	124.6	25
OSMS26-100(Z)-INCH	356.5	150	50
OSMS26-200(Z)-INCH	463	199.2	100
OSMS26-300(Z)-INCH	556.5	250	150

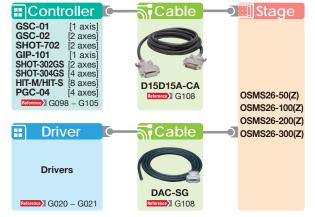
■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor.

© 2 Compatible cable connector: DDK Ltd. 17JE-13150

■Compatible Controllers / Drivers and Cables



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□40mm □60mm

□80mm

□85mm

⊒100mm

⊒120mm



Precision Motorized Stages with Built-in Compact Scale | OSMS(CS)26-(X) Stage size 100mm





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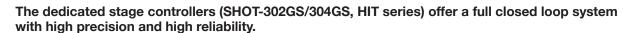
□40mm □60mm

□80mm □85mm

□100mm

□120mm

Others





- The stages enable high stiffness and high precision positioning because their structure, which is strong against momentum and combined load, is less susceptible to pitching, rolling and yawing.
- A compact scale is built in, but the installation space is the same as that of other OSMS series when the travel is the same.

Guide

- ▶ Contact our International Sales Division for replacement of motors or for stabilizing (drop-preventing) mechanism. Reference G017, G111 (Motorized Stage System Question Sheet)
- ▶ Grease change is optionally available. Reference G110
- ▶ Contact our International Sales Division to use the stage as an XY axis or a Z axis stage.

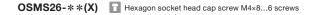
Specification	ons			
Part Number			OSMS(CS)26-100(X)	OSMS(CS)26-200(X)
Part Number (-N	M6)		OSMS(CS)26-100(X)-M6	OSMS(CS)26-200(X)-M6
Part Number (-I	NCH)		OSMS(CS)26-100(X)-INCH	OSMS(CS)26-200(X)-INCH
	Travel [mm]		100	200
	Table Size [m (M6, INCH)	nm]	100×100 (120×120)	100×100 (120×120)
Mechanical	Feed Screw		Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead
Specifications	Positioning S	Blide	Outer rail structure	Outer rail structure
	Stage Materi	al	Aluminum	Aluminum
	Finish		Black anodized	Black anodized
	Weight [kg]		3.2	4.3
	Resolution	(Full) [µm/pulse]	4	4
	nesolution	(Half) [µm/pulse]	2	2
	MAX Speed	[mm/sec]	40	40
	Positioning A	ccuracy [μm]	10	15
	Positional Re	epeatability [µm]	2	3
	Load Capaci	ty [N]	117 (12.0kgf)	117 (12.0kgf)
Accuracy		Pitch ["/N·cm]	0.23	0.23
Specifications	Moment Stiffness	Yaw ["/N·cm]	0.12	0.12
		Roll ["/N·cm]	0.2	0.2
	Lost Motion	[µm]	3	5
	Backlash [µn	1]	3	3
	Parallelism [µ	ım]	50	50
	Running Para	allelism [µm]	10	10
	Pitch ["] / Yaw ["]		25/20	30/25
	Sensor Part Number		Micro photo sensor: GP1S09	92HCPIF (Sharp Corporation)
Canaar	Limit Sensor		Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Sensor	Origin Senso	r	Equipped	Equipped
	Proximity Ori	gin Sensor	Equipped	Equipped
Scale head	Resolution [µ	ım]	0.5	0.5

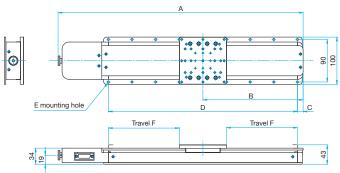
Motor / Ser	Motor / Sensor Specifications				
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number	PK525HPB-C4 (□28mm)			
	Step Angle	0.72°			
	Power Voltage	DC5 - 24V±10%			
Sensor	Current Consumption	80mA or lower (20mA or lower per sensor)			
	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF (no conduction)			
Scale head	Power Voltage / Current Consumption	DC5V±25% / 50mA			

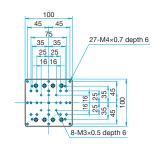
Compatible		
0-61-	Driver Cable	D15D15A-CA
Cable	Scale Cable	GSEF-CA-3

Compatible Driver / Controller					
Control Custom	Compatible Driver	_			
Control System	Compatible Controller	SHOT-302GS, SHOT-304GS, HIT-M·HIT-S			

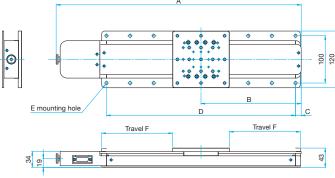


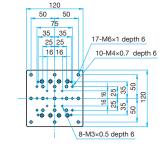




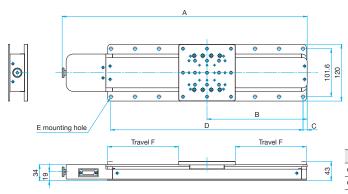


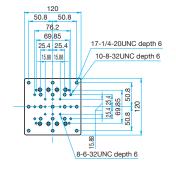
Part Number	Α	В	С	D	Е	F
OSMS(CS)26-100(X)	318.5	112	12	200 (50×4)	10-φ4.5	50
OSMS(CS)26-200(X)	418.5	162	12	300 (50×6)	14-φ4.5	100





Part Number	Α	В	С	D	E	F
OSMS(CS)26-100(X)-M6	318.5	112	12	200 (50×4)	10-φ4.5	50
OSMS(CS)26-200(X)-M6	418.5	162	12	300 (50×6)	14-φ4.5	100





Part Number	А	В	С	D	Е	F
OSMS(CS)26-100(X)-INCH	318.5	112	10.4	203.2 (50.8×4)	10-φ7	50
OSMS(CS)26-200(X)-INCH	418.5	162	9.6	304.8 (50.8×6)	10-φ7	100

■Compatible Controllers / Drivers and Cables



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□40mm

□40mm

□80mm

⊒85mm

□100mm

□120mm



OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS33-(X) Stage size 120mm





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□40mm

□60mm

□80mm □85mm

□100mm

□120mm

Others

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools from which high stiffness and high precision are required.



• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

Guide

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

► Grease change is optionally available. Reference G110

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.

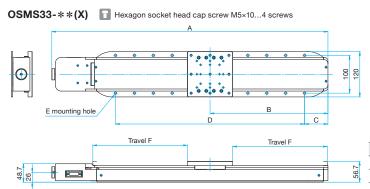
Part Number			OSMS33-300(X)	OSMS33-500(X)	
Part Number (-N	16)		OSMS33-300(X)-M6	OSMS33-500(X)-M6	
Part Number (-II	NCH)		OSMS33-300(X)-INCH	OSMS33-500(X)-INCH	
	Travel [mm]		300	500	
	Table Size [mm]	120×120	120×120	
	Feed Screw	1	Ball screw diameter φ10mm, 10mm lead	Ball screw diameter φ10mm, 10mm lead	
Mechanical Specifications	Positioning	Slide	Outer rail structure	Outer rail structure	
opcomodiono	Stage Mate	rial	Aluminum	Aluminum	
	Finish		Black anodized	Black anodized	
	Weight [kg]		7.0	8.6	
	Resolution	(Full) [µm/pulse]	20	20	
	riesolution	(Half) [µm/pulse]	10	10	
	MAX Speed [mm/sec]		120	120	
	Positioning Accuracy [µm]		25	25	
	Positional Repeatability [µm]		6	6	
	Load Capacity [N]		196 (20.0kgf)	196 (20.0kgf)	
Accuracy	Moment Stiffness	Pitch ["/N·cm]	0.12	0.12	
Specifications		Yaw ["/N·cm]	0.08	0.08	
		Roll ["/N·cm]	0.1	0.1	
	Lost Motion	ı [µm]	5	5	
	Backlash [µ	m]	3	3	
	Parallelism	[µm]	50	50	
	Running Pa	rallelism [µm]	15	25	
	Pitch ["] / Y	aw ["]	40/25	40/25	
	Sensor Parl	Number	Micro photo sensor: GP1S09	2HCPIF (Sharp Corporation)	
Sensor	Limit Senso	r	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
001/301	Origin Sens	or	Equipped	Equipped	
	Proximity O	rigin Sensor	Equipped	Equipped	

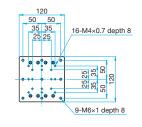
Motor / S	Motor / Sensor Specifications						
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)					
Motor	Motor Part Number	TS3667N43E967 (□42mm)					
	Step Angle	0.72°					
	Power Voltage	DC5 - 24V±10%					
Sensor	Current Consumption	80mA or lower (20mA or lower per sensor)					
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower					
	Output Logic	When shaded: Output transistor OFF (no conduction)					

Compatible Driver / Controller					
Control Custom	Compatible Driver	SG-55M, SG-55MA, SG-514MSC, MC-7514PCL			
Control System	Compatible Controller	SHOT-702, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04			

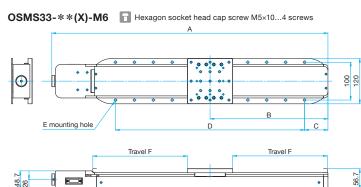


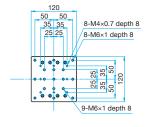




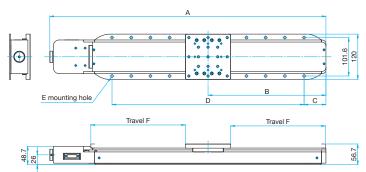


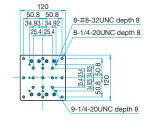
Part Number	Α	В	С	D	E	F
OSMS33-300(X)	530.3	211.8	61.8	300 (50×6)	14-φ6.5	150
OSMS33-500(X)	730.3	311.8	61.8	500 (50×10)	22-φ6.5	250





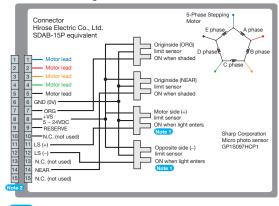
	Part Number	Α	В	С	D	Е	F
Ī	OSMS33-300(X)-M6	530.3	211.8	61.8	300 (50×6)	14-φ6.5	150
	OSMS33-500(X)-M6	730.3	311.8	61.8	500 (50×10)	22-φ6.5	250





Part Number	Α	В	С	D	E	F
OSMS33-300(X)-INCH	530.3	211.8	59.4	304.8 (50.8×6)	14-φ7	150
OSMS33-500(X)-INCH	730.3	311.8	57.8	508 (50.8×10)	22-φ7	250

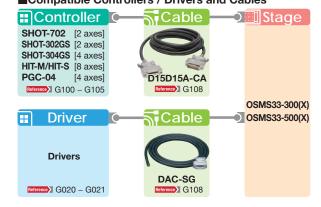
■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

■Compatible Controllers / Drivers and Cables



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Vacuum Options

□40mm

□60mm

⊒80mm

□85mm

□100mm

□120mm

OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS33-(XY) Stage size 120mm | RoHS





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□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Others

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools from which high stiffness and high precision are required.



• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

Guide

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

► Grease change is optionally available. Reference G110

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.

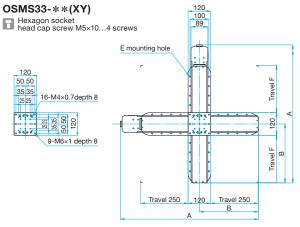
Specification	ons				
Part Number			OSMS33-300(XY)	OSMS33-500(XY)	
Part Number (-M	16)		OSMS33-300(XY)-M6	OSMS33-500(XY)-M6	
Part Number (-IN	NCH)		OSMS33-300(XY)-INCH	OSMS33-500(XY)-INCH	
	Travel [mm]		300	500	
	Table Size [mm]	120×120	120×120	
	Feed Screv	V	Ball screw diameter ϕ 10mm, 10mm lead	Ball screw diameter ϕ 10mm, 10mm lead	
Mechanical Specifications	Positioning Slide		Outer rail structure	Outer rail structure	
opcomodions.	Stage Material		Aluminum	Aluminum	
	Finish		Black anodized	Black anodized	
	Weight [kg]		14.0	17.2	
	Full) [μm/pulse]		20	20	
	Resolution	(Half) [µm/pulse]	10	10	
Accuracy	MAX Speed [mm/sec]		80	80	
Specifications	Load Capa	city [N]	156 (16.0kgf)	156 (16.0kgf)	
	Backlash [µ	ım]	3	3	
	Orthogonal	ity of Motion [µm]	5	5	
	Sensor Par	t Number	Micro photo sensor: GP1S09	92HCPIF(Sharp Corporation)	
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
Serisur	Origin Sens	sor	None	None	
	Proximity C	rigin Sensor	None	None	

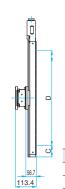
Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)			
Motor	Motor Part Number	TS3667N43E967 (□42mm)			
	Step Angle	0.72°			
Sensor	Power Voltage	DC5 - 24V±10%			
	Current Consumption	40mA or lower (20mA or lower per sensor)			
	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF (no conduction)			

(Reference) Precision Specifications of Single Axis Stage						
Part Number			OSMS33-300(X)	OSMS33-500(X)		
	Positioning	Accuracy [µm]	15	20		
	Positional Repeatability [µm]		6	6		
		Pitch ["/N·cm]	0.12	0.12		
Accuracy	Moment Stiffness	Yaw ["/N·cm]	0.08	0.08		
Specifications	0	Roll ["/N·cm]	0.08	0.08		
	Lost Motion [µm]		5	5		
	Parallelism	[µm]	50	50		
	Running Pa	arallelism [µm]	10	10		

Compatible Driver / Controller				
Control System	Compatible Driver	SG-55M, SG-55MA, SG-514MSC, MC-7514PCL		
	Compatible Controller	SHOT-702, SHOT-302GS, SHOT-304GS, HIT-M+HIT-S, PGC-04		





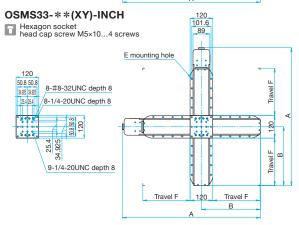


Part Number	Α	В	С	D	Е	F
OSMS33-300(XY)	530.3	211.8	61.8	300 (50×6)	14-φ7	150
OSMS33-500(XY)	730.3	311.8	61.8	500 (50×10)	22-φ7	250

OSMS33-**(XY)-M6 120 100 89 Hexagon socket head cap screw M5×10...4 screws E mounting hole 120 50 50 8-M4×0.7 depth 8 **Travel F** 25 25 8-M6×1 depth 8 100 25.25 35.35 50.50 120 120 9-M6×1 depth 8 Travel F Travel F



Part Number	Α	В	С	D	Е	F
OSMS33-300(XY)-M6	530.3	211.8	61.8	300 (50×6)	14-φ7	150
OSMS33-500(XY)-M6	730.3	311.8	61.8	500 (50×10)	22-φ7	250





Controller

SHOT-702 [2 axes]

SHOT-302GS [2 axes]

SHOT-304GS [4 axes] HIT-M/HIT-S [8 axes]

[4 axes]

■ G100 – G105

Driver

Drivers

Reference G020 - G021

PGC-04

Part Number	Α	В	С	D	Е	F
OSMS33-300(XY)-INCH	530.3	211.8	59.4	304.8 (50.8×6)	14-φ7	150
OSMS33-500(XY)-INCH	730.3	311.8	57.8	508 (50.8×10)	22-φ7	250

Cable

D15D15A-CA

■3 G108

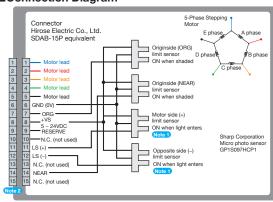
Cable

DAC-SG

33 G108

■Compatible Controllers / Drivers and Cables

■Connection Diagram



Note 1	The motor	or side	limit sensor is	s the + direction limit sensor.	
$\overline{}$					

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

0	pti	CS	&	
0	nti	ca	П	

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Stage

OSMS33-300(XY)

OSMS33-500(XY)

□40mm

□60mm

□80mm

□85mm

□100mm

□120mm



OSMS Series Translation Motorized Stages - 5 Phase Stepping Motor | OSMS33-(Z) RoHS





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□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Others

Stepping motor driven stages, ideal for positioning of measuring instruments or inspection tools from which high stiffness and high precision are required.



• U-shaped rail offers light weight, and minimized deflection to achieve high stiffness.

Guide

▶ Contact our International Sales Division if you desire to change motors, etc.

Reference G017, G111 (Motorized Stage System Question Sheet)

► Grease change is optionally available. Reference G110

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.

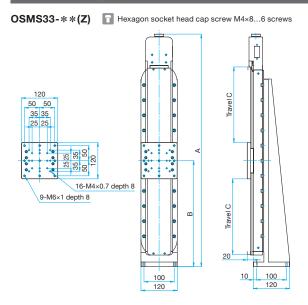
Part Numb	ner		OSMS33-300(Z)	OSMS33-500(Z)	
Part Number (-M6)			OSMS33-300(Z)-M6	OSMS33-500(Z)-M6	
Part Numb			OSMS33-300(Z)-INCH	OSMS33-500(Z)-INCH	
	Travel [mm]		300	500	
	Table Size [mr	n]	120×120	120×120	
Mechani-	Feed Screw		Ball screw diameter ϕ 10mm, 10mm lead	Ball screw diameter ϕ 10mm, 10mm lead	
cal Specifica-	Positioning SI	ide	Outer rail structure	Outer rail structure	
tions	Stage Materia	I	Aluminum	Aluminum	
	Finish		Black anodized	Black anodized	
	Weight [kg]		14.5	16.1	
	Resolution	(Full) [µm/pulse]	20	20	
		(Half) [µm/pulse]	10	10	
	MAX Speed [mm/sec]		30	30	
	Positioning Accuracy [µm]		50	50	
	Positional Repeatability [µm]		6	6	
Accuracy	Load Capacity [N]		68.6 (7.0kgf)	68.6 (7.0kgf)	
Specifica-		Pitch ["/N·cm]	0.2	0.2	
tions	Moment Stiffness	Yaw ["/N·cm]	0.15	0.15	
		Roll ["/N·cm]	0.15	0.15	
	Lost Motion [µ	ım]	5	5	
	Backlash [µm]		3	3	
	Orthogonality	of Motion [µm]	30	35	
	Pitch ["] / Yaw	' ["]	50/25	55/25	
	Sensor Part N	umber	Micro photo sensor: GP1S09	2HCPIF(Sharp Corporation)	
Sensor	Limit Sensor		Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
CONSON	Origin Sensor		None	None	
	Proximity Orig	in Sensor	None	None	

Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)			
Motor	Motor Part Number	TS3667N43E967 (□42mm)			
	Step Angle	0.72°			
	Power Voltage	DC5 - 24V±10%			
0	Current Consumption	40mA or lower (20mA or lower per sensor)			
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF (no conduction)			

Compatible Driver / Controller				
Control	Compatible Driver	SG-55M, SG-55MA, SG-514MSC, MC-7514PCL		
System	Compatible Controller	SHOT-702, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04		



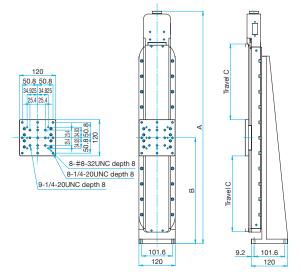




OSMS33-**(Z)-M6 🔳 H	exagon socket head cap	screw M4×86 screws
120 50 50 35 35 25 25 25 25 8-M4×0.7 depth 8 8-M6×1 depth 8	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Olevent C

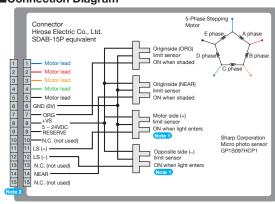
Part Number OSMS33-300(Z) OSMS33-500(Z)		А	В	С	
		620	250	150	
		768.5	350	250	

Part Number	Α	В	С
OSMS33-300(Z)-M6	620	250	150
OSMS33-500(Z)-M6	768.5	350	250



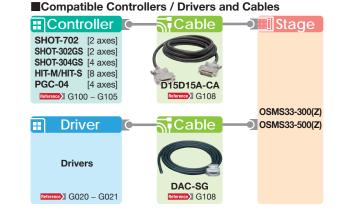
Part Number	А	В	С
OSMS33-300(Z)-INCH	620	248.4	150
OSMS33-500(Z)-INCH	768.5	350	250

■Connection Diagram



Note 1) The motor side limit sensor is the + direction limit sensor.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150



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Vacuum **Options**

□40mm

□60mm

□80mm

□85mm

□100mm

□120mm

Precision Motorized Stages with Built-in Compact Scale | OSMS(CS)33-(X) Stage size 120mm





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Vacuum **Options**

□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Others

The dedicated stage controllers (SHOT-302GS/304GS, HIT series) offer a full closed loop system



with high precision and high reliability.

- The stages enable high stiffness and high precision positioning because their structure, which is strong against momentum and combined load, is less susceptible to pitching, rolling and yawing.
- A compact scale is built in, but the installation space is the same as that of other OSMS series when the travel is the same.

Guide

- ▶ Contact our International Sales Division for replacement of motors or for stabilizing (drop-preventing) mechanism. Reference G017, G111 (Motorized Stage System Question Sheet)
- ▶ Grease change is optionally available. Reference G110
- ▶ Contact our International Sales Division to use the stage as an XY axis or a Z axis stage.

Specification	ons				
Part Number			OSMS(CS)33-300(X)	OSMS(CS)33-500(X)	
Part Number (-M6)			OSMS(CS)33-300(X)-M6	OSMS(CS)33-500(X)-M6	
Part Number (-INCH)			OSMS(CS)33-300(X)-INCH	OSMS(CS)33-500(X)-ICH	
	Travel [mm]		300	500	
	Table Size [m	m]	120×120	120×120	
	Feed Screw		Ball screw diameter φ10mm, 10mm lead	Ball screw diameter φ10mm, 10mm lead	
Mechanical Specifications	Positioning S	lide	Outer rail structure	Outer rail structure	
Opcomodiono	Stage Materia	al	Aluminum	Aluminum	
	Finish		Black anodized	Black anodized	
	Weight [kg]		7.8	9.6	
	Danah dian	(Full) [µm/pulse]	20	20	
	Resolution	(Half) [µm/pulse]	10	10	
	MAX Speed [mm/sec]		100	100	
	Positioning A	ccuracy [µm]	25	25	
	Positional Re	peatability [µm]	5	5	
	Load Capacity [N]		196 (20.0kgf)	196 (20.0kgf)	
Accuracy		Pitch ["/N·cm]	0.12	0.12	
Specifications	Moment Stiffness	Yaw ["/N·cm]	0.08	0.08	
		Roll ["/N·cm]	0.1	0.1	
	Lost Motion [μm]	5	5	
	Backlash		3	3	
	Parallelism [µ	m]	50	50	
	Running Para	allelism [µm]	15	25	
	Pitch ["] / Yav	v ["]	40/25	40/25	
	Sensor Part I	Number	Micro photo sensor: GP1S09	92HCPIF (Sharp Corporation)	
Conner	Limit Sensor		Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
Sensor	Origin Senso	r	Equipped	Equipped	
	Proximity Ori	gin Sensor	Equipped	Equipped	
Scale head	Resolution [µ	m]	0.5	0.5	

Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)			
Motor	Motor Part Number	TS3667N43E967 (<u>42mm</u>)			
	Step Angle	0.72°			
	Power Voltage	DC5 - 24V±10%			
Sensor	Current Consumption	80mA or lower (20mA or lower per sensor)			
Serisor	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF (no conduction)			
Scale head	head Power Voltage / Current Consumption DC5V±5% / 100mA				

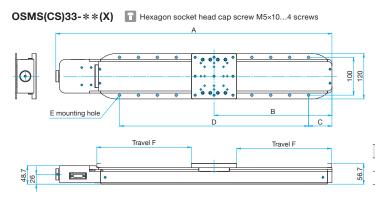
Compatible Cable				
Cable	Driver Cable	D15D15A-CA		
Cable	Scale Cable	GSEF-CA-3		

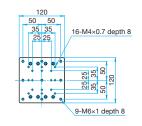
Compatible Driver / Controller				
Control Custom	Compatible Driver	_		
Control System	Compatible Controller	SHOT-302GS, SHOT-304GS, HIT-M·HIT-S		



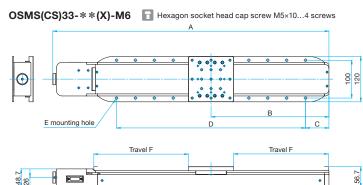


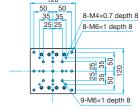






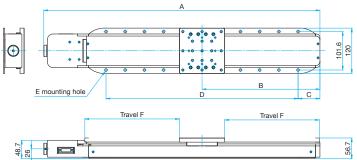
Part Number	Α	В	С	D	Е	F
OSMS(CS)33-300(X)	530.3	211.8	61.8	300 (50×6)	14-φ7	150
OSMS(CS)33-500(X)	730.3	311.8	61.8	500 (5×10)	22-φ7	250

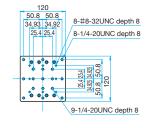




Part Number	Α	В	С	D	Е	F
OSMS(CS)33-300(X)-M6	530.3	211.8	61.8	300 (50×6)	14-φ7	150
OSMS(CS)33-500(X)-M6	730.3	311.8	61.8	500 (5×10)	22-φ7	250

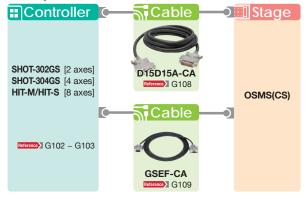






Part Number	Α	В	С	D	E	F
OSMS(CS)33-300(X)-INCH	530.3	211.8	59.4	304.8 (50.8×6)	14-φ7	150
OSMS(CS)33-500(X)-INCH	730.3	311.8	57.8	508 (50.8×10)	22-φ7	250

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□40mm **□60mm**

□80mm

□85mm

□100mm □120mm



SGMV series Translation Motorized Stages - AC servo Motor | SGMV RoHS

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Vacuum

Options

□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Others

High precision/high stiffness stages driven by AC servo motor.



• The stage structure unifies the functions of precision linear guide and precision ball screw, places the linear guide, inner block (table) and drive ball screw at the same position, and uses high stiffness U-shape outer rail for the guide to offer small footprint with large load rating.

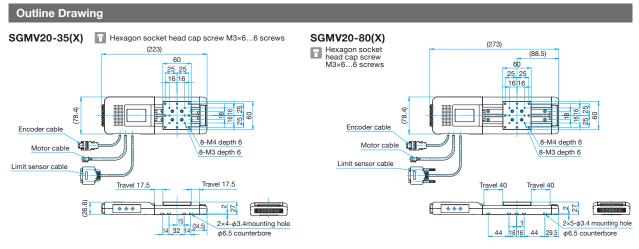
Specification	ons					
Part Number			SGMV20-35(X)	SGMV20-80(X)	SGMV26-100(X)	SGMV26-200(X)
	Travel [mm]		35	80	100	200
	Table Size [mm]	60×60	60×60	80×80	80×80
Mechanical	Feed Screv	V	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter ϕ 8mm, 2mm lead
Specifications	Positioning	Slide	Outer rail structure	Outer rail structure	Outer rail structure	Outer rail structure
	Stage Mate	erial	Aluminum	Aluminum	Aluminum	Aluminum
	Finish		Black anodized	Black anodized	Black anodized	Black anodized
	Weight [kg]		0.7	1	1.7	2.5
	D 1.:	(Full) [µm/pulse]	2	2	4	4
	Resolution	(Half) [µm/pulse]	1	1	2	2
	MAX Speed [mm/sec]		35	80	130	130
	Positioning Accuracy [µm]		7	10	10	15
	Positional Repeatability [µm]		4	5	5	6
	Load Capacity [N]		80 (8kgf)	80 (8kgf)	130 (13kgf)	130 (13kgf)
Accuracy	Moment Stiffness	Pitch ["/N·cm]	0.4	0.4	0.23	0.23
Specifications		Yaw ["/N·cm]	0.25	0.25	0.12	0.12
	Cumicoo	Roll ["/N·cm]	0.35	0.35	0.2	0.2
	Lost Motion	n [µm]	2	2	2	2
	Backlash [µ	ım]	2	2	2	2
	Parallelism	[µm]	30	30	50	50
	Running Pa	rallelism [µm]	10	10	10	10
	Pitch ["] / Y	'aw [″]	30/20	30/20	30/20	30/25
	Sensor Par	t Number		Micro photo sensor: P	M-L24 (SUNX Co.,Ltd.)	
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sens	sor	None	None	None	None
	Proximity C	rigin Sensor	None	None	None	None

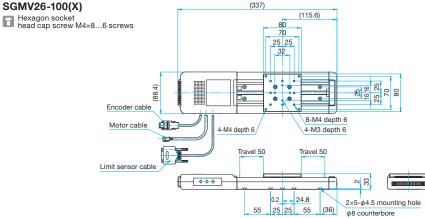
Motor / Sensor Specifications					
	Туре	AC servo Motor 10W (YASKAWA Electric Corporation)			
Motor	Motor Part Number	SGMMV-A1E2A21 (□25mm)			
	Step Angle	0.0318N·m			
	Power Voltage	DC5 - 24V±10%			
Sensor	Current Consumption	30mA or lower (15mA or lower per sensor)			
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF (no conduction)			

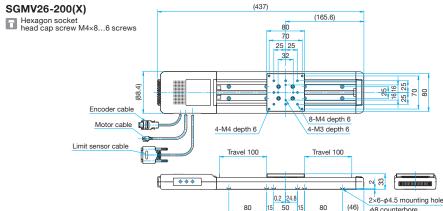
Compatible	Compatible Driver / Controller		
Control Custom	Compatible Driver	SGDV-2R9EP1A	
Control System Compatible Controller		PGC-04	











Cable Length ≒280mm Plug: 55102-0600 (Molex Japan Co., Ltd.) Motor cable*²
Cable Length ≒280mm
Receptacle: 43025-0400 (Molex Japan Co., Ltd.)

Limit sensor e. able
Cable Length ≒280mm
D-sub9Pin (JAE)
(Connector DE-9P-NR
Hood DE-C8-J9-F1-1R

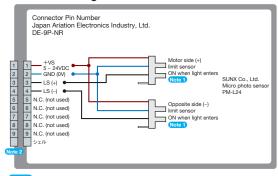
*2 Servo Pack SGDV-2R9EP1A

Controller / Servo Pack Part Number Products Name PGC-04 Pulus Generating Controller SGDV-2R9EP1A Servo Packs for Driving Servo Motor



Cable				
Part Number	Controller Side	Stage Side	Servo Pack Side	Cable Length [m]
PGC-ACS-2	10126-3000PE	DE-957S-NR	10126-3000PE	2
JZSP-CF1M00-03E	_	_	_	3
JZSP-CMP00-03E	_	_	_	3
JZSP-CF1G00-01-E	_	_	_	1

■Connection Diagram



The motor side limit sensor is the + direction limit sensor.

Motorized stages are not fitted with origin and proximity origin sensors.

Limit sensors are used as origin detection sensors. Compatible cable connector:

Japan Ariation Electronics Industry, Ltd. DE-C8-J9-F1-1R

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□40mm

⊒60mm **□80mm**

□85mm

□100mm

□120mm



Thin Long Travel Stage | KLSA/KLSS

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Options

□40mm □60mm

□80mm

□85mm

□100mm

□120mm

Others

These stages are thin but ensure long travel.

These thin motorized stages can minimize the stage height even when used in combination.



- Four linear guide blocks are located at optimal positions to improve positional repeatability.
- To place importance on price, KLSA which has an aluminum body is recommended. To place importance on rigidity, KLSS which has a steel body is recommended.

Guide

- ▶ Please contact us when assembled into XYZ axis or use in reversion on the ceiling or vertical direction.
- ▶ Opposite model or various motor changes are optionally available. ☐ George ☐ G030

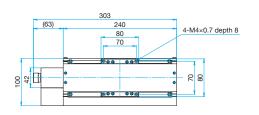
Specification			1/1 04 4007	1/1 00 4001/	1/1 04 0001/	141.00.0007
Part Number		KLSA-100X	KLSS-100X	KLSA-200X	KLSS-200X	
	Travel [mm]		100	100	200	200
	Table Size [mm]	80×80	80×80	120×120	120×120
Mechanical	Feed Screw	ı	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ8mm, 2mm lead	Ball screw diameter φ10mm, 5mm lead	Ball screw diameter φ10mm 5mm lead
Specifications	Positioning	Slide	Liner guide	Liner guide	Liner guide	Liner guide
	Stage Mate	rial	Aluminum	Steel	Aluminum	Steel
	Finish		Black anodized	Black chromium oxide	Black anodized	Black chromium oxide
	Weight [kg]		2.2	3.5	5.1	7.7
	Resolution	(Full) [µm/pulse]	4	4	10	10
	Resolution	(Half) [µm/pulse]	2	2	5	5
	MAX Speed [mm/sec]		30	30	50	50
	Positioning	Accuracy [µm]	15	15	20	20
	Positional Repeatability [µm]		±1	±1	±1	±1
	Load Capacity [N]		147 (15kgf)	147 (15kgf)	294 (30kgf)	294 (30kgf)
Accuracy	Moment Stiffness	Pitch ["/N·cm]	0.05	0.05	0.02	0.02
Specifications		Yaw ["/N·cm]	0.05	0.05	0.02	0.02
		Roll ["/N·cm]	0.1	0.1	0.02	0.02
	Lost Motion	n [µm]	4	4	4	4
	Backlash [µ	ım]	1	1	1	1
	Parallelism	[µm]	50	50	50	50
	Orthogonali	ity of Motion [µm]	10	10	10	10
	Pitch ["] / Ya	aw ["]	20/15	20/15	40/20	40/20
	Sensor Part	t Number	Micro p	hoto sensor: PM-L24 (SUNX	Co.,Ltd.) Limit sensor, origin	sensor
•	Limit Senso	or	Equipped	Equipped	Equipped	Equipped
Sensor	Origin Sens	sor	Equipped	Equipped	Equipped	Equipped
	Proximity O	rigin Sensor	None	None	None	None

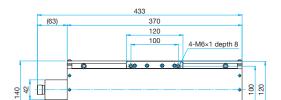
Motor / S	Motor / Sensor Specifications			
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)		
Motor	Motor Part Number	PK545-NBW (□42mm)		
	Step Angle	0.72°		
	Power Voltage	DC+5V - +24V		
	Current Consumption	45mA or lower (15mA or lower per sensor)		
Sensor	Control Output	NPN open collector output 50mA		
	Output Logic	In the case of light shielded ,output transistor OFF (No conduction): Limit sensor In the case of light shielded ,output transistor ON (Conduction): Origin sensor		

Compatible	Compatible Driver / Controller			
Control Custom	Compatible Driver	SG-5M, SG-55M, SG-514MSC, MC-7514PCL		
Control System	Control System Compatible Controller SHOT-302GS, SHOT-304GS, HIT-M-HIT-S, PGC-04			

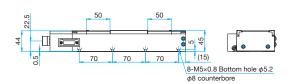


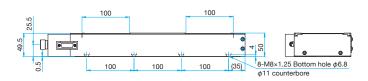




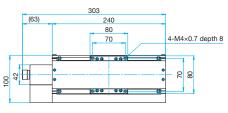


KLSA-200X





Hexagon socket head cap screw M4×8...6 screws

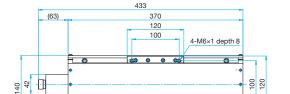


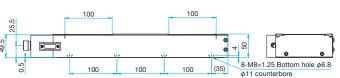


(15)

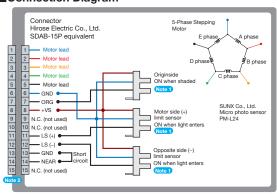
8-M5×0.8 Bottom hole φ4.2

70





■Connection Diagram

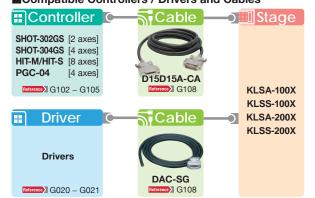


Note 1 The motor side limit sensor is the + direction limit sensor.

Motorized stages are not fitted with origin and proximity origin sensors.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

■Compatible Controllers / Drivers and Cables



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□40mm

□60mm

■80mm ■85mm

□100mm

□100mm



Aluminum Crossed Roller Guide Motorized Stage TAMM Stage size 40/60/100mm

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Vacuum **Options**

□40mm □60mm

□80mm □85mm

□100mm

□120mm

Motorized crossed roller stages that combine compactness, low-profile and high durability.



- Linear motorized stages fitted with anti-creep crossed roller guide and special nut-shape ball screw configuration, offering low-profile and high durability.
- Aluminum is used as a main material to achieve lightweight, compact and slim body, effective for spacesaving.

Guide

- ▶ A spacer is required when fixing the stage on a vibration isolator bench. It can be purchased separately. Reference D055
- ▶ After purchasing two X axis stages, to assemble them into an XY axis stage, assembly adjustment cost and performance inspection cost will be charged separately.
- ▶ Contact our International Sales Division if you desire to change motors, etc. Or, use the motorized stage system question sheet. Reference G111

Specification	ons					
Part Number			TAMM40-10C	TAMM60-15C	TAMM100-50C	TAMM100-100C
Opposite ModelPart Number		TAMM40-10CR	TAMM60-15CR	TAMM100-50CR	TAMM100-100CR	
	Travel [mm]		10	15	50	100
	Table Size [mm]	40×40	60×60	100×100	100×175
Mechanical	Feed Screw	1	Ball screw diameter φ4mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ8mm, 1mm lead
Specifications	Positioning	Slide	Crossed roller guide	Crossed roller guide	Crossed roller guide	Crossed roller guide
	Stage Mate	rial	Aluminum	Aluminum	Aluminum	Aluminum
	Finish		Black anodized	Black anodized	Black anodized	Black anodized
	Weight [kg]		0.33	0.48	1.9	2.9
	Resolution	(Full) [µm/pulse]	2	2	2	2
	nesolution	(Half) [µm/pulse]	1	1	1	1
	MAX Speed [mm/sec]		10	10	10	10
	Positioning	Accuracy [µm]	6	6	6	10
	Positional Repeatability [µm]		1	1	1	1
Accuracy	Load Capacity [N]		29.4 (3.0kgf)	49 (5.0kgf)	98 (10.0kgf)	98 (10.0kgf)
Specifications	Moment Stiffness["/N·cm]		1.5	0.5	0.05	0.03
	Lost Motion [µm]		1	1	1	1
	Backlash [µm]		1	1	1	1
	Parallelism	[µm]	30	30	30	30
	Running Pa	rallelism [µm]	10	10	10	10
	Pitch ["] / Ya	aw ["]	25/25	20/20	20/15	20/15
	Sensor Part	t Number	Micro photo sensor: GP1S0 Limit Sensor,	97HCZ (Sharp Corporation) Origin Sensor		M-L24 (SUNX Co.,Ltd.) Origin Sensor
Sensor	Limit Senso	pr	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sens	or	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)
	Proximity O	rigin Sensor	None	None	None	None

Motor / Se	Motor / Sensor Specifications				
	Туре	5-phase stepping motor 0.75A/	phase (Oriental Motor Co., Ltd.)		
Motor	Motor Part Number	C9863-90215P (□28mm)	PK544NBW (□42mm)		
	Step Angle	0.7	72°		
	Power Voltage	DC+5V - +24V			
	Current Consumption	60mA or lower (20mA or lower per sensor)			
Sensor	Control Output	NPN open collector output 50mA			
	Output Logic	In the case of light shielded ,output transistor OFF (No conduction): Limit sensor In the case of light shielded ,output transistor ON (Conduction): Origin sensor			

Compatible Driver / Controller				
Cantral System	Compatible Driver	SG-5M, SG-5MA, SG-55M, SG-55MA, SG-514MSC, MC-7514PCL	SG-5M, SG-55M, SG-514MSC, MC-7514PCL	
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04	SHOT-702, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S	





Connector Pin Number Hirose Electric Co., Ltd. RP17-13JA-12SC

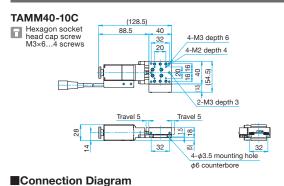
Motor lead
 Motor lead
 Motor lead

- Motor lead

LS (+) •

11 FG 12 FG

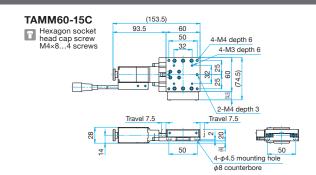
Sensor Power source 12V GND (0V)



E-Pha

ON when light enters

ON when light enters



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Options

⊒40mm

□60mm

□80mm

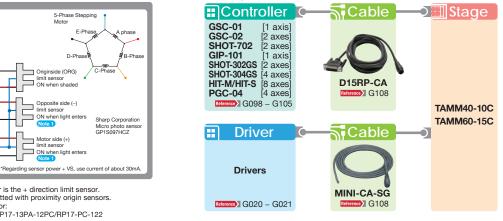
85mm

□100mm

□120mm

Others

■Compatible Controllers / Drivers and Cables



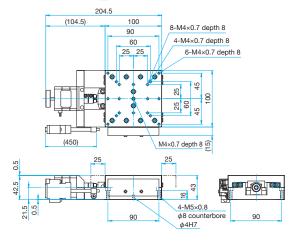
TAMM100-50C Hexagon socket head cap screw M4×8...4 screws

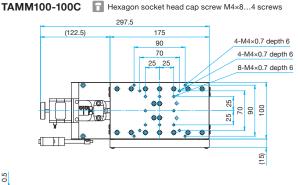
The motor side limit sensor is the + direction limit sensor.

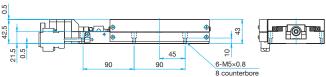
Motorized stages are not fitted with proximity origin sensors.

Compatible cable connector:

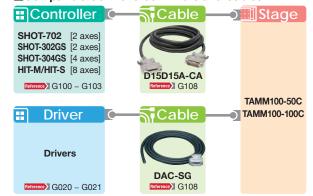
Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122



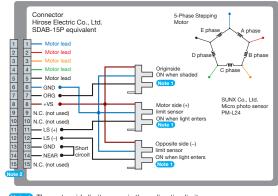








■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor Motorized stages are not fitted with origin and proximity origin sensors.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150



Precision Motorized Stages - 5 Phase Stepping Motor

KST-X

RoHS

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Options

□40mm

□60mm

□80mm

□85mm

□120mm

Others

High precision X axis stages fitted with precision ball screws and precision crossed roller.



 Steel body offers excellent stiffness and high load capacity.

Guide

► Contact our International Sales Division if you desire to change motors, etc. Or, use the motorized stage system question sheet.

Reference G111

Attention

▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.

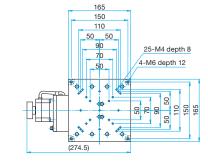
	ons				
Part Number			KST-50X	KST-100X	KST-200X
	Travel [mm]		50	100	200
	Table Size [mm]	165×165	165×200	165×360
Mechanical	Feed Screw	ı	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ14mm, 2mm lead
Specifications	Positioning	Slide	Crossed roller	Crossed roller	Crossed roller
	Stage Mate	rial	Steel (S50C)	Steel (S50C)	Steel (S50C)
	Weight [kg]		8.6	10.2	20.0
	Danalistias	(Full) [µm/pulse]	2	2	4
	Resolution	(Half) [µm/pulse]	1	1	2
	MAX Speed [mm/sec]		10	10	20
	Positioning Accuracy [µm]		5	7	8
	Positional Repeatability [µm]		2	2	2
	Load Capacity [N]		392 (40.0kgf)	392 (40.0kgf)	392 (40.0kgf)
Accuracy	Moment Stiffness	Pitch ["/N·cm]	0.01	0.01	0.01
Specifications		Yaw ["/N·cm]	0.01	0.01	0.01
		Roll ["/N·cm]	0.005	0.005	0.005
	Lost Motion [µm]		1	1	1
	Backlash [µ	ım]	1	1	1
	Parallelism	[µm]	50	70	100
	Running Pa	rallelism [µm]	10	10	20
	Pitch ["] / Yaw ["]		15/15	20/20	20/20
	Sensor Part	t Number	Micro photo sens	sor: PM-L24 (SUNX Co., Ltd.): Limit se	nsor, origin sensor
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
sensor	Origin Sens	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Proximity Origin Sensor		None	None	None

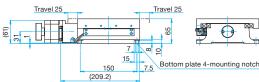
Motor / Sensor Specifications						
Type 5-phase stepping motor 1.4A/phase (Oriental Motor Co., Ltd.)				tor Co., Ltd.)		
Motor	Motor Part Number	PK564-NBW (□60mm)	PK566-NBW (□60mm)	PK569-NBW (□60mm)		
	Step Angle	0.72°				
Sensor	Power Voltage	DC5 – 24V ±10%				
	Current Consumption	45mA or lower (15mA or lower per sensor)				
	Control Output	NPN open collector output DC30V or lower, 50mA				
	Output Logic	When	shaded: Output transistor OFF (no con	duction)		

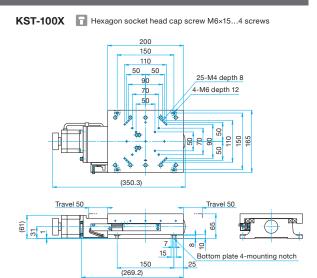
Compatible	Compatible Driver / Controller		
0 1 10 1	Compatible Driver	SG-5M, SG-55M, SG-514MSC, SG-5151, KR-525M	
Control System	Compatible Controller	SHOT-302GS, SHOT-304GS	

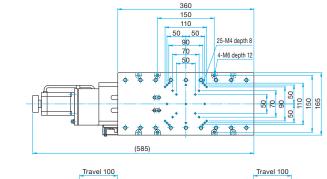






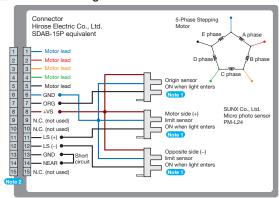








■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor. KST-50/100/200 is fitted with an origin sensor.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

■Compatible Controllers / Drivers and Cables



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□40mm

□60mm □80mm

□85mm

□100mm



Precision Motorized Stages with built in Glass-scale Encoder | KST(GS) | RoHS

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□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm

Linear scales consist of "scales" used as a ruler and a "detector" which obtains positional information from the scales.



• Linear scales are used in indispensable processes in many fields, and mainly used in equipment for manufacturing electronic devices such as semiconductors, flat panel displays (FPD), and printed wiring boards, electronic component mounting machine, machine tools, and carrier machine.

- ▶Theoretical resolution of the glass scale is set to 0.05µm.
- Contact our International Sales Division for resolutions not listed in the catalog.

Attention

▶ When operating the KST(GS) series with closed loop control, in order to use it within the specifications listed in the catalog, the number of motor divisions of the controller is recommended to be set to 100 or higher (travel per pulse is 0.05µm or less).

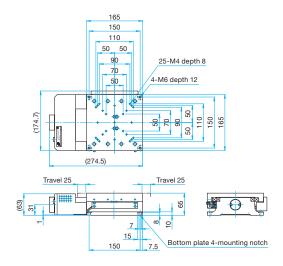
Specification	ons				
Part Number		KST(GS)-50X	KST(GS)-100X	KST(GS)-200X	
	Travel [mm]		50	100	200
	Table Size [mm]	165×165	165×200	165×360
Mechanical	Feed Screw	V	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ14mm, 2mm lead
Specifications	guide		Crossed roller guide	Crossed roller guide	Crossed roller guide
	Stage Mate	erial	Steel	Steel	Steel
	Weight [kg]		9.2	14.3	19.4
	Danal Mina	(Full) [µm/pulse]	2	2	4
	Resolution	(Half) [µm/pulse]	1	1	2
	MAX Speed [mm/sec]		10	10	20
	Positioning Accuracy [µm]		3	4	5
	Positional Repeatability [µm]		0.5	0.5	0.8
	Load Capacity [N]		392 (40.0kgf)	392 (40.0kgf)	392 (40.0kgf)
Accuracy	Moment Stiffness	Pitch ["/N·cm]	0.01	0.01	0.01
Specifications		Yaw ["/N·cm]	0.01	0.01	0.01
		Roll ["/N·cm]	0.005	0.005	0.005
	Lost Motion	n [µm]	0.5	0.5	0.5
	Backlash [µ	ım]	1	1	1
	Parallelism	[µm]	50	70	100
	Running Pa	rallelism [µm]	10	10	20
	Pitch ["] / Yaw ["]		15/15	20/20	20/20
	Sensor Par	t Number	Micro photo sen	sor: PM-L24 (SUNX Co.,Ltd.) Limit ser	nsor, origin sensor
0	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Sensor	Origin Sens	sor	None	None	None
	Proximity C	rigin Sensor	None	None	None

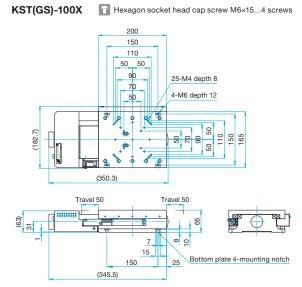
MotorSpecifications							
	Туре	5-phase ste	5-phase stepping motor 1.4A/phase (Oriental Motor Co., Ltd.)				
Motor	Motor Part Number	PK564-NBW (□60mm)	PK566-NBW (□60mm)	PK569-NBW (□60mm)			
	Step Angle	0.72°					

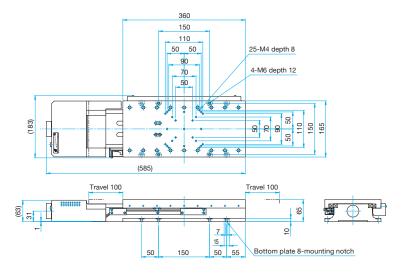
Compatible Controller				
Compatible Controller	SHOT-302GS, SHOT-304GS			



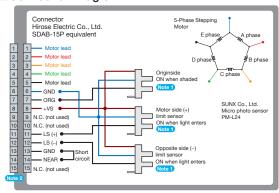








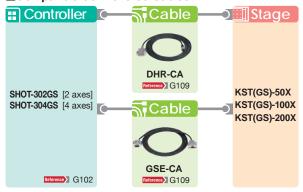
■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor. KST-50/100/200 is fitted with an origin sensor.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

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□85mm

□100mm

□100mm



Precision Motorized Stages - 5 Phase Stepping Motor

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□40mm

□60mm

□80mm

□100mm

□120mm

Others

High precision XY axis stages fitted with precision ball screws and precision crossed roller.



 Steel body offers excellent stiffness and high load capacity.

Guide

- ► Contact our International Sales Division if you desire to change motors, etc. Or, use the motorized stage system question sheet.

 Reference 3 G111
- ▶ We will assemble your X axis stage with a newly purchased X axis stage at a separate cost.

Specifications						
Part Number			KST-50XY	KST-50XY KST-100XY		
Mechanical	Travel [mm]		50	100	200	
	Table Size [[mm]	165×165	165×200	165×360	
	Feed Screv	V	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ14mm, 2mm lead	
Specifications	Specifications Positioning Slide Crossed roller Crossed roller Stage Material Steel (S50C) Steel (S50C)	Crossed roller	Crossed roller			
	Stage Mate	erial	Steel (S50C)	Steel (S50C)	Steel (S50C)	
	Weight [kg]		17.2	20.4	40.0	
	Resolution	(Full) [µm/pulse]	2	2	4	
		(Half) [µm/pulse]	alf) [µm/pulse] 1 1		2	
	MAX Speed	d [mm/sec]	10	10	20	
	Positioning Accuracy [µm]		10	12	15	
Accuracy Specifications	Positional Repeatability [µm]		2	2	2	
ороспосионо	Load Capa	city [N]	196 (20.0kgf)	196 (20.0kgf)	196 (20.0kgf)	
	Lost Motion	n [µm]	1	1	1	
	Backlash [µ	ım]	1	1	1	
	Orthogonal	ity of Motion [µm]	5	5	10	
	Sensor Par	t Number	Micro photo sens	or: PM-L24 (SUNX Co., Ltd.): Limit se	nsor, origin sensor	
Sonor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
3611501	Sensor	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)		
	Proximity C	Origin Sensor	None	None	None	

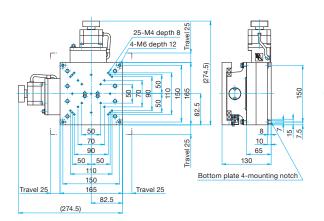
Motor / Sensor Specifications							
Motor	Туре	5-phase stepping motor 1.4A/phase (Oriental Motor Co., Ltd.)					
	Motor Part Number	PK564-NBW (□60mm)	PK566-NBW (□60mm)	PK569-NBW (□60mm)			
	Step Angle	0.72°					
	Power Voltage	DC5 – 24V ±10%					
Sensor	Current Consumption	45mA or lower (15mA or lower per sensor)					
Serisor	Control Output	NPN open collector output DC30V or lower, 50mA					
	Output Logic	When	shaded: Output transistor OFF (no con	duction)			

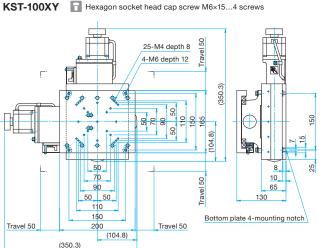
(Reference) Precision Specifications of Single Axis Stage						
Part Number KST-50X KST-100X KST-200X					KST-200X	
	Moment Stiffness	Pitch ["/N·cm]	0.01	0.01	0.01	
		Yaw ["/N·cm]	0.01	0.01	0.01	
Accuracy Specifications		Roll ["/N·cm]	0.005	0.005	0.005	
	Parallelism [µm]		50	70	100	
	Running Pa	arallelism [µm]	10	10	20	

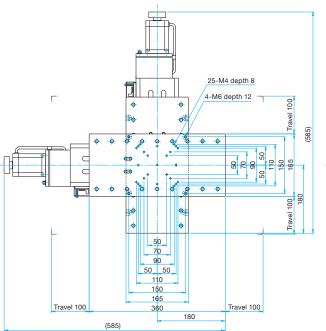
Compatible Driver / Controller				
Control Custom	Compatible Driver	SG-5M, SG-55M, SG-514MSC, SG-5151, KR-525M		
Control System	Compatible Controller	SHOT-302GS, SHOT-304GS		

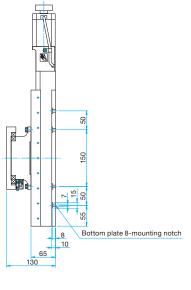




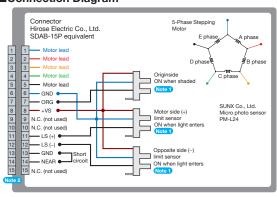








■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor. KST-50/100/200 is fitted with an origin sensor.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

■Compatible Controllers / Drivers and Cables



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□40mm □60mm

□100mm

□100mm



Precision Motorized Stages - 5 Phase Stepping Motor

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Options

□40mm

□60mm **□80mm**

□85mm

□100mm □120mm

High precision Z axis stages fitted with precision ball screws and precision crossed roller.



 Steel body offers excellent stiffness and high load capacity.

Guide

▶ Contact our International Sales Division if you desire to change motors, etc. Or, use the motorized stage system question sheet.

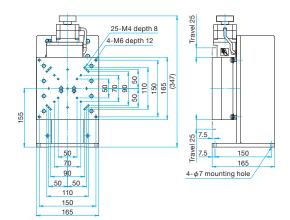
Specification	ons				
Part Number			KST-50Z	KST-100Z	KST-200Z
Mechanical Specifications	Travel [mm]		50	100	200
	Table Size [mm]	165×165	165×200	165×360
	Feed Screw	V	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ8mm, 1mm lead	Ball screw diameter φ14mm, 2mm lead
	Positioning Slide		Crossed roller	Crossed roller	Crossed roller
	Stage Mate	erial	Steel (S50C)	Steel (S50C)	Steel (S50C)
	Weight [kg]		12.8	14.5	27.0
	Danalistias	(Full) [µm/pulse]	2	2	4
	Resolution	(Half) [µm/pulse]	1	1	2
	MAX Speed [mm/sec]		10	10	20
	Positioning Accuracy [µm]		5	7	8
	Positional Repeatability [µm]		2	2	2
	Load Capacity [N]		98 (10.0kgf)	98 (10.0kgf)	98 (10.0kgf)
Accuracy Specifications		Pitch ["/N·cm]	0.015 (Y pitch)	0.020 (Y pitch)	0.030 (Y pitch)
opeomediene.	Moment Stiffness	Yaw ["/N·cm]	0.01 (X pitch)	0.015 (X pitch)	0.020 (X pitch)
	0	Roll ["/N·cm]	0.005	0.015	0.015
	Lost Motion	n [µm]	1	1	1
	Backlash [µ	ım]	1	1	1
	Perpendicul	arity of Motion [µm]	10	15	25
	Pitch ["] / Yaw ["]		20/15	25/20	25/25
	Sensor Parl	t Number	Micro photo sens	or: PM-L24 (SUNX Co., Ltd.): Limit se	nsor, origin sensor
	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Sensor	Origin Sens	sor	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Proximity O	rigin Sensor	None	None	None

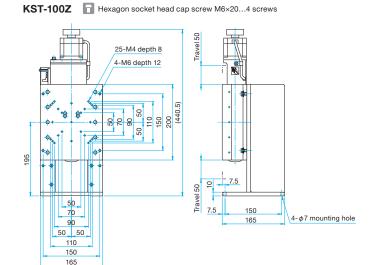
Motor / Sensor Specifications						
	Туре	5-phase stepping motor 1.4A/phase (Oriental Motor Co., Ltd.)				
Motor	Motor Part Number	PK564-NBW (□60mm)	PK566-NBW (□60mm)	PK569-NBW (□60mm)		
	Step Angle	0.72°				
	Power Voltage	Power Voltage DC5 – 24V ±10%				
Sensor	Current Consumption	45mA or lower (15mA or lower per sensor)				
Serisor	Control Output	NPN open collector output DC30V or lower, 50mA				
	Output Logic	When	shaded: Output transistor OFF (no con	duction)		

Compatible Driver / Controller				
Control Custom	Compatible Driver	SG-5M, SG-55M, SG-514MSC, SG-5151, KR-525M		
Control System	Compatible Controller	SHOT-302GS, SHOT-304GS		

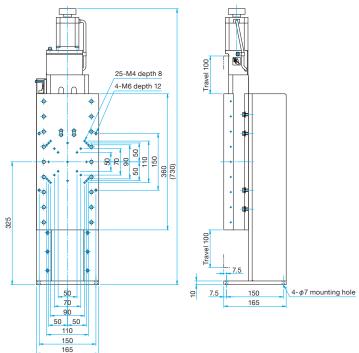




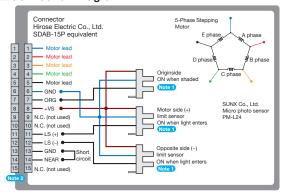




KST-200Z Hexagon socket head cap screw M6×20...4 screws



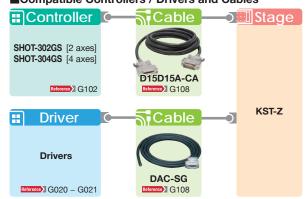
■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor. KST-50/100/200 is fitted with an origin sensor.

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

■Compatible Controllers / Drivers and Cables



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□40mm □60mm

□100mm



Translation Motorized Stages, Flat Z axis - 5 Phase Stepping Motor | OSMS-ZF Stage size 40/60/80mm | RoHS





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Options

□40mm □60mm

□80mm □85mm

□100mm

□120mm

Others

Z axis stepping motor driven stages for measurement and inspection, offering high stiffness and high precision.

The table that travels up and down is horizontal and offers smooth travel.



- Originally designed horizontal plane Z axis stages in which a motor is incorporated in its main body for space-saving.
- Minimized protrusions make these stages ideal for system assembly

Specifications							
Part Number			OSMS40-5ZF	OSMS60-5ZF	OSMS60-10ZF	OSMS80-20ZF	
	Travel [mm]		5	5	10	20	
	Table Size [mm]	40×40	60×60	60×60	80×80	
Mechanical	Feed Screw	,	Ball screw diameter φ5mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ8mm, 2mm lead	
Mechanical Specifications	Positioning	Slide	Outer rail structure	Outer rail structure	Outer rail structure	Outer rail structure	
	Stage Mate	rial	Aluminum	Aluminum	Aluminum	Aluminum	
	Finish		Black anodized	Black anodized	Black anodized	Black anodized	
	Weight [kg]		0.35	0.6	0.6	1.6	
	Resolution	(Full) [µm/pulse]	1.0	2.0	2.0	0.2	
	nesolution	(Half) [µm/pulse]	0.5	1.0	1.0	0.1	
	MAX Speed	[mm/sec]	2	4	4	1	
	Positional F	Repeatability [µm]	10	10	10	10	
	Load Capac	city [N]	19.6 (2.0kgf)	39.2 (4.0kgf)	39.2 (4.0kgf)	147 (15.0kgf)	
Accuracy		Pitch ["/N·cm]	2.0	0.4	0.4	0.2	
Specifications	Moment Stiffness	Yaw ["/N·cm]	2.0	1.0	1.0	1.0	
		Roll ["/N·cm]	1.0	1.0	1.0	1.0	
	Lost Motion	n [µm]	5	5	5	5	
	Parallelism	[µm]	50	50	50	50	
	Running Pa	rallelism [µm]	15	15	15	15	
	Pitch ["]		25	20	20	25	
	Sensor Part	Number	Micro photo sensor: GP1S097HCZ0F (Sharp Corporation): Limit Sensor (60-5ZF/60-10ZF) Micro photo sensor: PM-U24 (SUNX Co.,Ltd.): Limit Sensor (40-5ZF/80-20ZF)				
Sensor	Limit Senso	pr	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
	Origin Sens	or	None	None	None	None	
	Proximity O	rigin Sensor	None	None	None	None	

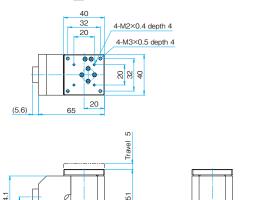
Motor / Sensor Specifications							
	Туре	5-phase stepping motor 0.35A/ phase (Oriental Motor Co., Ltd.)	5-phase stepping	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number	PK513PA-C21 (□20mm)	PK523HPB-C12 (□28mm)	PK523HPB-C12 (□28mm)	A7177-90215KTG (□28mm)		
	Step Angle		0.036°				
	Power Voltage	DC5 – 24V ±10% or lower					
Canaar	Current Consumption	30mA or lower (15mA or lower per sensor)					
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower					
	Output Logic		When shaded: Output tran	sistor OFF (no conduction)			

Compatible Driver / Controller					
Control System	Compatible Driver	SG-5MA, SG-55MA, SG-514MSC	SG-5M, SG-5MA, SG-55M, SG-55MA, SG-514MSC, MC-7514PCL	SG-55M, SG-55MA, SG-514MSC, MC-7514PCL	
	Compatible Controller	GSC-01, GSC-02, SHOT-702, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04			





OSMS40-5ZF Hexagon socket head cap screw M3×15...4 screws



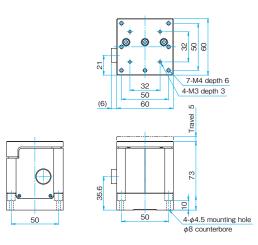
4-φ3.5 mounting hole

32

φ8 counterbore

32

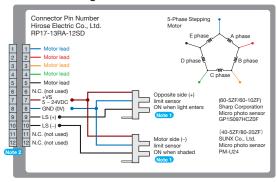
OSMS60-5ZF Hexagon socket head cap screw M4×15...4 screws



25 22 32 90 90 2 8 25 \bigoplus 7-M4depth 6 32 25 25 4-M4×0.7 depth 8 4-M3depth 3 20 50 70 8-M4×0.7 depth 4 0 80 Travel 14 16 16 14 8-M4×0.7 depth 5 25 25 10-M3×0.5 depth 5 25 ω 8 25 108 50 4-φ4.5 mounting hole 39.5

4-φ4.5 mounting hole

■Connection Diagram

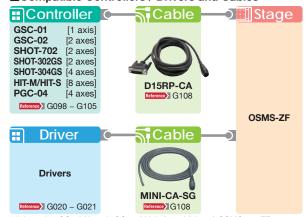


The motor side limit sensor is the + direction limit sensor. Motorized stages are not fitted with proximity origin sensors. Limit sensors are used as origin detection sensors.
Compatible cable connector:
Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

■Compatible Controllers / Drivers and Cables

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* Adaptation SG-5MA, only SG-55MA is (0.35A/phase) OSMS40-5ZF

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⊒40mm

⊒60mm

780mm □85mm

□100mm

□120mm



Actuator for Objective Lenses (Stepper motor type)

SGSP-OBL

RoHS

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□40mm

□60mm

□85mm

□100mm

□120mm

Others

Stepping motor type objective lens actuator compatible with long strokes.



- Since this actuator uses a stepping motor, it can be connected to our various controllers.
- It is compact and high resolution, best suited for incorporation into a microscope lens tube or an auto focus system.
- Can be used for upright type and inverted type microscopes.

Guide

▶ The dedicated adapters are available according to the microscope and screw size of objective lens of each manufacturer.

Attention

▶The dedicated adapters are required for mounting the actuator on microscopes and objective lenses.

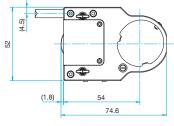
Specification	ons		
Part Number			SGSP-OBL-3
Mechanical Specifications	Travel [mm]		3
	Table Size [mm]		(Mounted adapter)
	Feed Screw		Precision ground screw ϕ 6mm, 0.5mm lead
	Positioning Slide		Crossed roller guide
	Stage Material		Aluminum
	Finish		White anodized
	Weight [kg]		0.4
	Resolution	(Full) [µm/pulse]	1
	nesolution	(Half) [µm/pulse]	0.5
	MAX Speed [mm/sec]		1
	Positioning Accuracy [µm]		5
	Positional Repeatability [µm]		2
Accuracy	Load Capacity [N]		4.9 (0.5kgf)
Specifications	Moment Stiffness["/N·cm]		-
	Lost Motion [µm]		2
	Backlash [µm]		1
	Parallelism [µm]		-
	Running Parallelism [µm]		2
	Pitch ["] / Yaw ["]		15/15
Sensor	Sensor Part Number		Micro photo sensor: GP1S092HCPI (Sharp Corporation)
	Limit Sensor		Equipped (NORMAL CLOSE)
	Origin Sensor		None
	Proximity Origin Sensor		None

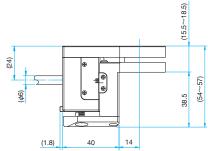
Motor / Sensor Specifications						
Motor	Туре	5-phase stepping motor 0.35A/phase (Oriental Motor Co., Ltd.)				
	Motor Part Number	PK513PA-C21 (<u>20mm</u>)				
	Step Angle	0.72°				
Sensor	Power Voltage	DC - 5V - +24V±10%				
	Current Consumption	40mA or lower (20mA or lower per sensor)				
	Control Output	NPN open collector output 50mA				
	Output Logic	In the case of light shielded ,output transistor OFF (No conduction): Limit sensor				

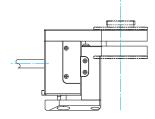
Compatible Driver / Controller						
Control System	Compatible Driver	SG-5MA, SG-55MA, SG-514MSC				
	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S				



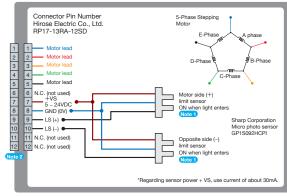
Outline Drawing







■Connection Diagram



Note 1 The motor side limit sensor is the + direction limit sensor.

Motorized stages are not fitted with proximity origin sensors.

Limit sensors are used as origin detection sensors.

Note 2 Compatible cable connector:

Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

Objective Lens Adapters



Outline Drawing	
OBL-ADP3-M**A 14.5 2, 4.5	OBL-ADP3-M**B

Specifications				
Part Number	Mounting Screw Size [mm]	A [mm]	B [mm]	
OBL-ADP3-M20.32A	Microscope side M20.32	M20.32 P=0.706 (W0.8×1/36)	15	
OBL-ADP3-M20.32B	Objective lens side M20.32	M20.32 P=0.706 (W0.8×1/36)	_	
OBL-ADP3-M25.0A	Microscope side M25.0	M25.0 P=0.75	20	
OBL-ADP3-M25.0B	Objective lens side M25.0	M25.0 P=0.75	_	
OBL-ADP3-M26.0A	Microscope side M26.0	M26.0 P=0.706 (W26.0×1/36)	21	
OBL-ADP3-M26.0B	Objective lens side M26.0	M26.0 P=0.706 (W26.0×1/36)		

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□40mm **□60mm**

□80mm

□85mm

□100mm

□120mm



Rotation Motorized Stages





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□60mm

□80mm □85mm

□100mm

□120mm

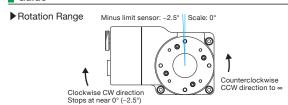
SGSP-YAW

Stepping motor driven rotation stages fitted with bearing guide and worm gear feed mechanism.



 Motorized stages suitable for positioning for measuring, inspection and evaluation instruments.

Guide



- \blacktriangleright Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- ▶ Origin detection is adjusted so that the stage stops at 0 degrees when homing is performed in the MINI system at half step.

Attention

- ▶ Attention is required when mounting in upside down direction or on a vertical plane.
- ▶ Precision and load capacity specifications may be partly not satisfied depending on the mounting direction.

Specification	ons				
Part Number		SGSP-40YAW	SGSP-60YAW-0B	SGSP-60YAW-W-0B	
	Rotation Ra	inge	Move in the counterclockwise CCW of	lirection to ∞, and stop at near 0 degree	e (-2.5°) in the clockwise CW direction.
	Table Size [mm]	φ40	φ60	φ60
Mechanical	Travel Mech (reduction ra		Worm gear (1:144)	Worm gear (1:144)	Worm gear (1:144)
Specifications	Positioning	Slide	Bearing method	Bearing method	Bearing method
	Stage Mate	rial	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze
	Weight [kg]		0.35	0.45	1.0
	D!-#:	(Full) [°/pulse]	0.005	0.005	0.005
	Resolution	(Half) [°/pulse]	0.0025	0.0025	0.0025
	MAX Speed [°/sec]		30	30	30
	Positioning	Accuracy [°]	0.1	0.1	_
	Positional Repeatability [°]		0.02	0.02	0.02
Accuracy	Load Capacity [N]		19.6 (2.0kgf)	29.4 (3.0kgf)	29.4 (3.0kgf)
Specifications	Moment Stiffness ["/N⋅cm]		2	1	_
	Lost Motion [°]		0.05	0.05	0.05
	Backlash [°]		0.1	0.1	0.1
	Parallelism [µm]		50	50	_
	Concentrici	ty [µm]	30	30	_
	Wobble [mm]		0.02	0.02	_
	Sensor Part	Number	Micro Photoelectric Sensor: PM-F24 (SUNX Co., Ltd.)	Micro Photoelectric Sensor: PM-R24 (SUNX Co., Ltd.)	Micro Photoelectric Sensor: PM-R24 (SUNX Co., Ltd.)
Sensor	Limit Senso	r	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sens	or	None	None	None
	Proximity O	rigin Sensor	None	None	None

Motor / S	Motor / Sensor Specifications				
	Туре	5-phase stepping motor 0.66A/phase (Tamagawa Seiki Co., Ltd.)			
Motor	Motor Part Number	TS3664N4 (□24mm)			
	Step Angle	0.72°			
	Power Voltage	DC5 – 24V ±10%			
0	Current Consumption	15mA or lower			
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF (no conduction)			

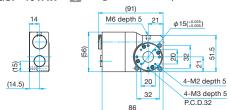
Compatible Driver / Controller			
Compatible Driver SG-5M, SG		SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL	
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04	

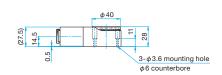


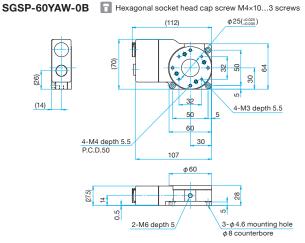


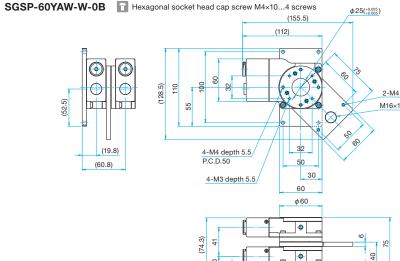
Outline Drawing

SGSP-40YAW Hexagon socket head cap screw M3×15...3 screws



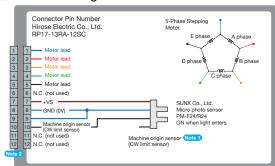






When homing of SGSP-60YAW-W-0B is performed, the position will become as shown below

■Connection Diagram



When a travel command in the "+" direction is issued, the mounting table rotates to ∞ in the CCW (counterclockwise) direction viewed from the top surface, but it is stopped by the COV (clockwise) direction when the machine origin sensor (CW limit sensor) in the CW (clockwise) direction.

Detect the machine origin using the method (MINI system) that detects the origin with a machine origin sensor (CW limit sensor).

Note 2 Compatible cable connector: Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

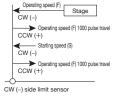
■Machine Origin Detection

MINI System

When the machine origin detection command is when the machine origin detection command is issued, the stage starts travelling in the CW (-) direction at the operating speed (F) set with the memory switch, and stops by the CW (-) side limit sensor. Then it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses. After stop, it starts traveling in the CW (-)

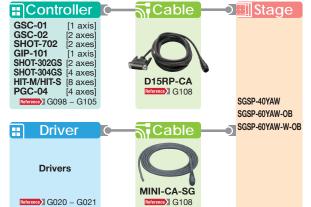
After stop, it starts traveling in the CW-() direction again at the starting speed (§), and stops by the CW (-) side limit sensor. After that, it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

This position is regarded as the machine origin.



■Compatible Controllers / Drivers and Cables

4-φ4.5 mounting hole



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□40mm

□60mm **□80mm**

□85mm

□100mm

□120mm



Rotation Motorized Stages

SGSP-YAW





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□40mm

□60mm

□80mm

□100mm

□120mm

Others

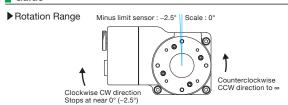
otation wotonzed Stages | 303F-17

Stepping motor driven rotation stages fitted with bearing guide and worm gear feed mechanism.



 Motorized stages suitable for positioning for measuring, inspection and evaluation instruments.

Guide



- ▶ Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- ▶ Origin detection is adjusted so that the stage stops at 0 degrees when homing is performed in the MINI system at half step.

Attention

- ▶ Attention is required when mounting in upside down direction or on a vertical plane.
- ▶ Precision and load capacity specifications may be partly not satisfied depending on the mounting direction.

Specification	ons					
Part Number			SGSP-80YAW	SGSP-120YAW	SGSP-160YAW	SGSP-120YAW-W
	Rotation Ra	nge	Move in the counterclockwis	e CCW direction to ∞, and st	op at near 0 degree (-2.5°) in	the clockwise CW direction.
	Table Size [r	mm]	φ80	φ120	φ160	φ120
Mechanical Specifications	Travel Mech (reduction ra		Worm gear (1:144)	Worm gear (1:144)	Worm gear (1:144)	Worm gear (1:144)
Specifications	Positioning	Slide	Bearing method	Crossed roller	Crossed roller	Crossed roller
	Stage Mater	rial	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze
	Weight [kg]		1.1	2.0	2.5	5.5
	Resolution	(Full) [°/pulse]	0.005	0.005	0.005	0.005
	nesolution	(Half) [°/pulse]	0.0025	0.0025	0.0025	0.0025
	MAX Speed [°/sec]		30	30	30	30
	Positioning .	Accuracy [°]	0.15	0.1	0.1	_
	Positional R	lepeatability [°]	0.02	0.02	0.02	0.02
Accuracy	Load Capacity [N]		98 (10.0kgf)	196 (20.0kgf)	196 (20.0kgf)	196 (20.0kgf)
Specifications	Moment Stiffness ["/N·cm]		0.2	0.1	0.1	_
	Lost Motion [°]		0.05	0.05	0.05	_
	Backlash [°]	0.08	0.08	0.08	0.08
	Parallelism	[µm]	50	50	60	_
	Concentricit	ty [µm]	30	30	30	_
	Wobble [mm]		0.02	0.02	0.02	_
	Sensor Part	Number		Micro Photoelectric Sensor	r: PM-F24 (SUNX Co., Ltd.)	
Sensor	Limit Senso	r	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
36/150/	Origin Sens	or	None	None	None	None
	Proximity O	rigin Sensor	None	None	None	None

Motor / S	Motor / Sensor Specifications				
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number	PK525HPB-C4 (□28mm)			
	Step Angle	0.72°			
	Power Voltage	DC5 - 24V ±10%			
0	Current Consumption	15mA or lower			
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF (no conduction)			

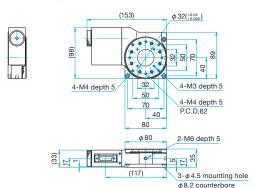
Compatible	Compatible Driver / Controller			
Compatible Driver	SG-55M, SG-55MA, SG-514MSC, MC-7514PCL			
Control System	Compatible Controller	SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04		

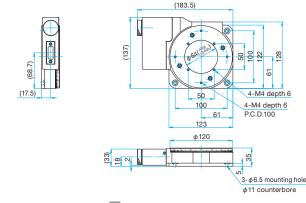




Outline Drawing

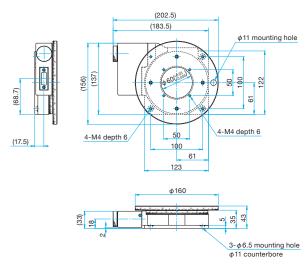
SGSP-80YAW Hexagonal socket head cap screw M4×10...3 screws

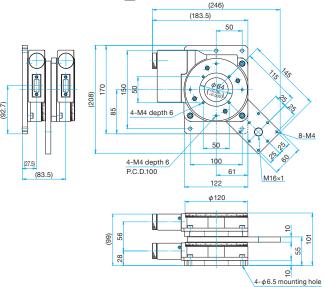




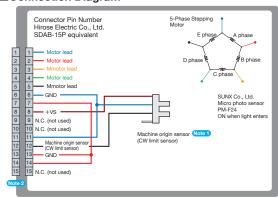
Hexagon socket head cap screw M6×10...3 screws

SGSP-120YAW





■Connection Diagram



Note 1 When a travel command in the "+" direction is issued, the mounting table rotates to ∞ in the CCW (counterclockwise) direction viewed from the top surface, but it is stopped by the machine origin sensor (CW limit sensor) in the CW (clockwise) direction. Detect the machine origin using the method (MINI system) that detects the origin with a machine origin sensor (CW limit sensor).

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

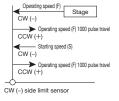
■Machine Origin Detection

MINI System

When the machine origin detection command is when the machine origin detection command is issued, the stage starts travelling in the CW (-) direction at the operating speed (F) set with the memory switch, and stops by the CW (-) side limit sensor. Then it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses. After stop, it starts traveling in the CW (-)

After stop, it starts traveling in the CW-() direction again at the starting speed (S), and stops by the CW (-) side limit sensor. After that, it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

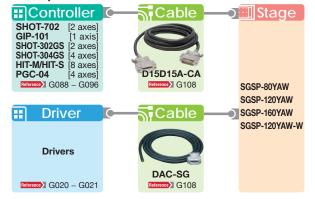
This position is regarded as the machine origin.



0 0

If homing of SGSP-120YAW-W is performed, the position will become as

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□40mm □60mm

□80mm

85mm

□100mm

□120mm



Precision Rotation Motorized Stages

KST-YAW





High precision and high stability rotation motorized stages fitted with bearing positioning slide.

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□60mm

□80mm

□100mm

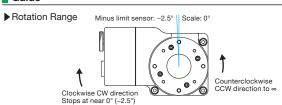
□120mm

Others



- Rotation motorized stages suitable for when high load capacity is required.
- Back up various inspection instruments according to usage such as the type, size, and measurement range of the measuring object.

Guide



- ▶ Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- ▶ Origin detection is adjusted so that the stage stops at 0 degrees when homing is performed in the MINI system at half step.

Attention

- ► Attention is required when mounting in upside down direction or on a vertical plane.
- ▶ Precision and load capacity specifications may be partly not satisfied depending on the mounting direction.

Specificati	ons			
Part Number			KST-120YAW	KST-160YAW
	Rotation Ra	inge	Move in the counterclockwise CCW direction to ∞, and sto	pp at near 0 degree (-2.5°) in the clockwise CW direction
	Table Size [mm]	φ120	φ160
Mechanical	Travel Mech (reduction ra		Worm gear (1:144)	Worm gear (1:144)
Specifications	Positioning	Slide	Bearing method	Bearing method
	Stage Mate	rial	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze
	Weight [kg]		5	8.5
	Resolution	(Full) [°/pulse]	0.005	0.005
	nesolution	(Half) [°/pulse]	0.0025	0.0025
	MAX Speed	l [°/sec]	30	30
	Positioning	Accuracy [°]	0.1	0.1
	Positional Repeatability [°]		0.01	0.01
Accuracy	Load Capacity [N]		343 (35.0kgf)	392 (40.0kgf)
Specifications	Moment Stiffness ["/N·cm]		0.015	0.01
	Lost Motion [°]		0.01	0.01
	Backlash [°]		0.003	0.003
	Parallelism	[µm]	50	50
	Concentrici	ty [µm]	20	20
	Wobble [mm]		0.01	0.01
	Sensor Part	Number	Micro Photoelectric Sensor: PM-U24 (SUNX Co., Ltd.)	Micro Photo Sensor: PM-R24 (SUNX Co., Ltd.)
Sensor	Limit Senso	r	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Serisor	Origin Sens	or	None	None
	Proximity O	rigin Sensor	None	None

Motor /	Motor / Sensor Specifications				
	Туре	5-phase stepping motor 1.4A/phase (Tamagawa Seiki Co., Ltd.)			
Motor	Motor Part Number	TS3624N42E (□60mm)			
	Step Angle	0.72°			
	Power Voltage	DC5 – 24V ±10%			
Canaar	Current Consumption	15mA or lower			
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	When shaded: Output transistor OFF			

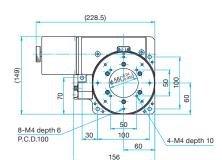
Compatible	Compatible Driver / Controller			
Control System Compatible Driver Compatible Controller		SG-5M*, SG-55M*, SG-514MSC*, MC-7514PCL (* DC36V)		
		SHOT-302GS, SHOT-304GS		

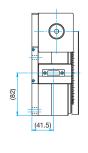




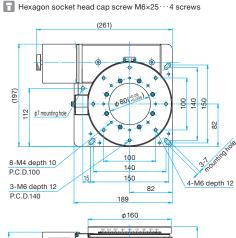
Outline Drawing

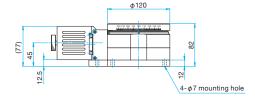
(42)

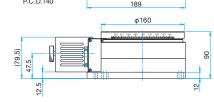




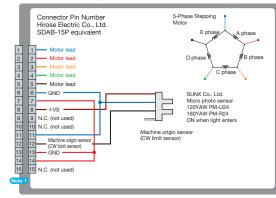
KST-160YAW







■Connection Diagram



Note 1 Compatible cable connector: DDK Ltd. 17JE-13150

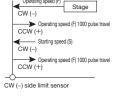
■Machine Origin Detection

MINI System

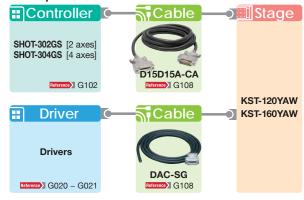
Winn System
When the machine origin detection command is issued, the stage starts traveling in the CW (-) direction at the operating speed (F) set with the memory switch, and stops by the CW (-) side limit sensor. Then it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses. After stop, it starts traveling in the CW (-)

After stop, it starts traveling in the CW (-) direction again at the starting speed (S), and stops by the CW (-) side limit sensor. After that, it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

This position is regarded as the machine origin.



■Compatible Controllers / Drivers and Cables



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□40mm

□60mm

□80mm □85mm

□100mm

□120mm



High Durability Motorized Rotation Stages

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□40mm □60mm

□80mm

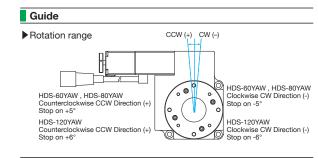
□85mm □100mm

□120mm

It is a small angle adjusting automatic rotation stages using in the alignments for a marker of semiconductor wafer.

- Good for the automatic alignment device which needs for adjusting the small angle of rotation by each sample.
- By using the ball screw system on the drive mechanism, it can reduce abrasion and backlash of parts which realized high
- Since it converted linear motion by the ball screw into rotational motion by the steel belt, there is no difference between traveling center and end by rotation speed and resolution.





Attention

▶ Please be mounted HDS series in horizontal. Can not be guaranteed the performance if used in reversion on the roof or vertically situation. If you would like a special mounting, please contact our sales department.

Specification	ons				
Part Number			HDS-60YAW	HDS-80YAW	HDS-120YAW
	Rotation Ra	ange	±5°	±5°	±6°
	Table Size [mm]	φ60	φ80	φ120
	Travel Mech	nanism	Ball screw with steel belt	Ball screw with steel belt	Ball screw with steel belt
Mechanical Specifications	Positioning	Slide	Bearing method	Bearing method	Crossed roller guide
opoomodiiono	Stage Mate	rial	Aluminum	Aluminum	Aluminum
	Finish		Black anodized	Black anodized	Black anodized
	Weight [kg]		0.5	0.9	1.4
	Decelution	(Full) [°/pulse]	≑0.00053	÷ 0.00038	≑ 0.00022
	Resolution	(Half) [°/pulse]	≑0.00027	≑ 0.00019	≑ 0.00011
	MAX Speed [°/sec]		60	60	60
	Positioning	Accuracy [°]	0.05	0.05	0.05
	Positional Repeatability [°]		0.003	0.003	0.003
Accuracy	Load Capacity [N]		29.4 (3.0kgf)	58.8 (3.0kgf)	98 (10kgf)
Specifications	Moment Stiffness ["/N·cm]		1	0.2	0.1
	Lost Motion [°]		0.003	0.003	0.003
	Backlash [°]]	0.05	0.05	0.05
	Parallelism	[µm]	50	50	50
	Concentrici	ty [µm]	10	10	10
	Wobble [mm]		0.01	0.01	0.01
	Sensor Part	t Number	Micro ph	noto sensor: GP1S097HCZ(Sharp Corp	poration)
0	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOS
Sensor	Origin Sens	or	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN
	Proximity O	rigin Sensor	None	None	None

Motor / Sensor Specifications					
Motor	Туре	5-phase stepping motor 0.66A/phase (Tamagawa Seiki Co., Ltd.)	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)		
	Motor Part Number	TS3664N4 (□24mm)	C9863-90215P (<u>28mm</u>)		
	Step Angle	0.72°			
	Power Voltage	DC5 - 24V±10%			
	Current Consumption	60mA or lower (20mA per sensor)			
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower			
	Output Logic	"When shaded: Output transistor OFF (no conduction): Limit sensor When shaded: Output transistor ON (conduction): Origin sensor"			

Compatible Driver / Controller				
Control Custom	Compatible Driver	SG-5M, SG-5MA, SG-55MA, SG-514MSC		
Control System	Compatible Controller	GSC-01, GIP-101, GSC-02, SHOT-702, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04		

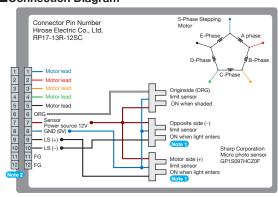




Outline Drawing HDS-80YAW Hexagon socket head cap screw M4×12...3 screws (142) (126)132 φ25 (+0.025) φ32 (+0.070) 90 (110.5) 0 0 4-M3 depth 5.5 4-M4 depth 5.5 P.C.D.50 30 4-M3 depth 5 119.5 4-M4 depth 5 P.C.D.62 4-M4 depth 5 40 φ60 88 φ80 4.5 28 **(** 6.5 3-φ4.5 mounting hole φ8 counterbore 3-φ4.5 mounting hole φ8.2 counterbore

(164)HDS-120YAW Hexagon socket head cap screw M6×12...3 screws 155 0 0 (161 8 29 (90 0 \oplus 4-M4 depth 6 4-M4 depth 6 100 P.C.D.100 60 130 φ120 3-φ6.5 mounting hole

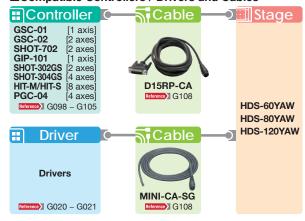
■Connection Diagram



Note 1 The motor side limit sensor is the (+) forward direction limit sensor.

Note 2 Compatible cable connector:
Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

■Compatible Controllers / Drivers and Cables



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□85mm □100mm



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□40mm

□60mm

□80mm

□85mm

□100mm □120mm

Others

High precision motorized goniometers with integrated bearing ways for superior stiffness, accuracy and durability.

Their smooth movement is ideal for frequent angle adjustment.



- Cost-effective motorized stages achieved by integrated structure in which guides are directly processed on the main body to reduce the number of parts and assembly time.
- Attachment pins (accessories) are ideal for positioning when assembling into $\alpha\beta$ axis or mounting on various instruments or devices.

Guide

- ▶ Contact our International Sales Division if you desire to assemble into an $\alpha\beta$ axis stage.
- ▶ Contact our International Sales Division if you desire a rotation center height not listed in the catalog.
- ▶ Manual type (GOHT-40) is also available. rence E168



GOHT-40

Part Number			OSMS-40A60	OSMS-40A75
(Opposite Mode	D		OSMS-40A60R	OSMS-40A75R
(- - -	Travel [°]		±5	±4
	Table Size	[mm]	40×40	40×40
Mechanical	Travel Mec		Worm gear (1: 332)	Worm gear (1: 406)
Specifications	Positioning	Slide	Extended Contact Ball Guide	Extended Contact Ball Guide
	Stage Mate	erial	SUS440C quench hardened	SUS440C quench hardened
	Finish		Super black chrome	Super black chrome
	Weight [kg]		0.4	0.4
	Stage Height [mm]		15	15
Size Tolerance	Rotation Center Height [mm]		60±0.1	75±0.1
	Rotation Center Deflection Accuracy [mm]		Within φ0.01	Within <i>φ</i> 0.01
	(Full) [°/pulse]		about 0.00217	about 0.00177
	Resolution	(Half) [°/pulse]	about 0.00108	about 0.00089
	MAX Speed [°/sec]		10	8.9
Accuracy Specifications	Positional Repeatability [°]		±0.004	±0.004
Оресписаного	Load Capacity [N]		19.6(2.0kgf)	19.6(2.0kgf)
	Moment Stiffness ["/N·cm]		Roll 0.6 Yaw 0.6	Roll 0.6 Yaw 0.6
	Lost Motion [°]		0.02	0.02
	Sensor Par	t Number	Micro photo sensor: GP1S092HCPII	F(Sharp Corporation): Limit Sensor
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sens	sor	None	None

Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number	PK523HPB-C12 (□28mm)			
	Step Angle	0.72°			
	Power Voltage	DC - 5V - +24V			
Sensor	Current Consumption	40mA or lower (20mA per sensor)			
Serisor	Control Output	NPN open collector output 50mA			
	Output Logic	When shaded: Output transistor OFF (no conduction)			

Compatible Driver / Controller				
Control Custom	Compatible Driver	SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL		
Control System	Compatible Controller	GSC-01, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04		





L 83 E

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φ4 H7

Outline Drawing Hexagon socket head cap screw M3×6...4 screws, Attachment pins Hexagon socket head cap screw M3×6...4 screws, Attachment pins OSMS-40A60 OSMS-40A60R (125.9) (125.9)78.3 40 78.3 (7.6) 40 (7.6) 6-M3depth 5 6-M3depth 5 M3depth 3 16 16 16 16 M3depth 3 M3depth 3 M3depth 3 ╟ 40 (51) (21) Ø Rotation center Rotation center M4depth 3 M4depth 3 8 8

4-φ3.5 mounting hole

φ6 counterbore

 ϕ 3.5 mounting hole

φ6 counterbore

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OSMS-40A75 Hexagon socket head cap screw M3×6...4 screws, Attachment pins (125.9) 78.3 (7.6)78.3 (7.6)40 6-M3depth 5 16 16 6-M3depth 5 16 16 M3depth 3 M3depth 3 M3depth 3 16 16 ₩ 유 (51) (51) 16 9 € B Rotation cente Rotation center M4depth 3 M4depth 3 75 # 1 (10) φ4 H7 32 4-φ3.5 mounting hole 4-φ3.5 mounting hole φ4 H7 32 32 φ6 counterbore φ6 counterbore

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□40mm

_40mm

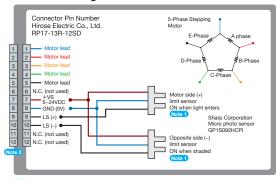
□ouiiiii □85mm

□100mm

□120mm

Others

■Connection Diagram



32

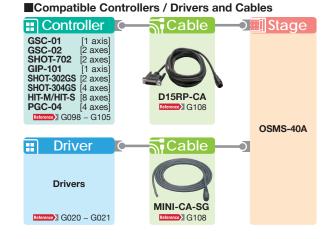
Note 1 The motor side limit sensor is the + direction limit sensor.

Motorized stages are not fitted with origin and proximity origin sensors.

Limit sensors are used as origin detection sensors.

Note 2 Compatible cable connector:

Compatible cable connector: Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122





Motorized Extended Guide Goniometer | OSMS-60A Stage size G0mm RoHS

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□40mm

□60mm

□80mm

□85mm □100mm

□120mm

Others

High precision motorized goniometers with integrated bearing ways for superior stiffness, accuracy and durability.

Their smooth movement is ideal for frequent angle adjustment.



- Cost-effective motorized stages achieved by integrated structure in which guides are directly processed on the main body to reduce the number of parts and assembly time.
- Attachment pins (accessories) are ideal for positioning when assembling into $\alpha\beta$ axis or mounting on various instruments or devices.

Guide

- ▶ Contact our International Sales Division if you desire to assemble into an $\alpha\beta$ axis stage.
- ▶ Manual type (GOHT-60) is also available. Reference E172



GOHT-60

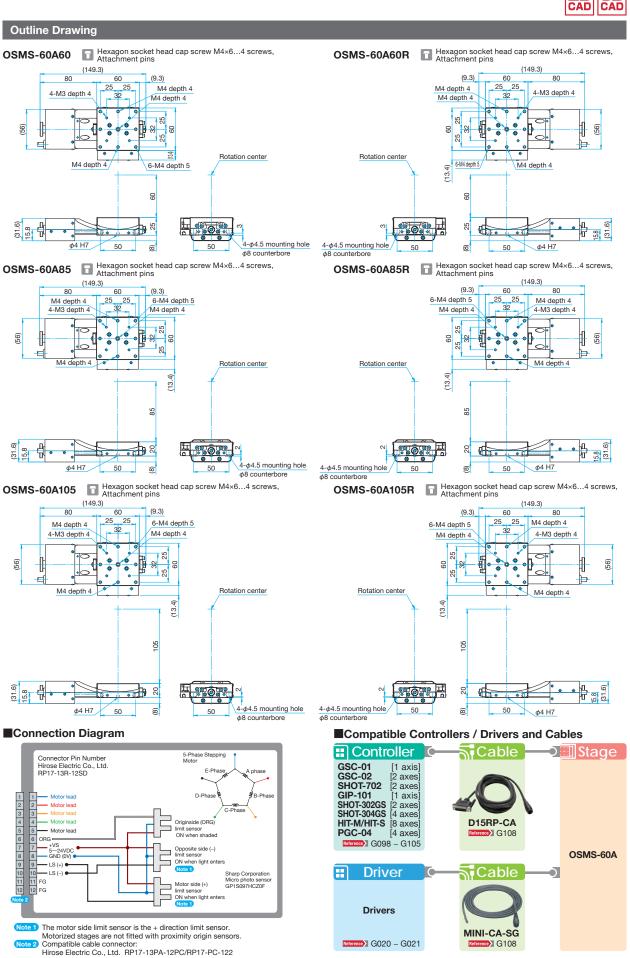
Specification	ons				
Part Number			OSMS-60A60	OSMS-60A85	OSMS-60A105
(Opposite Mode	l)		OSMS-60A60R OSMS-60A85R		OSMS-60A105R
	Travel [°]		±14	±9	±7
	Table Size [mm]	60×60	60×60	60×60
Mechanical	Travel Mech (reduction r		Worm gear (1: 246)	Worm gear (1: 314)	Worm gear (1: 380)
Specifications	Positioning	Slide	Extended Contact Ball Guide	Extended Contact Ball Guide	Extended Contact Ball Guide
	Stage Mate	erial	SUS440C quench hardened	SUS440C quench hardened	SUS440C quench hardened
	Finish		Super black chrome	Super black chrome	Super black chrome
	Weight [kg]		0.85	0.75	0.75
	Stage Height [mm]		25	20	20
Size Tolerance	Rotation Center Height [mm]		60±0.1	85±0.1	105±0.1
	Rotation Center Deflection Accuracy [mm]		Within ϕ 0.01	Within φ0.01	Within φ0.01
	Resolution	(Full) [°/pulse]	about 0.00293	about 0.00229	about 0.00198
		(Half) [°/pulse]	about 0.00146	about 0.00115	about 0.00095
	MAX Speed [°/sec]		10	8	6.6
Accuracy Specifications	Positional F	Repeatability [°]	±0.004	±0.004	±0.004
opeooa.iono	Load Capa	city [N]	29.4(3.0kgf)	29.4 (3.0kgf)	29.4 (3.0kgf)
	Moment St	iffness ["/N·cm]	Roll 0.3 Yaw 0.3	Roll 0.3 Yaw 0.3	Roll 0.3 Yaw 0.3
	Lost Motion	ı [°]	0.02 0.02		0.02
	Sensor Par	t Number	Micro photo sensor: GF	1S097HCZ0F(Sharp Corporation): Lin	mit Sensor, Origin Sensor
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sensor		Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)	Equipped (NORMAL OPEN)

Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number	PK523HPB-C12 (□28mm)			
	Step Angle	0.72°			
	Power Voltage	DC - 5V - +24V			
	Current Consumption	60mA or lower (20mA per sensor)			
Sensor	Control Output	NPN open collector output 50mA			
	Output Logic	When shaded: Output transistor OFF (no conduction): Limit sensor When shaded: Output transistor ON (conduction): Origin sensor			

Compatible Driver / Controller				
Cantral Custom	Compatible Driver	SG-5M, SG-5MA, SG-55MA, SG-514MSC, MC-7514PCL		
Control System	Compatible Controller	GSC-01, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04		







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□40mm

⊒60mm

80mm

85mm

□100mm □120mm

Others

G020 - G021



Motorized Goniometers - 5 Phase Stepping Motor

SGSP-A Stage size ☐60mm

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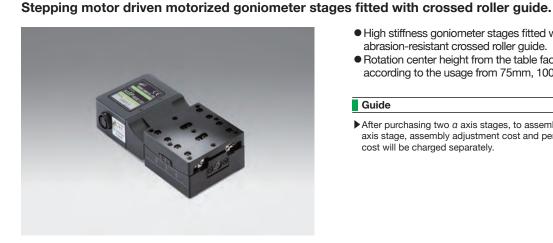
□40mm

□60mm **□80mm**

□85mm

□100mm □120mm

Others



- High stiffness goniometer stages fitted with excellent abrasion-resistant crossed roller guide.
- Rotation center height from the table face is selectable according to the usage from 75mm, 100mm or 130mm.

Guide

 \blacktriangleright After purchasing two α axis stages, to assemble them into an $\alpha\beta$ axis stage, assembly adjustment cost and performance inspection cost will be charged separately.

Specification	ons				
Part Number			SGSP-60A75	SGSP-60A100	SGSP-60A130
	Angle Range [°]		±7	±5	±4
	Table Size [mm]	60×60	60×60	60×60
	Positioning	Slide	Crossed roller guide	Crossed roller guide	Crossed roller guide
Mechanical Specifications	Travel Mech	nanism	Worm and worm wheel	Worm and worm wheel	Worm and worm wheel
,	Stage Mate	rial	Aluminum	Aluminum	Aluminum
	Finish		Black anodized	Black anodized	Black anodized
	Weight [kg]		0.65	0.55	0.65
	Stage Height [mm]		35	30	35
Size Tolerance	Rotation Center Height [mm]		75	100	130
	Rotation Center Deflection Accuracy [mm]		ϕ 0.05	ϕ 0.05	φ0.05
	Resolution	(Full) [°/pulse]	about 0.002	about 0.001	about 0.001
	Resolution	(Half) [°/pulse]	about 0.001	about 0.0005	about 0.0005
	MAX Speed [°/sec]		6	6	6
Accuracy Specifications	Positional Repeatability [°]		±0.004	±0.004	±0.004
	Load Capac	city [N]	24.5 (2.5kgf)	24.5 (2.5kgf)	24.5 (2.5kgf)
	Moment Sti	iffness ["/N·cm]	1	1	1
	Lost Motion [°]		0.02	0.02	0.02
	Sensor Part	t Number	Micro photo sensor: GP1S092HCPI(Sharp Corporation)		
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
erisor	Origin Sens	sor	None	None	None
	Proximity O	rigin Sensor	None	None	None

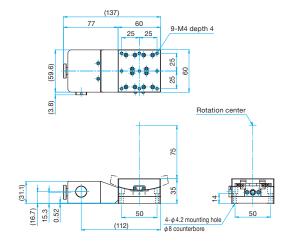
Motor / S	Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)				
Motor	Motor Part Number	C9863-90215P				
	Step Angle	0.72°				
	Power Voltage	DC5 - 24V				
Sensor	Current Consumption	40mA or lower (20mA per sensor)				
Sensor	Control Output	NPN open collector output 50mA				
	Output Logic	When shaded: Output transistor OFF (no conduction)				

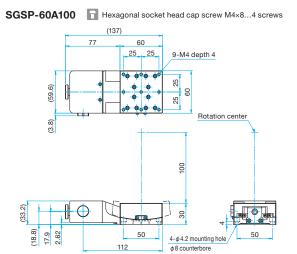
Compatible Driver / Controller				
Control Custom	Compatible Driver	SG-5M, SG-55M, SG-514MSC		
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S		

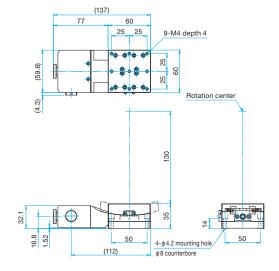




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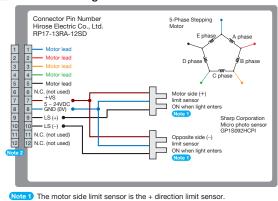
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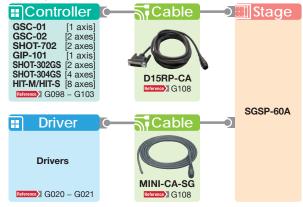
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■Connection Diagram



Compatible cable connector:
Hirose Electric Co., Ltd. PR17-13PA-12PC/RP17-PC-122

■Compatible Controllers / Drivers and Cables



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□40mm

⊒60mm

□80mm

□85mm

□100mm

□120mm



Motorized Goniometers - 5 Phase Stepping Motor

SGSP-B Stage size ☐60mm

RoHS

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□40mm

■60mm

□100mm

□120mm

Others

Stepping motor driven motorized goniometer stages fitted with crossed roller guide.



- Combination of two axes of excellent abrasion-resistant z stages enables flexible alignment.
- Rotation center height from the table face is selectable according to the usage from 75mm or 100mm.

Attention

Assembly was adjusted for precision of both α and β axis stages. Note that if you disassemble the two axes, they might not work normally and may require assembly readjustment by us.

Specifications						
Part Number				SGSP-60B75	SGSP-60B100	
	Angle Denge	A 1 B 101		β axis: ±7	β axis: ±5	
	Angle Range	; []	(Lower)	α axis: ±5	α axis: ±4	
	Table Size [r	nm]		60×60	60×60	
Mechanical	Positioning S	Slide		Crossed roller	Crossed roller	
Specifications	Travel Mech	anism		Worm and worm wheel	Worm and worm wheel	
	Stage Mater	ial		Aluminum	Aluminum	
	Finish			Black anodized	Black anodized	
	Weight [kg]			1.10 (2 axes)	1.20 (2 axes)	
	Stage Height [mm]			55	65	
Size Tolerance	Rotation Center Height [mm]		[mm]	75	100	
	Rotation Center Deflection Accuracy [mm]		n Accuracy [mm]	_	_	
	Resolution	(Full) [°/pulse]		α axis: about 0.001, β axis: about 0.002	α axis: about 0.001, β axis: about 0.001	
	Resolution	(Half) [°/pulse]		α axis: about 0.0005, β axis: about 0.001	α axis: about 0.0005, β axis: about 0.0005	
	MAX Speed [°/sec]			6	6	
Accuracy Specifications	Positional Repeatability [°]		/[°]	Within ±0.004	Within ±0.004	
opeooanone	Load Capac	Load Capacity [N]		19.1 (1.9kgf)	19.1 (1.9kgf)	
	Moment Stif	fness ["/N·	cm]	_	_	
	Lost Motion [°]			_	_	
	Sensor Part	Number		GP1S092HCPI (Sharp Corporation)		
Sensor	Limit Sensor			Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	
Sensor	Origin Senso	or		None	None	
	Proximity Or	igin Senso	r	None	None	

Motor / Sensor Specifications					
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number	C9863-90215P			
	Step Angle	0.72°			
	Power Voltage	DC5 – 24V			
Sensor	Current Consumption	40mA or lower (20mA per sensor)			
Selisoi	Control Output	NPN open collector output 50mA			
	Output Logic	When shaded: Output transistor OFF (no conduction)			

Configuration						
Part Number	SGSP-60B75	SGSP-60B100				
(Upper) β axis	SGSP-60A75	SGSP-60A100				
(Lower) α axis	SGSP-60A100	SGSP-60A130				

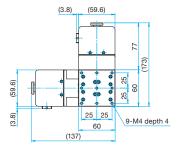
(Reference) Precision Specifications of Single Axis Stage							
Part Number SGSP-60A75 SGSP-60A100 SGSP-6							
Accuracy Specifications	Positional Repeatability [°]	±0.004	±0.004	±0.004			
	Moment Stiffness ["/N·cm]	1	1	1			
	Lost Motion [°]	0.02	0.02	0.02			

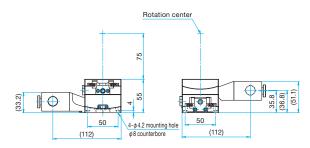
Compatible Driver / Controller					
Control System	Compatible Driver	SG-5M, SG-55M, SG-514MSC			
	Compatible Controller	GSC-01, GSC-02, SHOT-702, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S			

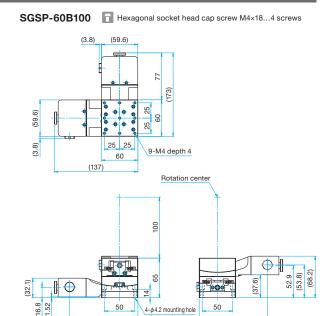




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□40mm

□60mm

□80mm

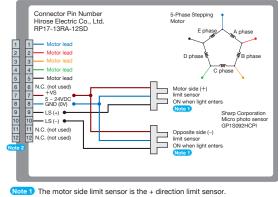
⊒85mm

□100mm

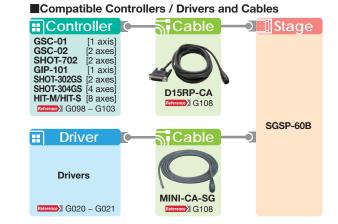
□120mm

Others

■Connection Diagram



Compatible cable connector:
 Hirose Electric Co., Ltd. PR17-13PA-12PC/RP17-PC-122



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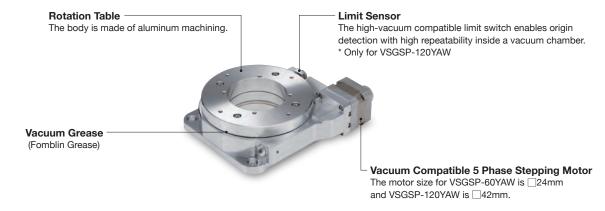
Vacuum Compatible Motorized Stage Guide VSGSP Guide

For use in vacuum environments, the vacuum compatible stage series offers replacement with a stainless steel or machined aluminum body as well as replacement with vacuum grease, and uses a vacuum rated motor and a contact type or mechanical driven type switch, and Teflon coated cables for signal wires.

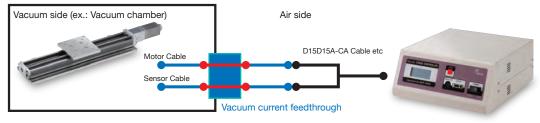
The series is suited for positioning in environments where the degree of vacuum is between 10⁻⁴ and 10⁻⁵Pa. For the vacuum characteristics, see the measurement data of outgas volume, degree of vacuum, and mass component ratio.

• In addition to the standard lineup, motor replacement, sensor replacement, special specifications such as vacuum compatible large mirror holders, and replacement of grease to vacuum grease for the guides or feed screws of standard specification stages to deal with low vacuum specifications are available. Contact our International Sales Division for more information.





[Attention] To use a vacuum compatible stage in a vacuum chamber, the connection cables between the vacuum side and the atmosphere side need to be relayed using a vacuum current feedthrough or the like. Prepare the feedthrough according to the vacuum chamber specifications.

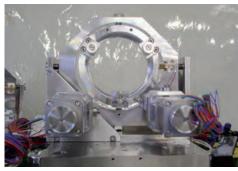


80°C.

▶ Because heat dissipation generally deteriorates in vacuum, specification temperature conditions are stricter than those for

atmosphere. Check the usage conditions such as stage operation

to make sure that the motor case temperature does not exceed



[Example of Special Order] Vacuum Compatible Large Mirror Holder

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□40mm

□80mm

□85mm

□100mm

□120mm

Emitted amount of gas

Part Number	Emitted Amount of Gas Q (after 40 minutes of emission)		
	(Torr∙ℓ/s/unit)	(Pa·ℓ/s/unit)	
VSGSP26-200	4.77×10 ⁻⁴	6.36×10 ⁻²	
VSGSP-60	6.75×10 ⁻⁵	9.00×10 ⁻³	
VSGSP-120YAW	4.78×10 ⁻⁴	6.37×10 ⁻²	

Evaluation and Device Specifications

Exhaust system: Turbo-Molecular Pump STP-301

Seiyu Instruments Inc. (Now Edwards Japan Limited)

Pumping speed: 300 l/sec

Mass spectroscope: Quad Mass Spectrometer QME200

Pfeiffer Vacuum Mass range: 1 - 200amu

Emitted amount of gas is found by the following equation:

$$Q = \frac{(P - P') \times V}{t \times N}$$

P: Vacuum immediately after seal off

Vacuum after seal-off time has elapsed

N: Number of stage units (1unit)

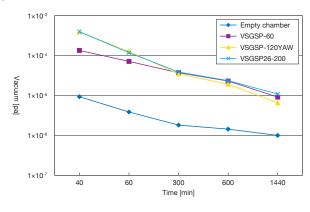
Vacuum chamber volume (ℓ)

Seal-off time (600s)

From the measurement results of gas volume discharged from a vacuum compatible motorized stage

The main components of outgas are water and nitrogen. This is because the gas was caused by residual air on the stage surface, and grease used for drive components is considered to have little impact on the amount of gas.

Vacuum of Vacuum Chamber



Mass Component Ratio

Mass	Com	ponent Ratio	o [%]	lon	Gas Molecule	
Number	VSGSP-60	VSGSP26-200	VSGSP-120YAW	1011	Gas Molecule	
1	19.58	19.96	17.90	H+	H ₂ , water vapor, hydrocarbon	
2	2.81	5.28	3.34	H ₂ ⁺	H ₂ , water vapor, hydrocarbon	
12	0.60	0.85	0.79	C+	CO, CO2, hydrocarbon	
13	0.17	-	ı	CH+	Hydrocarbon	
14	0.79	1.26	0.91	N ⁺ , CO ²⁺ , CH ₂ ⁺	N2, NH3, CO, hydrocarbon	
15	_	2.37	_	CH₃+, NH+	Hydrocarbon, NH₃	
16	3.03	-	2.98	O+, CH ₄ +, NH ₂ +	O2, CH4, NH3	
17	15.77	_	14.48	OH ⁺ , NH₃ ⁺	H₂O, NH₃	
18	48.02	17.30	43.89	H₂O ⁺	H₂O	
20	0.22	_	0.29	HF+, Ar2+	HF, Ar	
26	0.33	-	0.53	C ₂ H ₂ ⁺	Hydrocarbon	
27	0.83	4.53	1.52	C ₂ H ₃ ⁺	Hydrocarbon	
28	2.17	2.49	2.76	CO+, N ₂ +, C ₂ H ₄ +	CO, CO ₂ , N ₂ , hydrocarbon	
29	0.73	6.08	1.44	C₂H₅ ⁺	Hydrocarbon	
30	0.08	-	-	C ₂ H ₆ +, NO+	C ₂ H ₆ , NO	
31	0.14	0.31	0.27	C ₂ H ₂ OH ⁺	C ₂ H ₃ OH	
32	0.26	_	0.27	O ²⁺ , S ⁺	O2, H2S, SO2	
39	0.39	2.57	0.78	C ₃ H ₃ +	Hydrocarbon	
41	0.51	7.44	1.07	C₃H₅+	Hydrocarbon	
42	ı	_	0.41	C₃H ₆ ⁺	Hydrocarbon	
43	0.74	8.00	1.01	C₃H₅ ⁺	Hydrocarbon	
44	0.40	-	0.66	$C_3H_8{}^+,CO_2{}^+,N_2O^+,C_2H_4OH^+$	C3H8, CO2, N2O, C2H4OH	
45	ı	0.31	0.31	C ₂ H ₅ O ⁺	C₂H₅OH	
50	_	0.23	-	C ₄ H ₂ ⁺	Hydrocarbon	

Data

●Interpretation of Mass Peak

The following list shows major gases that appear for each mass number when mass peaks (mass spectra) of residual gas are measured, and their interpretations.

List of Residual Gas Spectra

Mass Number	lon	Remarks	Mass Number	lon	Remarks
1	H ⁺	H ₂ , H ₂ O, hydrocarbons, etc	30	NO ⁺	Appears immediately after emission of dirty vacuum system.
2	H ₂ ⁺	H ₂ , H ₂ O, hydrocarbons, etc	31	CH₃O ⁺	Alcohol
3	HD ⁺	Abundance ratio of D is about 0.01%.	32	O ₂ ⁺	Becomes N_{23} : $O_{32} = 4$: 1 when air leak occurs.
4	He ⁺		35	CI ⁺	
12	C ⁺	CO, CO ₂ , hydrocarbons	37	CI ⁺	Clas : Clar = 3 : 1
14	N ⁺ , CH ₂ ⁺ , CO ₂ ⁺	N ₂ , CO ₂ , hydrocarbons	39	K ⁺ , C ₃ H ₃ ⁺	K ⁺ dissociates from filament.
15	CH ₃ ⁺	Molecule that has CH ₄ , CH ₃	40	Ar ⁺ , C ₃ H ₄ ⁺	Ar makes up 1% of the atmosphere.
16	C ⁺ , CH ₄ ⁺	O ₂ , CH ₄ , oxygen compounds	41	C ₃ H ₅ ⁺	Hydrocarbon
17	OH ⁺	H ₂ O	42	C3H6 ⁺	Hydrocarbon
18	H ₂ O ⁺	H ₂ O, OH ⁺ : H ₂ O ₊ ≒ 1 : 5	43	C ₃ H ₇ ⁺	Hydrocarbon
19	F ⁺	Sometimes adsorbed to filaments and electrode surface.	44	CO ₂ ⁺	
20	Ar ⁺ , H ₂ O ⁺ , Ne ⁺	H ₂ O(20) is present about 0.2% of abundance ratio of O ₁₅ .	50	C ₄ H ₂ ⁺	Hydrocarbon
22	CO2 ²⁺ , Ne ⁺	Abundance ratio of NE22 is 8.8%.	51	C ₄ H ₃ ⁺	Hydrocarbon
23	Na ⁺	Sometimes adsorbed to filaments and electrode surface.	55	C ₄ H ₇ ⁺	Hydrocarbon
27	C ₂ H ₃ ⁺	Hydrocarbon	56	C ₄ H ₈ ⁺	Hydrocarbon
28	N ₂ ⁺ , CO ⁺	Remain till the last.	57	C ₄ H ₉ ⁺	Hydrocarbon
29	C ₂ H ₅ ⁺ , N ₂ ⁺ , CO ⁺	Abundance ratio of N ₁₅ is 0.7%, and that of C ₁₃ is 1.1%.			

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□40mm □60mm

□80mm □85mm

□100mm □120mm



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Vacuum Applications Miniature Motorized Stages

VSGSP-60

Compact motorized stages used for experiments and inside a chamber of measuring instrument. Compact slim body is effective for space-saving.



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▶ Fitted with 1m teflon coated cable to directly connect the vacuum motor or vacuum limit switch to the connector of chamber.

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□40mm

□60mm

□80mm

□100mm

□120mm

Part Number			VSGSP-60(X)	VSGSP-60(XY)	VSGSP-60(Z)
	Travel [mm]		20	20	20
	Table Size [mm]	55×60	55×60	55×60
Mechanical	Feed Screw	1	Precision ground screw ϕ 4mm, 0.5mm lead	Precision ground screw φ4mm, 0.5mm lead	Precision ground screw φ4mm 0.5mm lead
Specifications	Positioning	Slide	Crossed roller guide	Crossed roller guide	Crossed roller guide
	Stage Material		Aluminum	Aluminum	Aluminum
	Finish		None	None	None
	Weight [kg]		0.55	1.1	0.6
	Resolution	(Full) [µm]	1	1	1
		(Half) [µm]	0.5	0.5	0.5
Accuracy	MAX Speed [mm/sec]		5	5	-
Specifications	Positional F	Repeatability [µm]	6	6	6
	Load Capac	city [N]	29.4 (3.0kgf)	19.6 (2.0kgf)	14.7 (1.5kgf)
	Lost Motion [µm]		5	5	5
	Туре		Vacuum limit switch	Vacuum limit switch	Vacuum limit switch
	Limit Senso	or	Contact type	Contact type	Contact type
Sensor	Origin Sens	sor	None	None	None
	Proximity O	rigin Sensor	None	None	None

Motor / Sensor Specifications						
	Туре	Vacuum compatible 5-phase stepping motor 0.66A/phase (Tamagawa Seiki Co., Ltd.)				
Motor	Motor Part Number	TS3664N5 (□24mm)				
	Step Angle	0.72°				
Sensor	Control Output	Contact type	Contact type	Contact type		
	Output Logic	NORMAL OPEN	NORMAL OPEN	NORMAL OPEN		

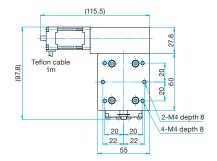
Compatible Driver / Controller					
Control Custom	Compatible Driver	SG-5M, SG-55M, SG-514MSC, MC-7514PCL			
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04			

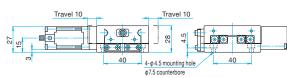


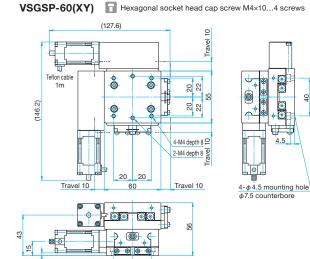


Outline Drawing

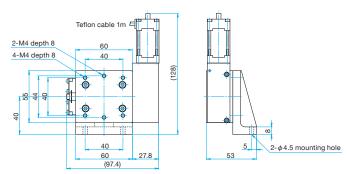
VSGSP-60(X) Hexagonal socket head cap screw M4×10...4 screws



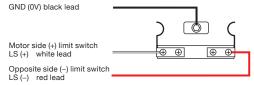








■Vacuum Limit Switch



* Use the motor side and opposite side limit switches as normal open.

■Wiring of Vacuum Stages

diagrams of driver or cable as follows.

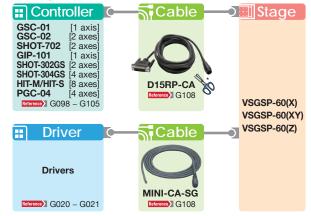
The vacuum compatible stepping motor TS3664N5 used for vacuum stages has five bare lead wires. For wiring, they correspond to the motor lead colors shown in the wiring

(The motor leads shown in the connection diagrams of driver or cable indicate

wiring of stepping motors used for normal stages.)

		Vacuum stage motor lead color	Motor lead color shown in driver or cable connection diagram
O	1	Blue	Blue
Corresponding	2	Red	Red
orrespondi connection	3	Red White	Orange
tion	4	Yellow	Green
DG.	5	Black	Black
		Vacuum compatible stage motor connection diagram Blue E phase Black A phase Red D phase C phase Red White	5-phase stepping motor connection diagram Blue Blue A phase D phase C

■Compatible Controllers / Drivers and Cables



^{*} Make the cable into bare wire specification after purchase.

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□40mm □60mm

⊒80mm

□85mm

□100mm

□120mm



Vacuum Compatible Motorized Stages | VSGSP-(X)

Motorized stages fitted with a limit sensor compatible with vacuum environments.

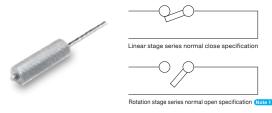
• Linear system has a long travel between 35 - 200mm, and is as compact as the conventional SGSP series.



Guide

▶ Motor cables and sensor cables are 1m bare wires.

■Limit Sensor (high vacuum compatible switch)



Set the controller of vacuum compatible motorized rotation stages to normal open.

Specification	ons				
Part Number		VSGSP20-35(X)	VSGSP20-85(X)	VSGSP26-200(X)	
	Travel [mm]		35	85	200
	Table Size [mm]	60×60	60×60	80×80
Mechanical	Feed Screv	V	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ6mm, 1mm lead	Ball screw diameter φ8mm, 2mm lead
Specifications	Positioning	Slide	Outer rail structure	Outer rail structure	Outer rail structure
	Stage Mate	erial	Aluminum / Stainless steel	Aluminum / Stainless steel	Aluminum / Stainless steel
	Finish		None	None	None
	Weight [kg]		1.0	1.1	2.5
	Resolution	(Full) [µm]	2	2	4
		(Half) [µm]	1	1	2
Accuracy	MAX Speed [mm/sec]		10	10	20
Specifications	Positional Repeatability [µm]		5	5	10
	Load Capacity [N]		39.2(4.0kgf)	39.2(4.0kgf)	58.8(6.0kgf)
	Lost Motion [µm]		3	3	10
	Sensor Par	t Number	GN-PT5M3B-1 (Metrol Co., Ltd.)	GN-PT5M3B-1 (Metrol Co., Ltd.)	GN-PT5M3B-1 (Metrol Co., Ltd.)
Sensor	Limit Sensor		Vacuum touch sensor (NORMAL CLOSE)	Vacuum touch sensor (NORMAL CLOSE)	Vacuum touch sensor (NORMAL CLOSE)
	Origin Sens	sor	None	None	None
	Proximity C	rigin Sensor	None	None	None

Motor / Sensor Specifications					
	Туре	Vacuum compatible 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)			
Motor	Motor Part Number	A7298-90215KV (□28mm)	A7298-90215KV (□28mm)	A7298-90215KV (□28mm)	
	Step Angle	0.72°			
	Power Voltage	DC5-24V			
Sensor	Current Consumption	10mA(Max 20mA)			
Sensor	Control Output	Mechanical			
	Output Logic	NORMAL CLOSE	NORMAL CLOSE	NORMAL CLOSE	

Compatible Driver / Controller			
Control System	Compatible Driver	SG-5M, SG-55M, SG-514MSC, MC-7514PCL	
	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04	

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□40mm

□60mm **□80mm**

□85mm □100mm

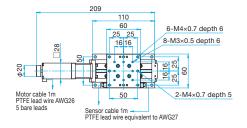
□120mm

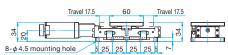


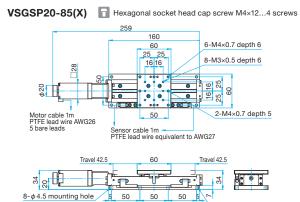
8-φ4.5

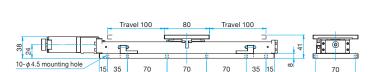
Outline Drawing

VSGSP20-35(X) Hexagonal socket head cap screw M4×12...4 screws





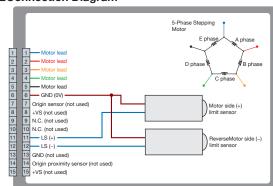




Sensor cable 1m PTFE lead wire equivalent to AWG27 © (12) (8)

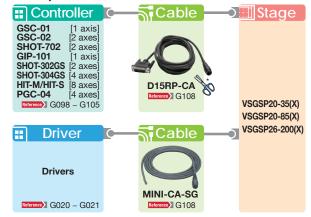
■Connection Diagram

PTFE lead wire AWG26 5 bare leads



* Motor cables and sensor cables are bare wires.

■Compatible Controllers / Drivers and Cables



^{*} Make the cable into bare wire specification after purchase.

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□40mm

⊒60mm ⊒80mm

85mm

□100mm

□120mm

of inspection equipment.



Vacuum Compatible Rotation Motorized Stage | VSGSP-YAW

The ϕ 60mm compact type is space saving, and best suited for experiments and use in chambers

The \$\phi\$120mm type is equipped with a limit sensor compatible with vacuum environments. It is thin

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□80mm

□85mm

□100mm □120mm

Others

Rotation motorized stages for vacuum environment.

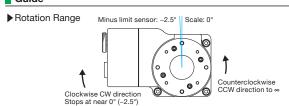
but has high load capacity because of its ☐42mm large motor.

Guide

▶ Motor cables and sensor cables are 1m bare wires.



Guide



- ▶ Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- ▶ Origin detection is adjusted so that the stage stops at 0 degrees when homing is performed in the MINI system at half step.

Specification	ons			
Part Number			VSGSP-60YAW	VSGSP-120YAW
	Rotation Range		In the CW or CCW direction to ∞	Counterclockwise CCW direction to ∞, Clockwise CW direction stops at near 0 degree (–2.5°)
	Table Size [mm]	φ60	φ120
Mechanical	Feed Screw	1	Worm and worm wheel	Worm and worm wheel
Specifications	Positioning	Slide	Bearing	Crossed roller
	Stage Material		Aluminum	Aluminum / Stainless steel
	Finish		None	None
	Weight [kg]		0.45	1.7
	Resolution	(Full) [°]	0.005	0.005
		(Half) [°]	0.0025	0.0025
Accuracy	MAX Speed [°/sec]		20	20
Specifications	Positional Repeatability [°]		0.02	0.02
	Load Capacity [N]		29.4 (3.0kgf)	98.0 (10.0kgf)
	Lost Motion [°]		0.05	0.05
	Туре		None	GN-STM35A-1 (Metrol Co., Ltd.)
0	Limit Sensor		None	Vacuum touch sensor (NORMAL OPEN)
Sensor	Origin Sens	or	None	None
	Proximity Origin Sensor		None	None

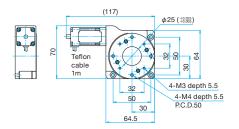
Motor / Sensor Specifications				
Motor	Туре	Vacuum compatible 5-phase stepping motor 0.66A/phase (Tamagawa Seiki Co., Ltd.)	Vacuum compatible 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)	
	Motor Part Number	TS3664N5 (□24mm)	PK543V-NB (<u></u> 42mm)	
	Step Angle	0.72°	0.72°	
	Control Output	_	DC5-24V	
0	Output Logic	_	Current Consumption 10mA(Max 20mA)	
Sensor	Control Output	Contact type	Mechanical	
	Output Logic	NORMAL OPEN	NORMAL OPEN	

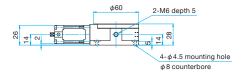
Compatible Driver / Controller			
0 1 10 1	Compatible Driver	SG-5M, SG-55M, SG-514MSC, MC-7514PCL	
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04	

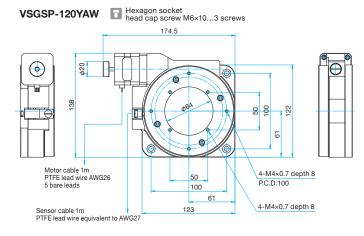


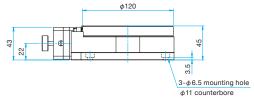


Outline Drawing









■Wiring of Vacuum Stages

The vacuum compatible stepping motor TS3664N5 used for vacuum stages has five bare lead wires.

For wiring, they correspond to the motor lead colors shown in the wiring

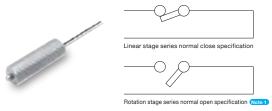
For wiring, they correspond to the motor lead colors shown in the wiring diagrams of driver or cable as follows.

(The motor leads shown in the connection diagrams of driver or cable indicate

wiring of stepping motors used for normal stages.)

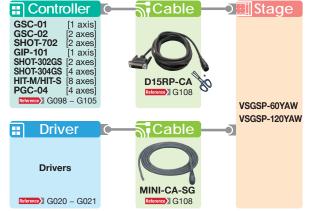
		Vacuum stage motor lead color	Motor lead color shown in driver or cable connection diagram
Ω	1	Blue	Blue
connection	2	Red	Red
spo	3	Red White	Orange
ondir	4	Yellow	Green
βľ	5	Black	Black
		Vacuum compatible stage motor connection diagram Ephase Black A phase D phase B phase	5-phase stepping motor connection diagram (SGSP series) E phase E phase A phase D phase B phase

■Limit Sensor (high vacuum compatible switch)



Note 1 Set the controller of vacuum compatible motorized rotation stages to normal open.

■Compatible Controllers / Drivers and Cables



* Make the cable into bare wire specification after purchase.

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□40mm □60mm

⊒85mm

□100mm

□100mm



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Single axis Stage Controller | GSC-01





A single axis stage controller with built-in 5-phase stepping motor driver.

• External control with RS232C interface, operation with a jog switch on the front panel, and jog operation with external I/O are available.



Guide

- ▶ Sample programs are available for download from our website.
 - SGCommander 32/64-bit version for Windows® (only for RS232C)
 - LabVIEW for RS232C (for v.5.1/v.6i/v7.1/v.8.6/v.2012)

Attention

▶ Power supply is DC+24V 2A. You need to purchase the PAT-001-POW1 (AC adapter) or prepare an adapter separately

Part Name	Part Number
Single axis Stage Controller	GSC-01
AC Adapter	PAT-001-POW1

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■Primary Functions

Controller Function	
Controller Function	0
Number of Control Axes	1
Stored Program Control	_
Feedback Control	_
Circular Interpolation Control	_
Linear Interpolation Control	_
Driver Function	Standard
Micro-step (Max. Division)	2
Driving Current (A/phase)	0.2 – 0.8

■General Specifications

Power Voltage	DC24V 2A
Power Consumption	48VA
Operating Temperature	5 – 40°C
Storage Temperature	_
Ambient Humidity	20 – 80%RH
External Dimensions (W×H×Dmm)	47×125×90
Weight (kg)	0.4

■Interface

GP-IB	_
RS232C	0
USB	_
Ethernet	_

■Performance Specifications

Coordinate Indication Range	_
Max. Travel to Set	16,777,215
Max. Driving Speed (pps)	20,000
Min. Driving Speed (pps)	100
Acceleration/Deceleration Time (ms)	0 – 1,000

I/O Specification

Origin Sensor	_
Proximity Sensor	_
CW (+) Limit	0
CCW (-) Limit	0
General Purpose Input	4 points
General Purpose Output	4 points
Control Input	3 points
Control Output	_
Trigger Output	_
33	

■Control Command

Machine Origin Return	0
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	0
Jog Operation	0
Position Appointment	ı
Circular Interpolation Control	_
Linear Interpolation Control	_
Drive	0
Deceleration Stop	0
Emergency Stop	0
Speed Setting	0
Motor Free/Hold	0
Port Input	0
Port Output	0
Origin Offset Setting	0
Jog Operation Speed Setting	0

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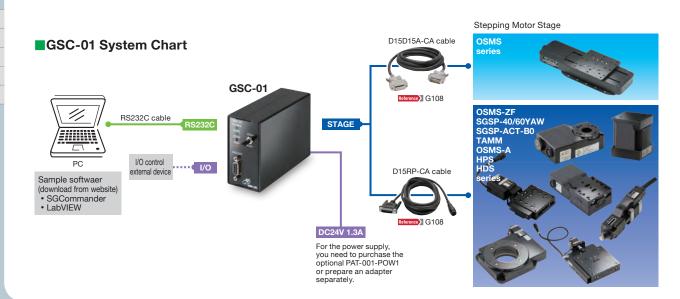
□40mm

□60mm

□80mm

□85mm □100mm

□120mm





A 2 axis stage controller with built-in 5-phase stepping motor driver.

External control with RS232C interface, manual operation and programmed operation with a dedicated controller (SJT-02).



Guide

- ▶ Sample programs are available for download from our website.
- SGCommander 32/64-bit version for Windows® (only for RS232C)
- LabVIEW for RS232C (for v.5.1/v.6i/v7.1/v.8.6/v.2010/v.2012)

Attention

▶ Power supply is DC+24V 2A.

You need to purchase the PAT-001-POW1 (AC adapter) or prepare an adapter separately

Part Name	Part Number
2 axis Stage Controller	GSC-02
Joystick Terminal	SJT-02
AC Adapter	PAT-001-POW1

■Primary Functions

Controller Function	0
Number of Control Axes	2
Stored Program Control	Δ
Feedback Control	_
Circular Interpolation Control	_
Linear Interpolation Control	_
Driver Function	Standard
Micro-step (Max. Division)	2 (half step only)
Driving Current (A/phase)	0.3 – 0.8

△...Programs can be controlled using SJT-02.

■General Specifications

Power Voltage	DC24V 2A
Power Consumption	48VA
Operating Temperature	5 – 40°C
Storage Temperature	−20 − 60°C
Ambient Humidity	20 – 80%RH
External Dimensions (W×H×Dmm)	180×40×125
Weight (kg)	0.7

■Interface

GP-IB	_
RS232C	0
USB	_
Ethernet	_

■Optional

CJ-200A	_
JS-300	_
JB-400	_
SJT-02	0

■Performance Specifications

Coordinate Indication Range	_
Max. Travel to Set	16,777,214
Max. Driving Speed (pps)	20,000
Min. Driving Speed (pps)	1
Acceleration/Deceleration Time (ms)	0 – 1,000

■I/O Specification

Origin Sensor	0
Proximity Sensor	0
CW (+) Limit	0
CCW (-) Limit	0
General Purpose Input	_
General Purpose Output	_
Control Input	_
Control Output	_
Trigger Output	_

■Control Command

Ö	
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	_
Jog Operation	0
Position Appointment	_
Circular Interpolation Control	_
Linear Interpolation Control	_
Drive	0
Deceleration Stop	0
Emergency Stop	0
Speed Setting	0
Motor Free/Hold	0
Port Input	_
Port Output	_
Jog Operation Position Appointment Circular Interpolation Control Linear Interpolation Control Drive Deceleration Stop Emergency Stop Speed Setting Motor Free/Hold Port Input	- 0 - - 0 0 0

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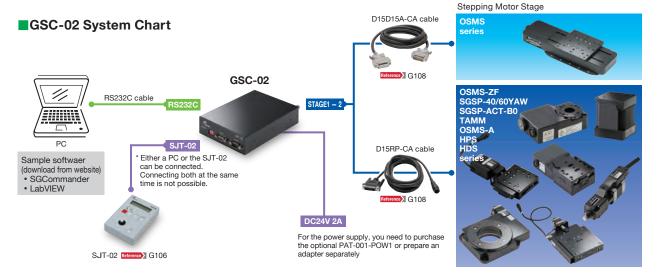
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□40mm

□60mm

□80mm

□85mm □100mm

□120mm

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2 axis Stage Controller SHOT-702





A 2 axis stage controller with built-in micro-step driver.

• External control with RS232C interface and manual operation with dedicated controllers (JS-300, JB-400).



Guide

- ▶ Sample programs are available for download from our website.
 - SGCommander 32/64-bit version for Windows® (only for RS232C)
 - LabVIEW for RS232C (for v.5.1/v.6i/v7.1/v.8.6/v.2010/v.2012)

Part Name	Part Number
2 axis Stage Controller	SHOT-702
Joy Stick	JS-300
Jog Operation Box	JB-400
Jog Dial	JD-100
MDR Cable	MDR14-CA-2.5

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■Primary Functions

Controller Function	0
Number of Control Axes	2
Stored Program Control	_
Feedback Control	_
Circular Interpolation Control	_
Linear Interpolation Control	_
Driver Function	Micro-step
Micro-step (Max. Division)	250
Driving Current (A/phase)	0.1 – 1.1

■General Specifications

AC100 – 240V 50/60Hz
50VA
5 – 40°C
−20 − 60°C
20 – 80%RH
260×70×280
2.8

■Interface

GP-IB	_
RS232C	0
USB	_
Ethernet	_

■Optional

CJ-200A	_
JS-300	0
JB-400	0
JD-100	0
SJT-02	_

■Performance Specifications

_
268,435,455
500,000
1
1 – 1,000

I/O Specification

Origin Sensor	0
Proximity Sensor	0
CW (+) Limit	0
CCW (-) Limit	0
General Purpose Input	1 point
General Purpose Output	1 point
Control Input	1 point
Control Output	1 point
Trigger Output	_

■Control Command

Stepping Motor Stage

Machine Origin Return	0
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	0
Jog Operation	0
Position Appointment	_
Circular Interpolation Control	_
Linear Interpolation Control	_
Drive	
Drive	
Deceleration Stop	0
	0
Deceleration Stop	0 0
Deceleration Stop Emergency Stop	0 0 0
Deceleration Stop Emergency Stop Speed Setting	0 0 0

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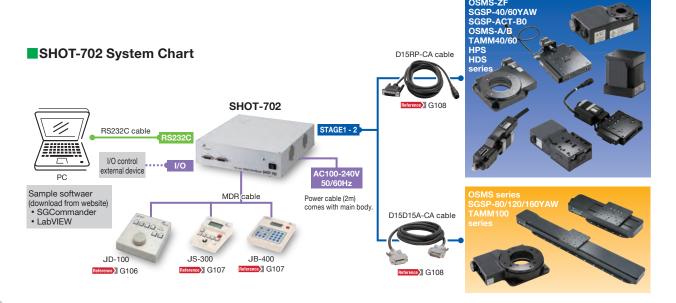
□40mm

□60mm

□80mm □85mm

□100mm

□120mm





A single axis controller with built-in micro-step driver having a 5-point preset function.

 Compatible with objective lens turrets and other LASER accessory units in addition to motorized stages fitted with 5-phase stepping motor.



Guide

- Sample programs are available for download from our website.
 - SGCommander 32/64-bit version for Windows® (only for RS232C)
 - LabVIEW for RS232C (for v.5.1/v.6i/v7.1/v.8.6/v.2010/v.2012)

Part Name	Part Number
Intelligent Positioning System	GIP-101

■Primary Functions

Controller Function	0
Number of Control Axes	1
Stored Program Control	_
Feedback Control	_
Circular Interpolation Control	_
Linear Interpolation Control	_
Driver Function	Micro-step
Micro-step (Max. Division)	250
Driving Current (A/phase)	0.23 - 0.75

■General Specifications

Power Voltage	AC100 - 240V 50/60Hz
Power Consumption	100VA
Operating Temperature	0 – 40°C
Storage Temperature	_
Ambient Humidity	20 – 80%RH
External Dimensions (W×H×Dmm)	145×205×81
Weight (kg)	2

■Interface

GP-IB	_
RS232C	0
USB	_
Ethernet	_

■Performance Specifications

Coordinate Indication Range	_
Max. Travel to Set	16,777,214
Max. Driving Speed (pps)	22,000
Min. Driving Speed (pps)	50
Acceleration/Deceleration Time (ms)	20 – 1,000 16 steps

■I/O Specification

Origin Sensor	0
Proximity Sensor	0
CW (+) Limit	0
CCW (-) Limit	0
General Purpose Input	_
General Purpose Output	_
Control Input	6 points
Control Output	1 point
Trigger Output	_

■Control Command

Machine Origin Return	0
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	0
Jog Operation	0
Position Appointment	0
Circular Interpolation Control	_
Linear Interpolation Control	_
Drive	0
Deceleration Stop	0
Emergency Stop	0
Speed Setting	0
Motor Free/Hold	0
Port Input	0
Port Output	0

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Options

□40mm

□60mm

□80mm □85mm

□100mm

□100mm



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2 axis / 4 axis Stage Controllers

SHOT-GS





2 axis and 4 axis stage controllers with built-in micro-step driver.

• External control with RS232C/GP-IB/USB interfaces, manual operation with a control pad (CJ-200A) or dedicated controllers (JS-300, JB-400, JD-100), and automatic control with two banks of stored programs are available.

• Full closed loop control is possible when used in combination with a stage with built in glass-scale.



Guide

- ▶ Sample programs are available for download from our website.
 - SGCommander 32/64-bit version for Windows® (only for RS232C)
 - LabVIEW for RS232C (for v.5.1/v.6i/v7.1/v.8.6/v.2010/v.2012)
 - LabVIEW for GP-IB (for v.5.1/v.6i/v7.1/v.8.6/v.2010/v.2012)

Part Name	Part Number
2 axis Stage Controller	SHOT-302GS
4 axis Stage Controller	SHOT-304GS
Control Pad	CJ-200A
Joy Stick	JS-300
Jog Operation Box	JB-400
Jog Dial	JD-100
MDR Cable	MDR14-CA-2.5

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Options

□40mm **□60mm □80mm**

□85mm

□100mm

□120mm

Others

Piezo

■Primary I	Functions
------------	-----------

Part Number	SHOT-302GS	SHOT-304GS
Controller Function	Ö	
Number of Control Axes	2	4
Stored Program Control	Ö	
Feedback Control	GS	
Circular Interpolation Control	0	
Linear Interpolation Control	2 axes	
Driver Function	Micro-step	
Micro-step (Max. Division)	250	
Driving Current (A/phase)	0.25 – 1.4	
CJ-200A	Required	

■General Specifications

Power Voltage	AC100 - 240V 50/60Hz	
Power Consumption	160VA 300VA	
Operating Temperature	5 – 40°C	
Storage Temperature	-20 - 60°C	
Ambient Humidity	20 – 80%RH	
External Dimensions (W×H×Dmm)	270×302×118	
Weight (kg)	5.5	6.5

■Interface

GP-IB	0
RS232C	0
USB	0
Ethernet	_

■Optional

CJ-200A	0
JS-300	0
JB-400	0
JD-100	0
SJT-02	_

■Performance Specifications

Coordinate Indication Range	±999,999,999
Max. Travel to Set	268,435,455
Max. Driving Speed (pps)	500,000
Min. Driving Speed (pps)	1
Acceleration/Deceleration Time (ms)	0 - 1,000

■I/O Specification

Origin Sensor	0		
Proximity Sensor	0		
CW (+) Limit	0		
CCW (-) Limit	0		
General Purpose Input	4 points		
General Purpose Output	4 points		
Control Input	15 points		
Control Output	5 points		
Trigger Output	0		

D15RA-CA cable

M G108

№ G108

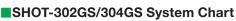
M G108

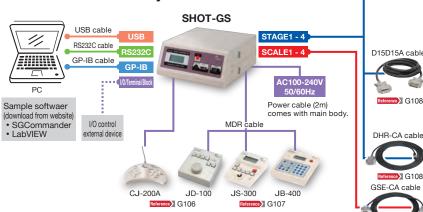
■Control Command

Machine Origin Return	0
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	0
Jog Operation	0
Position Appointment	_
Circular Interpolation Control	0
Linear Interpolation Control	0
Drive	0
Deceleration Stop	0
Emergency Stop	0
Speed Setting	0
Motor Free/Hold	0
Port Input	0
Port Output	0

Stepping Motor Stage















Stage control system with Master controller and from one to eight slave Axes.

- Control with RS232C/USB/Ethernet interfaces is available.
- Full closed loop control is possible when used in combination with a stage with built in glass-scale.



Guide

- ▶ Sample programs are available for download from our website.
 - HIT sample
 - SGCommander 32-bit version for Windows® (only for RS232C)
 - SGCommander 32/64-bit version for Windows® (only for RS232C)
 - LabVIEW for RS232C (for v.5.1/v.6i/v7.1/v.8.6/v.2010/v.2012)

Attention

▶ Power supply is DC+24V 1A. Depending on the number of stage axes, rated current of 2A (single axis) to 9A (8 axes) is required. You need to purchase the PAT-001-POW1 (AC adapter) or prepare an adapter separately.

■Primary Functions

Part Number	HIT-M	HIT-S
Controller Function	0	_
Number of Control Axes	8	_
Stored Program Control	0	_
Feedback Control	GS	_
Circular Interpolation Control	0	_
Linear Interpolation Control	3 axes	_
Driver Function	_	Micro-step
Micro-step (Max. Division)	_	250
Driving Current (A/phase)	_	0.1 – 1.1

■General Specifications

Power Voltage	DC24V 1A	
Power Consumption	24VA	
Operating Temperature	5 – 40°C	
Storage Temperature	-20 - 60°C	
Ambient Humidity	20 – 80%RH	
External Dimensions (W×H×Dmm)	130×120×50	
Weight (kg)	0.62	0.63

■Interface

GP-IB	_
RS232C	0
USB	0
Ethernet	0

■Optional

CJ-200A	_
JS-300	_
JB-400	_
JD-100	_
SJT-02	_

■Performance Specifications

Coordinate Indication Range	_
Max. Travel to Set	134,217,727
Max. Driving Speed (pps)	500,000
Min. Driving Speed (pps)	1
Acceleration/Deceleration Time (ms)	1 – 1,000

I/O Specification

Origin Sensor	0
Proximity Sensor	0
CW (+) Limit	0
CCW (-) Limit	0
General Purpose Input	4 points
General Purpose Output	4 points
Control Input	_
Control Output	_
Trigger Output	_

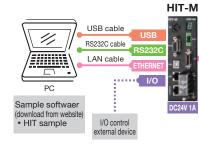
■Control Command

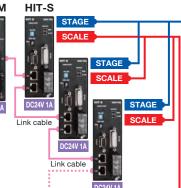
Machine Origin Return	0
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	0
Jog Operation	0
Position Appointment	_
Circular Interpolation Control	0
Linear Interpolation Control	0
Drive	0
Deceleration Stop	0
Emergency Stop	0
Speed Setting	0
Motor Free/Hold	0
Port Input	0
Port Output	0

Stepping Motor Stage



■HIT System Chart





Maximum 8 units



D15RP-CA cable

™ G108





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□40mm

□60mm

□80mm

□85mm

□120mm



Pulse Generating Controller

A 4-axis pulse generator type controller that can be connected to the various motor drivers.

- External control with USB and Ethernet interfaces are available.
- Can be manually operated by a Handy Terminal (JS-300, JB-400, JD-100).



Guide

▶ Sample programs are available for download from our website.

• SGCommander 32/64-bit version for Windows® (only for RS232C)

Attention

- ▶ Cable and motor driver are sold separately. Please purchase 5-phase stepping motor drivers SG-55M or prepare compatible driver of customer choice.
- ▶ Power supply is DC+24V 2A. You need to purchase the PAT-001-POW1 (AC adapter) or prepare an adapter separately.

Products Name	Part Number
Pulse Generating Controller	PGC-04
Joystick Terminal	JS-300
Jog Operation Box	JB-400
Jog Dial	JD-100
AC Adapter	PAT-001-POW

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■Primary Functions

Controller Function	0
Number of Control Axes	4
Stored Program Control	0
Feedback Control	_
Circular Interpolation Control	0
Linear Interpolation Control	0
Driver Function	_
Micro-step (Max. Division)	_
Driving Current (A/phase)	_

■General Specifications

Power Voltage	DC24V
Power Consumption	1.4A
Operating Temperature	5 – 40°C
Storage Temperature	_
Ambient Humidity	20 – 80%RH
External Dimensions (W×H×Dmm)	180×140×60
Weight (kg)	1.3

■Interface

GP-IB	_
RS232C	0
USB	_
Ethernet	0

■Optional

CJ-200A	_
JS-300	0
JB-400	0
JD-100	0
SJT-02	_

■Performaifications

Coordinate Indication Range	_
Max. Travel to Set	16,777,215
Max. Driving Speed (pps)	4,000,000
Min. Driving Speed (pps)	1
Acceleration/Deceleration Time (ms)	1 – 1,000

■I/O Specification

Origin Sensor	0
Proximity Sensor	0
CW (+) Limit	0
CCW (-) Limit	0
General Purpose Input	4 points
General Purpose Output	4 points
General Purpose Output Control Input	4 points
	4 points
Control Input	4 points

■Control Command

Machine Origin Return	0
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	0
Jog Operation	0
Position Appointment	_
Circular Interpolation Control	0
Linear Interpolation Control	0
Drive	_
Deceleration Stop	0
Emergency Stop	0
Speed Setting	0
Motor Free/Hold	0
Port Input	0
Port Output	0

□80mm □85mm

□40mm □60mm

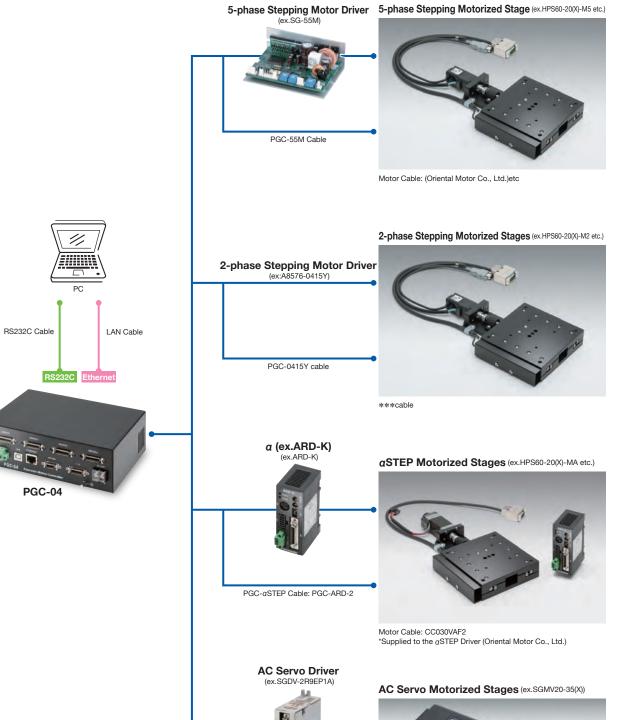
X Translation Theta Rotation Goniometer Vacuum **Options**

□100mm

□120mm



System Diagram



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□40mm

□60mm

□80mm □85mm

□100mm

□120mm

Others

PGC-ACS Cable: PGC-ACS-2



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Joystick Terminal Jog Dial

SJT-02 JD-100

SJT-02

Catalog W9049

A dedicated joystick terminal for the GSC-02 controller to manually operate a motorized stage. Internal program memory allows automatic operation without using a PC.



Attention

▶ Pin 1 of GSC-02 connector for use with the SJT-02 has an electrical output of +24V. Under no circumstances should it be connected to a PC. Although it has a protective circuit, be sure to disconnect either RS232C or SJT-02, otherwise there is a risk of damage.

* If RS232C and SJT-02 are connected at the same time, neither of them will function.

Specifications	
Part Number	SJT-02
Туре	Joystick
Power Supply	Supplied from controller
Display	LCD (16 digits × 2 lines)
External Dimensions [W×H×Dmm]	94×30×140
Weight [kg]	0.45

General Specifications				
Power Supply	DC+24V Supplied from a 2 axis stage controller (GSC-02/SHOT-602).			
Operating Temperature	5 – 40°C			
Ambient Humidity	20 - 80%RH (without condensation)			
External Dimensions	(W)94 × (H)30 × (D)140mm			
Weight	560g (including a special cable)			
Display	LDC 16 digits, 2 lines			
Connecting Cable	Attached special connecting cable (detachable)			

Performance Specifications				
Number of Control Axes	2 axes			
Operation Mode	MANUAL (M) / TEACHING (T) / RUN (R) EDIT (E) / MEM SW SET Mode			
Coordinate Indication Range	X axis: Approx99999999 - +99999999 pulses Y axis: Approx99999999 - +99999999 pulses			
Coordinate Input Range	X axis: Approx. –16777214 – +16777214 pulses Y axis: Approx. –16777214 – +16777214 pulses			
Limit Sensor Status	X axis: Displayed left side of coordinate symbol ("L" is displayed when detected.) Y axis: Displayed left side of coordinate symbol ("L" is displayed when detected.)			
Speed Parameter	Switchable among 10 steps			
Min. Driving Speed	(S) 1 – 20000pps			
Max. Driving Speed	(F) 1 – 20000pps			
Acceleration / Deceleration Time	(R) 0 – 1000mS			
Coordinate Display Unit	[PLS] [µm] [°]			
Program Memory Capacity	128 steps × 4 channels			
Program Parameter	Wait time 0 – 25.5 [sec] Unit: 0.1 sec Repeated 0 – 99999999 [times]			
Origin Return Axes	X axis only / Y axis only / Both axes			
Motor Rotation Direction	X axis: Positive (POS) / Negative (NEG) Y axis: Positive (POS) / Negative (NEG)			

JD-100

Catalog W9085

Manual operation of motorized stages is possible using the JOG buttons or JOG dial. The RATE button allows easy switching of the travel per click (2 steps). Mode switching between SHOT-302GS/SHOT-304GS and switching of travel speed (4 steps) can be performed at hand.



Functions	
LCD Panel	None
MODE Button	Switches between SHOT-302GS/SHOT-304GS modes.
RATE Button	Changes the travel per click. (Normal RATE: 1 pulse/click, High RATE: 5 pulses/click)
AXIS-SEL Button	Switches the motion axes (1 to 4 axes) using the jog dial.
SPEED Button	Switches the travel speed in 4 steps set with the controller.
JOG+/- Button	Operates in +/- direction while the respective button is being pressed.

Specifications	
Part Number	JD-100
Туре	Jog Dial
Cable	MDR14-CA-2.5 (purchase separately)
Display	None
External Dimensions [W×H×Dmm]	130×36×145
Weight [kg]	0.6

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□40mm
□60mm
□80mm
□85mm
□100mm
□120mm
Others

Cables

Piezo





A dedicated joystick terminal for the GSC-02 controller to manually operate a motorized stage. Internal program memory allows automatic operation without using a PC.

JS-300



 Allows easy manual operation of a motorized stage using a joystick.

Specifications	
Part Number	JS-300
Туре	Button operation
Cable	MDR14-CA-2.5 (purchase separately)
Display	LCD (16 digits × 4 lines)
External Dimensions [W×H×Dmm]	120×50×160
Weight [kg]	0.7

Functions	
LCD Panel	Display digits: 16 digits × 4 lines
MODE Button	Switches modes (SHOT-302GS/SHOT-304GS)
E-ORG Button	Returns to theoretical (electric) origin
ZERO Button	Sets theoretical (electric) origin
Control Axis Switch Button	Switches the operating axis of joystick (1, 2 or 3, 4 axes) (Enabled only for SHOT-304GS)
Joystick	Joystick Controls 1, 2 or 3, 4 axes
M-ORG Button	Machine Origin Return
Third axis Operating Switch	Operates third axis
SPEED Button	Switches the travel speed (4 stages) set with SHOT-302GS/SHOT-304GS
STOP Button	Emergency stop

JB-400



 Enable manual operation of motorized stages. It also has a program function.

Specifications	
Part Number	JB-400
Туре	Button operation
Cable	MDR14-CA-2.5 (purchase separately)
Display	LCD (16 digits × 4 lines)
External Dimensions [W×H×Dmm]	178×38×195
Weight [kg]	0.7

Functions				
LCD Panel	Display digits: 16 digits × 4 lines			
Program Button	Executes SHOT-302GS/SHOT-304GS internal progra	ıms		
SPEED Button	Switches the travel speed (4 stages) set with SHOT-3	302GS/SHOT-304GS		
MODE Button	Switches between SHOT-302GS/SHOT-304GS mode	els		
ORG X/Y Button	Returns X/Y axis to machine origin	Returns X/Y axis to machine origin		
Reset X/Y Button	Sets theoretical (electric) origin of X/Y axis			
STOP Button	Emergency stop			
JOG/Pulse Button	Switches between JOG operation and fixed pulse op	Switches between JOG operation and fixed pulse operation		
X axis / Y axis Control Button	When set to JOG operation: Move while the button is being pressed When set to fixed pulse operation: Move for the registered number of pulses at each press of the button			
CLEAR Button	Resets the fixed pulse setting to zero			
Numeric Keypad (0 – 9)	Inputs the number of fixed pulse			
SET Button	Completes setting of fixed pulse			

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□40mm

□60mm

□80mm

□85mm □100mm

□120mm



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□40mm

□60mm

□80mm □85mm

□100mm

□120mm Others

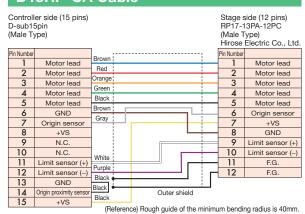


Cables for connecting between motorized stages and controllers or drivers.

Select cables according to control methods or operating environments.

• Refer to compatible controllers/drivers and cables described on the page of each motorized stage.

D15RP-CA Cable



MINI-CA-SG Cable

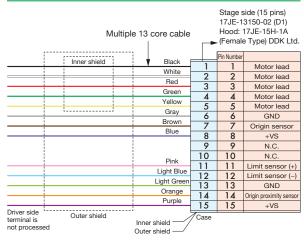
			RP17-10 (Male T	ide (12 pins) 3PA-12PC ype) Electric Co., Ltd.
		-: Brown	Pin Number	
		Red	1	Motor lead
		Orange	2	Motor lead
		1	3	Motor lead
		Yellow	4	Motor lead
		Green	5	Motor lead
		Blue	6	N.C.
		Purple	7	+VS
		Gray	8	GND
		White	9	Limit sensor (+)
		Black	10	Limit sensor (-)
		1	11	F.G.
	Inner shield			
Driver side	Outer shield		12	F.G.
terminal is not processed	(Reference) Rough guide	of the minimum b	ending	radius is 40mm.

D15D15A-CA Cable

17JE-23	er side (15 pins) 3150-02(D1) ype) DDK Ltd.				17JE-13	ide (15 pins) 3150-02(D1)A Type) DDK Ltd.
Pin Number		O/Dis-std [;	Pin Number	
1	Motor lead	Orange/Black1	1111	+	1	Motor lead
2	Motor lead	Orange/Red1	Inner shield	1	2	Motor lead
3	Motor lead	Light grey/Black1	+ +	+	3	Motor lead
4	Motor lead	Light grey/Red1	+ +	-	4	Motor lead
5	Motor lead	White/Black1		+	5	Motor lead
6	GND	White/Red1		-	6	GND
7	Origin sensor	Yellow/Black1		-	7	Origin sensor
8	+VS	Yellow/Red1			8	+VS
9	Autoconfig	Pink/Black1			9	Autoconfig
10	Reserve	Pink/Red1			10	Reserve
11	Limit sensor (+)	Orange/Black2		-	11	Limit sensor (+)
12	Limit sensor (-)	Orange/Red2		-	12	Limit sensor (-)
13	GND	Light grey/Black2		-	13	GND
14	Origin proximity sensor	Light grey/Red2		-	14	Origin proximity sensor
15	N.C.	i.	Outer shield		15	N.C.
	or of the cable wiring, it ulating color, dot color a					

(Reference) Rough guide of the minimum bending radius is 60mm.

DAC-SG Cable



Specifications			
Part Number	Controller Side	Stage Side	Cable Length [m]
D15RP-CA-2	D-sub 15pin / male type	RP17-13PA-12PC / 12pin	2
D15RP-CA-3	D-sub 15pin / male type	RP17-13PA-12PC / 12pin	3
D15RP-CA-5	D-sub 15pin / male type	RP17-13PA-12PC / 12pin	5
MINI-CA-SG-1	Unprocessed	RP17-13PA-12PC / 12pin	1
MINI-CA-SG-2	Unprocessed	RP17-13PA-12PC / 12pin	2
MINI-CA-SG-3	Unprocessed	RP17-13PA-12PC / 12pin	3
MINI-CA-SG-4	Unprocessed	RP17-13PA-12PC / 12pin	4
MINI-CA-SG-5	Unprocessed	RP17-13PA-12PC / 12pin	5
D15D15A-CA-2	17JE-23150 / male type	17JE-13150 / female type	2
D15D15A-CA-3	17JE-23150 / male type	17JE-13150 / female type	3
D15D15A-CA-5	17JE-23150 / male type	17JE-13150 / female type	5
DAC-SG-2	Unprocessed	17JE-13150 / female type	2
DAC-SG-3	Unprocessed	17JE-13150 / female type	3
DAC-SG-4	Unprocessed	17JE-13150 / female type	4
DAC-SG-5	Unprocessed	17JE-13150 / female type	5



Cables for precision motorized stages with built in glass-scale encoder.

MDR14-CA-2.5 Cable

Controller side (14 pins) Connector: 10114-3000PE Shell: 10314-52F0-008 Sumitomo 3M Limited

Stage side (14 pins) Connector: 10114-3000PE Shell: 10314-52F0-008 Sumitomo 3M Limited

Pin Number		Blue			Pin Number	
1	Signal GND		Inner shield		1	Signal GND
2	+5V	Red	inner snield		2	+5V
3	RXD+	Gray	-		3	RXD+
4	TXD+	White	[4	TXD+
5	STOP-	Orange			5	STOP-
6					6	
7					7	
8	Signal GND	Green			8	Signal GND
9	+5V	Brown			9	+5V
10	RXD-	Purple			10	RXD-
11	TXD-	Black	1 1		11	TXD-
12	CONNECT-	Yellow			12	CONNECT-
13					13	
14					14	
	Case		Outer shield	\longrightarrow		Case

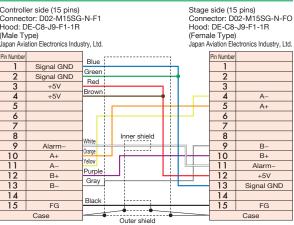
• The MDR14-CA-2.5 cable is for connecting between SHOT-302GS/304GS/SHOT-702 and JS-300/JB-400.

Specification	ıs		
Part Number	Controller Side	JS/JB side	Cable Length [m]
MDR14-CA-2.5	10114-3000PE	10114-3000PE	2.5

GSE-CA-3 Cable

Controller side (15 pins) Connector: D02-M15SG-N-F1 Hood: DE-C8-J9-F1-1R (Male Type)

Japan Aviation Electronics Industry, Ltd.



Specifications									
Part Number	Controller Side	Stage Side	Cable Length [m]						
GSE-CA-3	D02-M15SG-N-F1	D02-M15SG-N-F0	3						
GSEF-CA-3		D02-M15SG-N-F0 rite core)	3						

DHR-CA-3 Cable

Controller side (15 pins) Connector: 17JE-23150-02(D1) Hood: 17JE-15H-1A-CF (Male Type) DDK Ltd.

Stage side (10 pins) HR10A-10P-10PC(73) (Male Type) Hirose Electric Co., Ltd.

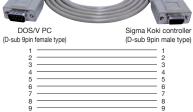
Pin Number		Brown		<i>[</i>	7	Pin Number	
1	Motor lead	Red		 	+	1	Motor lead
2	Motor lead			1	+	2	Motor lead
3	Motor lead	Orange		1	+	3	Motor lead
4	Motor lead	Yellow			-	4	Motor lead
5	Motor lead	Green				5	Motor lead
6	GND	Gray			- -	6	Auto config
7	Origin sensor	Green			#	7	Limit sensor power
8	+VS]		Inner shield		8	GND
9	Auto config	Blue	1	++	-	9	Limit sensor (+)
10	N.C.		╢╫		-	10	Limit sensor (-)
11	Limit sensor (+)	White		,	-	Clamp	F.G.
12	Limit sensor (-)	Black	$ _{l}$	Outer shield	•	Bracket	F.G.
13	GND	Green	Λ	Outer snield			
14	Origin proximity sensor	Green	"				
15	+VS	Purple					
Cla	amp bracket	Y					

Specifications									
Part Number	Controller Side	Stage Side	Cable Length [m]						
DHR-CA-3	17JE-23150-02(D1)	HR10A-10P-10PC(73)	3						

Other Cables

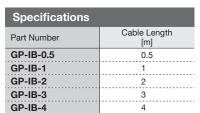






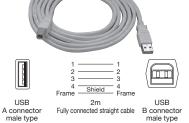
RS232C Cable

Specifications	
Part Number	Cable Length [m]
RS232C/STR-1.8	1.8
RS232C/STR-3	3
RS232C/STR-4.5	4.5



USB Cable

Catalog W9054



Specifications							
Part Number	Cable Length [m]						
USB-1	1						
USB-2	2						

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□40mm

□60mm

□80mm

□85mm □100mm

□120mm



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Maintenance / Grease Replacement

AFA/AFB/AFE/YVAC

Maintenance

Catalog W9005

To maintain smooth operation, grease condition needs to be inspected and checked periodically and grease needs to be supplied if necessary.

Use of grease will prevent rust, extending product life cycle significantly.



Effect of Grease

Minimizes friction to enable smooth drive.

Grease Up Method

- 1 Wipe off old grease.
- 2 Pour grease to supply in a syringe or the like.
- ③ Move the entire travel several times to apply grease thoroughly.
- 4 Wipe off grease that runs over in step 3.
- * Too much grease will cause dust to adhere. Wipe the excess grease clean.

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▶ We will perform filling of grease (charged separately). Contact our International Sales Division for more information.

Attention

▶ Handling of grease requires attention. Avoid contamination with foreign substances, mixing with different type of grease or air, and heat treatment.

Specifications									
Part Number	AFA	AFB							
Motorized Stages Used	SGSP15 Series SGSP20 Series SGSP26 Series	SGSP33 Series SGSP46 Series SGSP65 Series TAMM							
Manufacturer	THK CO., LTD.	THK CO., LTD.							
Operating Temperature Range [°C]	−45 ~ +160	−15 ~ +100							

Replacement of Grease

Catalog W9006

Grease used for motorized stages can be replaced with grease for clean room environments or grease for vacuum applications.

Replacement Sites

Motorized stage : Ball screw part, crossed roller part (TSDM/TAMM series)

Always contact our International Sales Division since grease used for each component (guide part /

screw part) is different.

Rotation stage : Cannot be replaced by customers. Contact our International Sales Division for more information. Goniometer stage: Cannot be replaced by customers. Contact our International Sales Division for more information. (Always contact our International Sales Division since grease used for each component is different for goniometer stages.)

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Goniometer

Vacuum Options

□40mm

□80mm

□85mm

□100mm

□120mm

Others

Features

Low dust generation grease for clean room environments

Reduces burden for maintenance since it is hard to deteriorate and has long life.

It may lose fluidity and get hard suddenly in low-temperature

Fomblin Vacuum Grease

Has excellent heat resistance, lubricity and compatibility with other materials.

It has long life and is usable in high temperature (-20° C $\sim +250^{\circ}$ C).

Specifications									
Part Number	AFE-GREASE-C	YVAC-GREASE-C							
Number of Axes [axis]	1	1							
Manufacturer	THK CO., LTD.	Solvay Solexis							
Name	Low dust generation grease for clean room environments	Fomblin Vacuum Grease							
Part Number	AFE	YVAC							
Operating Temperature Range [°C]	−40 ~ +120	−25 ~ +250							

Question Sheet

Motorized Stage System Question Sheet

Quotation Order

Date

☐ To: Sigma Koki Co., Ltd. FAX +81
I 10. Sigilia Koki Co., Liu. FAA +O

10. 31	jma Koki Co., i	Ltu.	FA/	^ +	01-3)-J	030	3-0 3 3(J	
Affiliation (Organization Name)										
Department					Name	;				
TEL		FAX				i	E-ma	ıil		
Country/Address	'					'				
Project Name									П	entative name is okay)
Drawing number				Est	imate	□ Y	'es: b	y Date		□No
Desired Delivery Date				Bu	dget					JP Yen
Quantity				Part I	Number	Fill in this	column if y	ou desire to modify a p	roduct listed on the catal	og or if you have a base product.
Usage	☐ Research and de ☐ For incorporatio (equipment	n			Direction		axis	☐ XY axis	☐ Z axis	☐ Combination
Weight of Sample, etc.				Cha (chan	nging 7	ravel sensor	positio	on)		
Table Size				mm	Tra	/el				mm
Number of Axes					Loa Capa					kgf
	(Full) Positioning									
Resolution	(Half)				Positi Repeat	onal				
Changing Motor	☐ Electromagnetic	brake	☐ Red	ductio	on gea		'	er (AC serv	o)	
Others	* Write more detailed spec	ifications he	ere. (Rou	ugh illus	stration is	ассер	table.)			

Sigma Koki Co., Ltd.

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Vacuum **Options**

□40mm **□60mm**

□80mm

□85mm

□100mm

□120mm Others

G111

Piezo Guide

For the guide mechanism, Sigma fine stages adopted a guide system that utilizes elastic deformation of metals and a mechanism to increase deformation of piezo elements. These originally designed stages achieved readable resolution of 10nm during closed loop control, ideal for uses that require high-speed high-precision positioning.

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□40mm

□60mm

□80mm

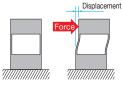
□100mm

□120mm Others

Structure of Sigma Fine Stage

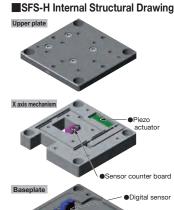
■ Displacement Magnification Method

Piezo actuator and displacement magnification mechanism offer a large operating range.



■Digital Sensor

Closed loop control is possible with a digital sensor that does not require any high precision analog amplifier or AD conversion circuit.



Digital sensor output connector

Piezo actuator

Operating Environment of Sigma Fine Stage

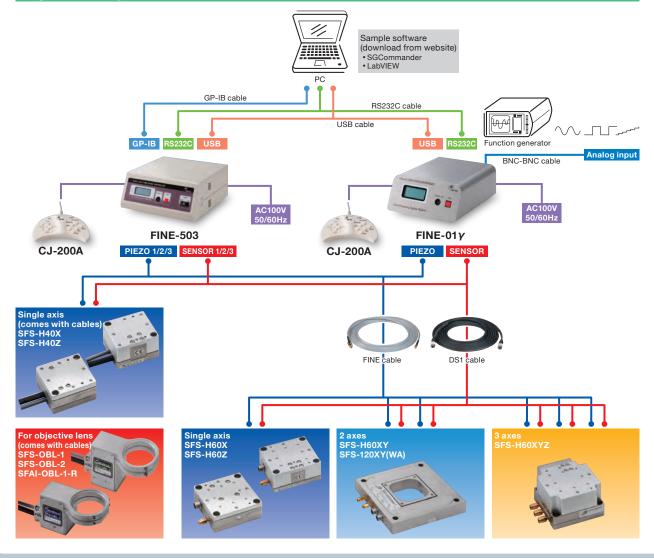
Use fine stages within the following operating environment temperature range. Contact us separately if you desire to use the stages outside the operating environment temperature range.

*Operating environment
Temperature: 10°C – 30°C
Humidity: 20% – 60%
(without condensation)

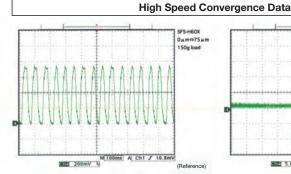
*Recommended environment Temperature: 20°C ±1°C Humidity: 40% or lower

Since durability of piezo elements used in the SFS/SFS-H stage series will deteriorate in high humidity environments, use them in the above environments.

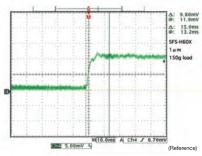
Sigma Fine System Chart



Accuracy Measurement Example: Sigma Fine Stage System SFS-H (Linear Stage)



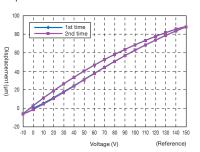
0⇔75µm pulse rate (16Hz) Closed loop control by SFS-H60X at 150g load



0⇒1µm step convergence data (15msec) Closed loop control by SFS-H60X at 150g load

Travel

The following graph shows the hysteresis curve unique to piezo actuators during open loop control travel.



Characteristics of Fine Feed

Characteristics when feed amount is small in closed loop control. Hysteresis disappears

in open loop control.

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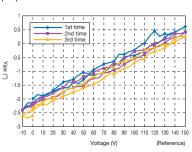
□40mm □60mm

□80mm

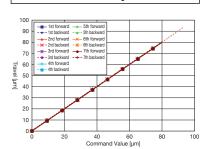
□85mm □100mm

□120mm Others

Piezo



Linearity



Straightness

Deviation from the straight line in the

32 40 48 56 64 72

24

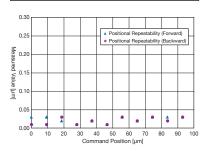
direction of travel.

0.4 0.3 0.2 0.

-0.2 -0.3 -0.4

0⇔80µm linearity within 0.3% Closed loop control by SFS-H60X at 150g load

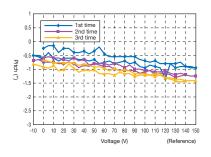
Positional Repeatability



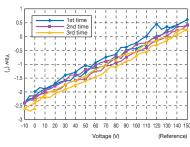
0⇔80µm positional repeatability 50nm or lower by SFS-H60X at 150g load

Pitch

Tilt around the axis in the horizontal plane perpendicular to the direction of travel.

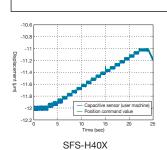


Characteristics of Yaw Rotation around the axis in the vertical plane perpendicular to the direction of travel.

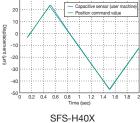


Follow-up example with Respect to Analog Input: SFS-H (Linear Stage) *Controlled by FINE-01γ

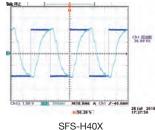
High Speed Convergence Data

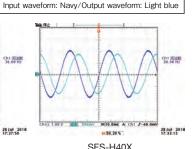


Staircase wave input/output waveforms Saw-tooth wave input/output waveforms Rectangular wave input/output (30Hz) (Step 50nm 20-step staircase wave) (Uniform motion 35µm1Hz)



(Uniform motion 35µm1Hz)





Sine wave input/output (30Hz)



Sigma Fine (Piezo) Stages (high stiffness type) **XY Piezo Stages Aperture Type**

These piezo stages achieved fine movement of theoretical resolution of 1nm, offering high

SFS-120XY(WA)



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□40mm □60mm

□80mm

□85mm

□100mm □120mm

Others

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precision, high stiffness and high speed with adoption of digital sensors. SFS-H

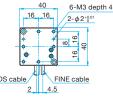


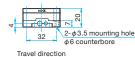
- These piezo stages offer high precision and high resolution positioning because full closed loop control is possible with digital sensors.
- With piezo elements used as actuators, travel between 90µm 100µm in open loop control, and fine movement of theoretical resolution of 1nm are possible.
- Readable resolution of 10nm is achieved during full closed loop control with adoption of a digital sensor (micro-displacement sensor based on the frequency digital conversion method) used as position detection sensors.
- Sigma Koki controller FINE series offers high speed. Reference G117 Regarding pulse rate, SFS-H (linear) achieved 10 – 15Hz, or 25Hz when the current FINE-01y analog input is used.

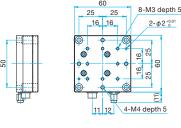


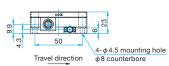
Outline Drawing



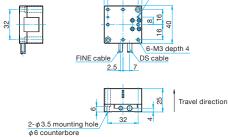


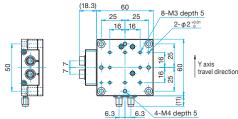


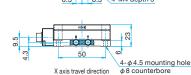




SFS-H40Z(CL) Hexagon socket head cap screw M3×10...2 screws 2-φ2^{+0.01}



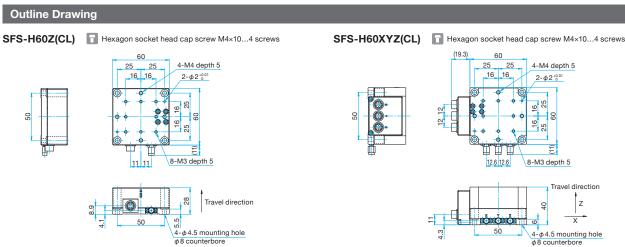




Specifications				
Part Number	SFS-H40X(CL)	SFS-H40Z(CL)	SFS-H60X(CL)	SFS-H60XY(CL)
Travel	90μm±15%	100μm±15%	100µm±15%	100μm±15%
Table Size [mm]	40×40	40×40	60×60	60×60
Actuator	Piezo actuator	Piezo actuator	Piezo actuator	Piezo actuator
Weight [kg]	0.28	0.28	0.4	0.43
Theoretical Resolution (open-loop) [nm]	1	1	1	1
Resolution (closed-loop) [nm]	10	10	10	10
Linearity [%]	0.3 or lower	0.3 or lower	0.3 or lower	0.3 or lower
Perpendicularity (Horizontal Direction) [µm]	1	1	1	1
Positional Repeatability [µm]	0.1 or lower	0.1 or lower	0.1 or lower	0.1 or lower
Load Capacity [N]	9.8 (1.0kgf)	6.7 (0.7kgf)	19.6 (2.0kgf)	14.7 (1.5kgf)
Micro-displacement Sensor	Digital Sensor	Digital Sensor	Digital Sensor	Digital Sensor
Compatible Cable	Attached cable (2m)	Attached cable (2m)	FINE-CA-3: For piezo DS1-CA-3: For digital sensor	FINE-CA-3: For piezo DS1-CA-3: For digital ser



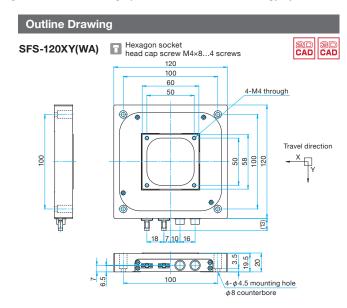




SFS-120XY(WA)

- A high precision positioning XY axis stage with 50×50mm aperture fitted with a piezo element as an actuator and digital sensor for position feedback, suitable for fine movement of samples under a microscope.
- Can be driven with the Sigma fine stage controller FINE-503. Since the controller supports RS232C, GP-IB (FINE-503 only) and USB interfaces, position control can be performed easily from a PC using the software for positioning & measurement SGEMCSE, SGTERME and SGSFSXE.
- Ideal for applications such as incorporation into various types of microscopes, precision measurement, semiconductor test equipment, high-precision mask alignment, scanning interferometer, image processor, and biotechnology systems.





Specifications			
Part Number	SFS-H60Z(CL)	SFS-H60XYZ(CL)	SFS-120XY(WA)
Travel	100μm±15%	100μm±15%	100μm±10%
Table Size [mm]	60×60	60×60	120×120
Actuator	Piezo actuator	Piezo actuator	Piezo actuator
Weight [kg]	0.33	0.63	1.2
Theoretical Resolution (open-loop) [nm]	1	1	1
Resolution (closed-loop) [nm]	10	10	10
Linearity [%]	0.3 or lower	0.5 or lower	_
Perpendicularity (Horizontal Direction) [µm]	1	1	1 or lower
Positional Repeatability [µm]	0.1 or lower	0.15 or lower	0.1 or lower
Load Capacity [N]	9.8 (1.0kgf)	9.8 (1.0kgf)	19.6 (2.0kgf)
Micro-displacement Sensor	Digital sensor	Digital sensor	Digital sensor
Compatible Cable	FINE-CA-3: For piezo DS1-CA-3: For digital sensor	FINE-CA-3: For piezo DS1-CA-3: For digital sensor	FINE-CA-3: For piezo DS1-CA-3: For digital sensor

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□40mm

□60mm

⊒80mm

⊒85mm

□100mm



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Piezo Actuator for Objective Lens

SFS-OBL (Upright)/SFAI-OBL (Inverted)





Objective lens actuator for inverted microscope employing a piezo element as actuator and digital sensor for feedback.



- Compact, and enabling high-speed high-resolution positioning.
- Travel is 100µm at open loop.
- Two types of erected model and inverted model are available for incorporation into various types of microscopes.
- In the case of the Sigma fine stage series, these actuators can be driven with the controller (FINE-01γ/503(CL)). Since RS232C, GP-IB (FINE-503 only) and USB interfaces are supported, position control can be performed easily from a PC using the software for positioning & measurement SGEMCSE, SGTERME and SGSFSXE.

Guide

- ▶ Adapters compatible with screw sizes of other manufacturers' objective lenses are also available.
- ▶ SFS-OBL-2 uses a metal enclosure type piezo actuator to improve environment resistance such as humidity compared to SFS-OBL-1.

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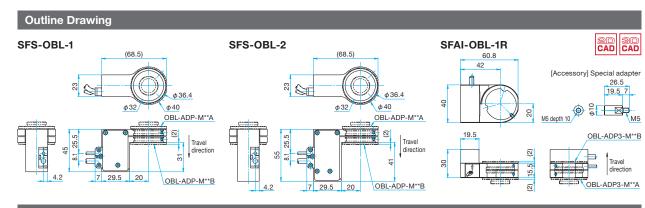
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Specifications			
Part Number	C€ SFS-OBL-1	SFS-OBL-2	SFAI-OBL-1R
Travel	100μm±15%	100μm±15%	100μm±15%
Objective Lens Diameter [mm]	Diameter φ39 or less	Diameter φ39 or less	Diameter φ39 or less
Dimensions [mm]	(W)75.5 × (H)45 × (D)40	(W)75.5 × (H)55 × (D)40	(W)60.8 × (H)30 × (D)40
Actuator	Piezo element	Piezo element	Piezo element
Weight [kg]	0.15	0.24	0.15
Theoretical Resolution (open-loop) [nm]	1	1	about 0.8
Resolution (closed-loop) [nm]	10	10	10
Straightness (Xy Xz Yx Yz) [µm]	1 or lower	1 or lower	0.2 or lower
Positional Repeatability [µm]	0.1 or lower	0.1 or lower	0.1 or lower
Load Capacity [N]	_	_	4.9 (0.5kgf)
Micro-displacement Sensor	Digital sensor	Digital sensor	Digital sensor
Compatible Adapter	OBL-ADP-**	OBL-ADP-**	OBL-ADP3-**
Accessories	Cable (2m)	Cable (2m)	Cable (2m), four special lift spacers

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□40mm

□60mm

□85mm

□85mm

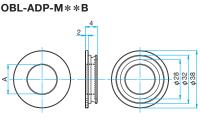
□120mm

Others

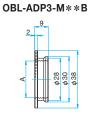
Objective Lens Adapters



3 45



OBL-ADP3-M**A



SFS-OBL Compatible Adapters			
Part Number	Mounting Screw Size [mm]	A [mm]	B [mm]
OBL-ADP-M20.32A	Microscope side M20.32	M20.32 P=0.706 (W0.8×1/36)	15
OBL-ADP-M20.32B	Objective lens side M20.32	M20.32 P=0.706 (W0.8×1/36)	_
OBL-ADP-M25.0A	Microscope side M25.0	M25.0 P=0.75	20
OBL-ADP-M25.0B	Objective lens side M25.0	M25.0 P=0.75	_
OBL-ADP-M26.0A	Microscope side M26.0	M26.0 P=0.706 (W26.0×1/36)	21
OBL-ADP-M26.0B	Objective lens side M26.0	M26.0 P=0.706 (W26.0×1/36)	

SFAI-OBL Cor	SFAI-OBL Compatible Adapters				
Part Number	Mounting Screw Size [mm]	A [mm]	B [mm]		
OBL-ADP3-M20.32A	Microscope side M20.32	M20.32 P=0.706 (W0.8×1/36)	15		
OBL-ADP3-M20.32B	Objective lens side M20.32	M20.32 P=0.706 (W0.8×1/36)	_		
OBL-ADP3-M25.0A	Microscope side M25.0	M25.0 P=0.75	20		
OBL-ADP3-M25.0B	Objective lens side M25.0	M25.0 P=0.75	_		
OBL-ADP3-M26.0A	Microscope side M26.0	M26.0 P=0.706 (W26.0×1/36)	21		
OBL-ADP3-M26.0B	Objective lens side M26.0	M26.0 P=0.706 (W26.0×1/36)	_		



Controllers with built-in piezo drivers for single axis / 3 axes.



- These controllers are fitted with digital sensor input for each axis, enabling closed loop control by correcting hysteresis curve unique to piezo.
- Being connected to a PC via RS232C, GP-IB, or USB interface, the FINE-503(CL) allows control of a fine stage by simple commands sent from a PC.
- In addition to PC control via RS232C or USB interface, the FINE-01y enables high-speed control synchronized with analog signal input.

Part Name	Part Number
1 axis SFS Controller with Analog Input Function	FINE-01γ
3 axes SFS Controller	FINE-503(CL)
Control Pad	CJ-200A
FINE Cable	FINE-CA-3
DS Cable	DS1-CA-3
BNC-BNC Cable	SKBNC-BNC-3.0

■Primary Functions

Part Number	FINE-01γ	FINE-503(CL)
Controller Function	(
Number of Control Axes	1	3
Stored Program Control	(
Feedback Control Digital sensor		sensor

■General Specifications

Power Voltage	AC100\ 50/6	/ ±10% 60Hz
Power Consumption	50	VA
Operating Temperature	10 –	30°C
Storage Temperature	-20 -	60°C
Ambient Humidity	20 – 8	0%RH
External Dimensions (W×H×Dmm)	225×118×250	270×118×297
Weight (kg)	3.5	5.3

■Interface

GP-IB	_	0
RS232C		
USB		
Analog input	0	_

■Optional

CJ-200A		
SKBNC-BNC-3.0	0	_

■Performance Specifications

Coordinate Indication Range	±999,999nm
Max. Travel to Set	±999,999nm

■Control Command

Machine Origin Return	0
Theoretical Origin Setting	0
Relative Position Drive	0
Absolute Position Drive	0
Jog Operation	0
Position Appointment	_
Circular Interpolation Control	_
Linear Interpolation Control	_
Drive	0
Deceleration Stop	_
Emergency Stop	_
Speed Setting	0
Motor Free/Hold	_
Port Input	_
Port Output	_

SFS Software

Free Software | SGCommander (for RS232C) Windows® Version

Free software is available to operate your controller easily from a PC. Each axis of a connected motorized stage can be moved using buttons on the screen. The software can be downloaded from our website.

(1) Jog operation -(2) Speed specification

(4) Travel contro

Simple operations are possible such as travel by specifying an axis, homing or jog operation.

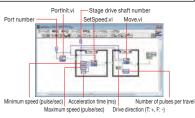


Controllers such as SHOT-30*/702 and FINE-**, which have a built-in program function, allow editing of programs from a PC. Since data can be downloaded/uploaded from/to Excel sheets, it is easy to edit programs. In addition, upload of memory switch or download mode is available.

Free Application LabVIEW (for v.5.1/v.6i/v.7.1/v.8.6/v.2010) RS232C/GP-IB

LabVIEW application is available for LabVIEW users.

(3) Homing control



Other: 30 Day Trial Version (SGEMCSE/SGTERME)

SGEMCSE.....SGEMCSE is software for collecting data or measuring using automatic positioning equipment, measuring instrument or controller, and is offered

30 days for free. SGTERME.....It allows command input Reference G024 using Excel for easy program making. SGTERME is ideal software to link with various devices, and is offered 30 days for free





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□80mm 85mm

□100mm

□120mm Others



ECS Positioners

ECS series





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□40mm
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□0thers

Cables

Piezo

With Industrial Line positioners, attocube has genuinely combined highest precision piezodrive technology with extremely rugged, yet cost effective design.

- All ECS positioners of the Industrial Line are dedicated for operation at ambient temperature and depending on the model for pressures ranging from atmospheric to UHV.
- The ECS drive series features implemented crossed roller bearings and is thus specified for high loads of up to several kilograms and guiding errors of less than 0.1mrad in pitch, yaw, and roll.
- This powerful performance is supplemented by travel ranges up to 50mm, step sizes as small as 50nm, and optional position sensor for closed loop operation with 1nm resolution. Attocube's Industrial Line positioners are available in a wide variety of designs, sizes, and travel ranges and can be stacked directly on top of each other for multi axis operation.

Specifications								
Exterior				15	35	35	X	Section III
Products Name		X axis positioner	X axis positioner	X axis positioner	Goniometer	Goniometer	Rotator	Rotator
Part Number		ECS3030	ECS3080	ECS5050	ECGt5050	ECGp5050	ECR3030	ECR5050
Closed-loop travel properties	Position Resolution	1nm	1nm	1nm	0.000001°	0.000001°	0.00001°	_
	Position Repeatability	50nm	50nm	50nm	±0.00005°	±0.00005°	±0.0005°	_
	Accuracy	< 0.01% of travel range	< 0.01% of travel range	< 0.01% of travel range	≑0.001°	≑0.001°	≑0.002°	-
Open-loop travel properties	Minimum step size	50nm	50nm	50nm	0.0001°	0.0001°	0.0004°	0.0002°
	Fine positioning range	1.6µm	1.6µm	1.6µm	0.0014°	0.0011°	0.012°	0.006°
Travel Range		20mm	50mm	30mm	10°	10°	360°	360°
Table Dimensions [mm]		30×30	30×80	50×50	50×50	50×50	30×30	50×50
Positioning Slide		Crossed Roller Bearing	Crossed Roller Bearing	Crossed Roller Bearing	Crossed Roller Bearing	Crossed Roller Bearing	Ball Bearing	Ball Bearing
Weight [kg]	Aluminum	0.029	0.078	0.070	0.137	0.137	0.28	0.1
	Stainless steel	0.051	0.147	0.247	0.247	0.247	0.66	0.215
Maximum Travel Speed		4.5mm/sec	4.5mm/sec	4.5mm/sec	≒1°/sec	≒1°/sec	≒10°/sec	≑5°/sec
Load Capacity (horizontal mounting)		9kg	24kg	15kg	1kg	1kg	2kg	2kg

^{*} Closed-loop properties are available if "encoder option" is selected. For ordering, add suffix "/NUM" after the model number.

Control of Industrial Line Positioners | ECC100

The three axes controller ECC100 is used for driving all ECS positioners either in open loop or closed loop mode, depending on the corresponding positioner model.



Software features

The ECC100 is delivered with a basic software package providing windows based software including LabView driver set and DLL. A dedicated software package /PRO providing enhanced controller functionality can be upgraded at any time. The /SYNC option offers the use of an Ethernet interface and allows for using the controller with Epics drivers.

Controller Hardware				
Part Number	ECC100			
Chassis [mm]	about (W)210 × (H)50 × (D)210			
Weight [kg]	1.9			
Power supply	100/115/230V, 50-60Hz			
Power consumption	max. 100W			

Output Signals			
Stepping - voltage range	0 – 45V		
Stepping - frequency range	0 – 5kHz (1 axis) 0 – 2kHz (3 axes simultaneously)		
Stepping - maximum current	>5A Peak		
Resolution of signal generation	680μV (16 bit)		
Output connectors	SubD 15 connectors		